FREE Evolution - FREE Panel

User Guide











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TABLE OF CONTENTS



CHAPTER	1. Introduction	12
	1.1. General description of FREE Evolution / Panel	12
	1.1.1. FREE Evolution / Panel offer	12
CHAPTER	2. Mechanical installation	15
	2.1. Before Starting	15
	2.2. Disconnecting Power	
	2.3. Programming Considerations	
	2.4. Operating Environment	16
	2.5. Installation Considerations	16
	2.6. EVD / EVC / EVE installation	18
	2.7. Assembling the EVS Communication modules	20
	2.8. Assembling the FREE Panel or FREE EVK1000	21
	2.8.1. Panel mounting	21
	2.8.2. Accessories for Wall mounting	22
CHAPTER	3. Electrical connections	23
	3.1. Wiring Best Practices	23
	3.1.1. Wiring Guidelines	23
	3.1.2. Rules for Removable Screw Terminal Block	24
	3.1.3. Protecting Outputs from Inductive Load Damage	25
	3.1.4. Special handling considerations	27
	3.1.5. Analog Inputs-Probes	27
	3.1.6. Serial connections	27
	3.2. Wiring diagrams	30
	3.2.1. FREE Evolution wiring diagram	30
	3.2.2. EVE4200 wiring diagram	32
	3.2.3. Examples of analog input connection (FREE Evolution only)	33
	3.2.4. FREE Evolution / EVK1000 connection	37
	3.2.5. EVP3300/C and EVP3500/C/RH connection	38
	3.3. FREE Evolution protocol connectivity	40
	3.3.1. Example: CAN (Field) network connection	40

	3.3.2. Example: CAN connection (Network)	41
	3.3.3. Example: RS485 connection (Field)	42
	3.3.4. Example: RS485 connection with the FREE Smart network	43
	3.4. FREE Panel protocol connectivity	44
	3.4.1. Example: RS485 connection (Field)	44
	3.4.2. Example: CAN connection	44
	3.4.3. Example: RS485 connection with the FREE Smart network	45
	3.4.4. Example: CAN network connection	46
	3.5. EVS Communication modules	47
	3.5.1. Communication modules compatible with FREE Evolution and FREE A	dvance
	3.5.2. Communication modules exclusively compatible with FREE Evolution .	48
	3.5.3. EVS RS232/R	51
	3.5.4. EVS ETH / EVS ETH + RS485	53
	3.5.5. Example: BACnet / IP	54
	3.5.6. EVS RS485	57
	3.5.7. EVS RS485 BACnet MS/TP / EVS ETH + RS485	58
	3.5.8. EVS CAN	59
	3.5.9. EVS PROFIBUS	60
	3.5.10. EVS LON	61
	3.6. Ethernet connection (for FREE Panel)	62
CHAPTER	4. Technical data	64
	4.1. General specifications	65
	4.1.1. FREE Evolution / EVE4200	65
	4.1.2. FREE Panel	66
	4.2. I/O Features	67
	4.2.1. FREE Evolution I/O features	67
	4.2.2. EVE4200 I/O features	69
	4.2.3. FREE Panel I/O features	70
	4.3. Display	71
	4.3.1. EVK1000 / FREE Panel display	71
	4.4. Serials	71
	4.4.1. EVS Communication module	72
	4.5. Power supply	73

	4.6. Mechanical dimensions	73
CHAPTER	5. FREE Evolution User Interface	75
	5.1. Keys and LEDs	75
	5.2. First power on	76
CHAPTER	6. EVK1000 user interface	77
	6.1. Keys and LEDs	77
	6.2. First power on	78
	6.3. DIAGNOSTICS menu	79
	6.3.1. BIOS parameters	79
	6.3.2. HMI Management	79
	6.4. Remote interface	79
	6.4.1. Language	79
	6.4.2. tl	
	6.4.3. HMI Management	80
CHAPTER	7. FREE Panel user interface	81
	7.1. Keys and LEDs	81
	7.2. First power on	82
	7.3. DIAGNOSTIC menu	83
	7.3.1. BIOS parameters	83
	7.3.2. HMI management	83
	7.3.3. Probe values	83
	7.3.4. Date and time	84
	7.4. Remote interface	85
	7.4.1. Language	85
	7.4.2. tl	85
	7.4.3. HMI sel	85
	7.4.4. COM Setting	86
	7.4.5. HMI Management	86
CHAPTER	8. Physical I/O and ports configuration	87
	8.1. Analog inputs	88
	8.1.1. Analog inputs configuration for FREE Evolution	88
	8.1.2. Analog inputs configuration for EVE4200	89
	8.1.3. Analog inputs configuration for FREE Panel	91

	8.2. Analog outputs configuration for FREE Evolution	92
	8.3. Digital inputs configuration for FREE Evolution	92
	8.4. Digital outputs configuration for FREE Evolution	92
	8.5. Ports configuration for FREE Evolution using DipSwitch	93
	8.5.1. EVD DipSwitch	94
	8.5.2. EVC DipSwitch	95
	8.5.3. EVE7500 expansion DipSwitch	99
	8.5.4. EVE4200 expansion DipSwitch	101
CHAPTER	9. Parameters	102
	9.1. FREE Evolution parameter table	103
	9.1.1. EVD / EVC / EVE7500 parameters	104
	9.1.2. EVE4200 parameters	115
	9.1.3. EVP parameters	119
CHAPTER	10. Programming of the EVE4200	128

SAFETY INFORMATION



Important Information

Read these instructions carefully, and look at the equipment to become familiar with the device before trying to install, operate, service, or maintain it. The following special messages may appear throughout this documentation or on the equipment to inform of potential hazards or to call attention to information that clarifies or simplifies a procedure.



The addition of this symbol to a 'Danger' or 'Warning' safety label indicates that an electrical hazard exists, which will result in personal injury if the instructions are not followed.



This is the safety alert symbol. It is used to alert you to potential personal injury hazards. Obey all safety messages that follow this symbol to avoid possible injury or death.

A DANGER

DANGER indicates a hazardous situation which, if not avoided, will result in death or serious injury.

WARNING

WARNING indicates a hazardous situation which, if not avoided, could result in death or serious injury.

A CAUTION

CAUTION indicates a hazardous situation which, if not avoided, **could result** in minor or moderate injury.

NOTICE

NOTICE is used to address practices not related to physical injury.

PLEASE NOTE

Electrical equipment should be installed, operated, serviced, and maintained only by qualified personnel.

No responsibility is assumed by Eliwell for any consequences arising out of the use of this material.

A qualified person is one who has skills and knowledge related to the construction and operation of electrical equipment and its installation, and has received safety training to recognize and avoid the hazards involved.

Qualified Personnel

Only appropriately trained persons who are familiar with and understand the contents of this manual and all other pertinent product documentation are authorized to work on and with this product.

The qualified person must be able to detect possible hazards that may arise from parameterization, modifying parameter values and generally from mechanical, electrical, or electronic equipment. The qualified person must be familiar with the standards, provisions, and regulations for the prevention of industrial accidents, which they must observe when designing and implementing the system.

Permitted use

This product is used to control HVAC-related and pumping applications.

For safety reasons, the device must be installed and used in accordance with the instructions provided. In particular, parts carrying dangerous voltages must not be accessible under normal conditions.

The device must be adequately protected from water and dust with regard to the application, and must only be accessible using tools (with the exception of the front panel).

The device is also suitable for use in household and commercial refrigeration appliances and/or similar equipment and has been tested for safety aspects in accordance with the harmonized European reference standards.

Prohibited use

Any use other than that expressed above under Permitted use is strictly prohibited.

The relay contacts supplied are of an electromechanical type and subject to wear. Functional safety protection devices, specified in international or local standards, must be installed externally to this device.

Liability and residual risks

Eliwell liability is limited to the proper and professional use of this product under the guidelines contained in the present and other supporting documents, and does not extend to damages caused by (but not limited to):

- Unspecified installation/use and, in particular, in contravention of the safety requirements of established legislation or specified in this document;
- Use on equipment which does not provide adequate protection against electrocution, water and dust in the actual installation conditions:
- Use on equipment which allow access to dangerous parts without the aid of a keyed or tooled locking mechanism;
- Installation/use on equipment which does not comply with established legislation and standards.

Disposal



The appliance (or the product) must be disposed of separately in compliance with the local standards in force on waste disposal.

Product Related Information

A A DANGER

HAZARD OF ELECTRIC SHOCK, EXPLOSION OR ARC FLASH

- Disconnect all power from all equipment including connected devices prior to removing any covers or doors, or installing or removing any accessories, hardware, cables, or wires.
- Always use a properly rated voltage sensing device to confirm the power is removed.
- Replace and secure all covers, accessories, hardware, cables, and wires and confirm that a proper ground connection exists before applying power to the unit.
- · Use only the specified voltage when operating this equipment and any associated products.

Failure to follow these instructions will result in death or serious injury.

This equipment has been designed to operate outside of any hazardous location.

Only install this equipment in zones known to be free of hazardous atmosphere.

A DANGER

POTENTIAL FOR EXPLOSION

Install and use this equipment in non-hazardous locations only.

Failure to follow these instructions will result in death or serious injury.

A WARNING

LOSS OF CONTROL

- The designer of any control scheme must consider the potential failure modes of control paths and, for certain critical
 control functions, provide a means to achieve a safe state during and after a path failure. Examples of critical control
 functions are emergency stop and overtravel stop, power outage and restart.
- Separate or redundant control paths must be provided for critical control functions.
- System control paths may include communication links. Consideration must be given to the implications of unanticipated transmission delays or failures of the link.
- Observe all accident prevention regulations and local safety guidelines.⁽¹⁾
- Each implementation of this equipment must be individually and thoroughly tested for proper operation before being placed into service.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

(1) For additional information, refer to NEMA ICS 1.1 (latest edition), "Safety Guidelines for the Application, Installation, and Maintenance of Solid State Control" and to NEMA ICS 7.1 (latest edition), "Safety Standards for Construction and Guide for Selection, Installation and Operation of Adjustable-Speed Drive Systems" or their equivalent governing your particular location.

A WARNING

UNINTENDED EQUIPMENT OPERATION

- · Only use software approved by Eliwell for use with this equipment.
- · Update your application program every time you change the physical hardware configuration.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

ABOUT THE BOOK



Document Scope

This document describes the **FREE Evolution / Panel logic controllers** and accessories including installation and wiring information.

Use this document to:

- Install and operate your FREE Evolution / Panel logic controller.
- Connect the FREE Evolution / Panel logic controller to a programming device equipped with FREE Studio software
- Interface the FREE Evolution / Panel logic controller with I/O expansion modules, HMI and other devices.
- Familiarize yourself with the FREE Evolution / Panel logic controller features.

NOTE: Read and understand this document and the related documents before installing, operating, or maintaining your controller.

Validity Note

This document is valid for FREE Studio (v.3.5 or greater).

The technical characteristics of the devices described in this manual also appear online.

The characteristics that are presented in this manual should be the same as those characteristics that appear online. In line with our policy of constant improvement, we may revise content over time to improve clarity and accuracy. If you see a difference between the manual and online information, use the online information as your reference.

Related Documents

Title of Documentation	Reference Document Code
User Guide FREE Smart - SKP SKW	9MA10251 (ENG) 9MA00251 (ITA)
User Guide FREE Evolution - FREE Panel	9MA00252 (ITA)
User Guide XVD	9MA10254 (ENG) 9MA00254 (ITA)
User Guide FREE Studio	9MA10255 (ENG) 9MA00255 (ITA)
FREE Studio software HelpOnLine Manual	9MA10256 (ENG) 9MA00256 (ITA)
User Guide FREE Advance	9MA10265 (ENG) 9MA00265 (ITA)
FREE Evolution 27 I/O – Instruction Sheet	9IS54403
FREE Panel 3 I/O Instruction Sheet	91S54404
FREE EVS Plugin – Instruction Sheet	91S54405
FREE EVK1000 – Instruction Sheet	9 \$54408
FREE Advance 28/42 I/O – Instruction Sheet	9IS54473

You can download these technical publications and other technical information from our website at:

www.eliwell.com

CHAPTER 1

Introduction

1.1. General description of FREE Evolution / Panel

The **FREE Evolution / Panel** is a **Eliwell** range of programmable controller, suitable for managing a wide range of HVAC/R and many other applications, from the simplest to the most complex.

In this manual, the photos and drawings are intended to show the **FREE Evolution / Panel** programmable controller (and other Eliwell devices) and are for illustrative purposes only. The relative sizes and proportions may not be indicative of actual dimensions nor to scale. In addition, any wiring diagrams or electrical schematics are to be considered as simplified renditions and not literal representations thereof.

1.1.1. FREE Evolution / Panel offer

The FREE Evolution / Panel offer is made of:

- FREE Evolution
- FREE EVK1000
- FREE Panel

FREE References	Description	
EVD7500/C/U	FREE Evolution Display 27 I/Os, Modbus	
EVD7500/C/U/SSR	FREE Evolution Display 27 I/Os Modbus, 2 SSR	
EVC7500/C/U	FREE Evolution Blind 27 I/Os, Modbus	
EVE7500	FREE Evolution expansion 27 I/Os	
EVE4200	FREE Evolution expansion 14 I/Os	
EVK1000	FREE Evolution Display Graphic	
EVP3300/C	FREE Panel 3 I/Os, MB & BACnet	
EVP3500/C/RH	FREE Panel 3 I/Os RH, MB & BACnet	

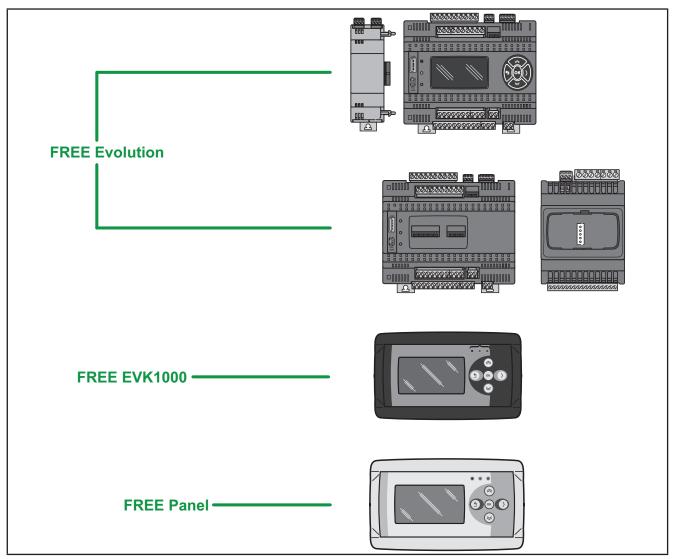


Fig. 1. FREE Evolution / Panel

FREE Evolution delivers performance in terms of memory, connectivity and user interface as well as straightforward programming, maintenance and servicing.

The references are available as 8DIN rail-mounted versions, which saves time in terms of wiring. The 8DIN format provides extra flexibility and easy installation.

A wide range of 2DIN rail mounted Communication modules allow integration with industrial systems, BMS and Ethernet networks.

Lastly, ratiometric pressure sensors and displays can also be connected with no need for further serial interfaces.

FREE Panel can be used as a system controller, with gateway functions; used in combination with the **FREE Evolution** and the **FREE Smart** or third-party controllers, it delivers performance in terms of memory, connectivity and user interface as well as straightforward programming, maintenance and servicing.

FREE Panel is designed for panel mounting, and can also be wall-mounted using a special backplate, available as an accessory

FREE Panel can be used to:

- · manage a local menu created with the FREE Studio User Interface;
- manage up to 10 remote menus, created with the FREE Studio User Interface and uploaded from the respective FREE Evolution devices connected to the network;

share network variables (binding).

In association with the **FREE Evolution** hardware, there is also the **FREE Studio** development tool to program and customize new programs for many HVAC- and pumping-related applications.

The use of several different programming languages in accordance with IEC61131-3 regulations makes it possible to develop new algorithms or programs, which can then be uploaded to the **FREE Evolution / Panel** modules via PC or (only for DIN rail mounted **FREE Evolution / Panel** controllers) USB memory key.

Web functionalities

The **FREE Evolution / Panel** also features web functionalities, offering makers of machinery and systems integrators remote access. Having a web-based connection in machines reduces support and maintenance by minimizing call-out charges. End users also benefit, as they can monitor their own systems both locally and from distance, using the graphics interface of any browser.

Main web functionalities

- · Web-based access.
- · Remote reading and support.
- · Local and remote system control, including alarms management.
- · Preventive and predictive maintenance.
- · Email alarm alerts.

Care must be taken and provisions made for use of this product as a control device to avoid inadvertent consequences of commanded machine operation, controller state changes, or alteration of data memory or machine operating parameters.

A WARNING

UNINTENDED EQUIPMENT OPERATION

- Configure and install the mechanism that enables the remote HMI local to the machine, so that local control over the machine can be maintained regardless of the remote commands sent to the application.
- You must have a complete understanding of the application and the machine before attempting to control the application remotely.
- Take the precautions necessary to assure that you are operating remotely on the intended machine by having clear, identifying documentation within the application and its remote connection.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

CHAPTER 2

Mechanical installation

2.1. Before Starting

Read and understand this chapter before beginning the installation of your system. The use and application of the information contained herein require expertise in the design and programming of automated control systems. Only you, the user, machine builder or integrator, can be aware of all the conditions and factors present during installation and setup, operation, and maintenance of the machine or process, and can therefore determine the automation and associated equipment and the related safeties and interlocks which can be effectively and properly used. When selecting automation and control equipment, and any other related equipment or software, for a particular application, you must also consider any applicable local, regional or national standards and/or regulations. Pay particular attention in conforming to any safety information, different electrical requirements, and normative standards that would apply to your machine or process in the use of this equipment.

WARNING

REGULATORY INCOMPATIBILITY

Be sure that all equipment applied and systems designed comply with all applicable local, regional and national regulations and standards.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

2.2. Disconnecting Power

All options and modules should be assembled and installed before installing the control system on a mounting rail, into a panel door or onto a mounting surface. Remove the control system from its mounting rail, mounting plate or panel before disassembling the equipment.

A A DANGER

HAZARD OF ELECTRIC SHOCK, EXPLOSION OR ARC FLASH

- Disconnect all power from all equipment including connected devices prior to removing any covers or doors, or installing or removing any accessories, hardware, cables, or wires.
- Always use a properly rated voltage sensing device to confirm the power is removed.
- Replace and secure all covers, accessories, hardware, cables, and wires and confirm that a proper ground connection exists before applying power to the unit.
- Use only the specified voltage when operating this equipment and any associated products.

Failure to follow these instructions will result in death or serious injury.

2.3. Programming Considerations

The products described in this manual have been designed and tested using Eliwell programming, configuration and maintenance software products.

WARNING

UNINTENDED EQUIPMENT OPERATION

- · Only use software approved by Eliwell for use with this equipment.
- · Update your application program every time you change the physical hardware configuration.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

2.4. Operating Environment

This equipment has been designed to operate outside of any hazardous location. Only install this equipment in zones known to be free of a hazardous atmosphere.

A DANGER

POTENTIAL FOR EXPLOSION

Install and use this equipment in non-hazardous locations only.

Failure to follow these instructions will result in death or serious injury.

A WARNING

UNINTENDED EQUIPMENT OPERATION

Install and operate this equipment according to the conditions described in the General Specifications.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

2.5. Installation Considerations

A WARNING

UNINTENDED EQUIPMENT OPERATION

- Use appropriate safety interlocks where personnel and/or equipment hazards exist.
- Install and operate this equipment in an enclosure appropriately rated for its intended environment.
- Power line and output circuits must be wired and fused in compliance with local and national regulatory requirements for the rated current and voltage of the particular equipment.
- · Do not use this equipment in safety-critical machine functions.
- · Do not disassemble, repair, or modify this equipment.
- · Do not connect any wiring to reserved, unused connections, or to connections designated as No Connection (N.C.).
- Do not mount devices in extremely damp and/or dirt-laden areas.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

NOTE: JDYX2 or JDYX8 fuse types are UL-recognized and CSA approved.

For mechanical dimensions, see 4.6. Mechanical dimensions on page 73.

The FREE Evolution / Panel logic controllers are intended for DIN rail mounting, panel mounting or wall mounting.

Care must be taken to avoid damage from electrostatic sources when handling this equipment. In particular exposed connectors and, in some cases, exposed printed circuit boards are vulnerable to electrostatic discharge.

A WARNING

UNINTENDED EQUIPMENT OPERATION DUE TO ELECTROSTATIC DISCHARGE DAMAGE

- Keep equipment in the protective conductive packaging until you are ready to install the equipment.
- Only install equipment in approved enclosures and / or locations that prevent casual access and provide electrostatic discharge protection.
- Use a conductive wrist strap or equivalent field force protective device attached to an earth ground when handling sensitive equipment.
- Always discharge yourself by touching a grounded surface or approved antistatic mat before handling the equipment.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

2.6. EVD / EVC / EVE installation

The equipment is intended for 8DIN rail mounting (refer to Fig. 2 on page 18 and Fig. 3 on page 19). For DIN rail installation, follow the steps described below:

- 1. Move the two clip-on locks to their standby position (use a screwdriver to press against the relative compartments).
- 2. Install the device on the DIN rail.
- 3. Press on the clip-on locks to put them into the locked position.
- 4. Once assembled on the DIN rail, the clip-on locks must be turned downwards.

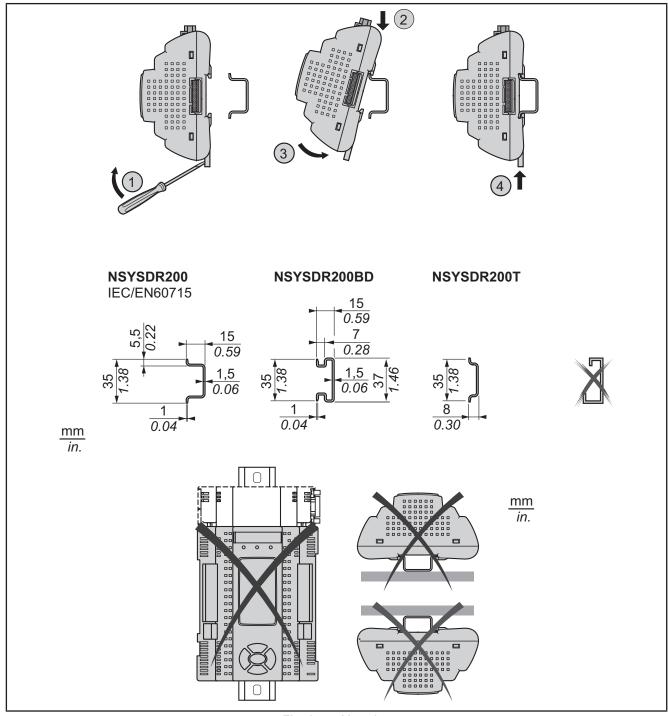


Fig. 2. Mounting

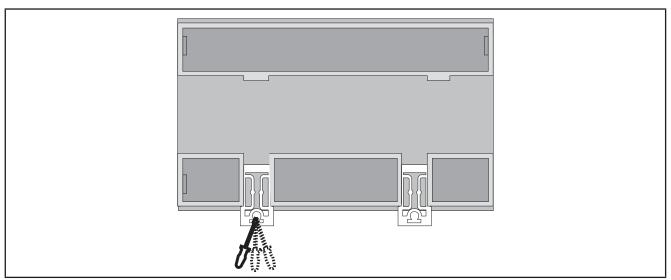


Fig. 3. Details of clip-on locks

The **FREE Evolution logic controller** has been designed as an IP20 product and must be installed in an enclosure. Clearances must be respected when installing the product.

There are 3 types of clearances between:

- The FREE Evolution and all sides of the cabinet (including the panel door).
- The **FREE Evolution** terminal blocks and the wiring ducts. This distance reduces electromagnetic interference between the controller and the wiring ducts.
- The FREE Evolution and other heat generating devices installed in the same cabinet.

A WARNING

UNINTENDED EQUIPMENT OPERATION

- Place devices dissipating the most heat at the top of the cabinet and ensure adequate ventilation.
- Avoid placing this equipment next to or above devices that might cause overheating.
- Install the equipment in a location providing the minimum clearances from all adjacent structures and equipment as directed in this document.
- · Install all equipment in accordance with the specifications in the related documentation.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

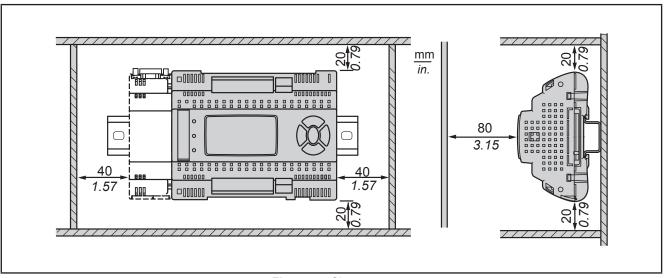


Fig. 4. Clearances

2.7. Assembling the EVS Communication modules

Communication modules are 2DIN modules that connect to an EVD / EVC controller (refer to Fig. 5 on page 20 and Fig. 6 on page 20).

To assemble EVS to EVD / EVC, follow the steps described below:

- 1. Remove the door (if present) on the left side of the EVD / EVC controller by using fingers or a screw-driver.
- 2. Anchor EVS to the EVD / EVC controller.
- · via the Communication module connector, behind the removable door.
- · with the fixing screws to which the Communication module is anchored to.

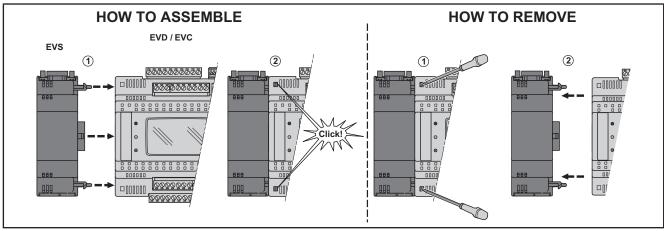


Fig. 5. Assembling the EVS Communication modules

Follow the instructions below to install it on DIN rail:

- 1. Move the clip-on locks (two for EVD / EVC, one for EVS) to its standby position (use a screwdriver).
- 2. Install EVD / EVC + EVS on the DIN rail.
- 3. Press the clip-on locks which will go to the closing position.
- 4. Once the "BASE" is mounted on the DIN rail, the clip-on locks must be turned downwards.

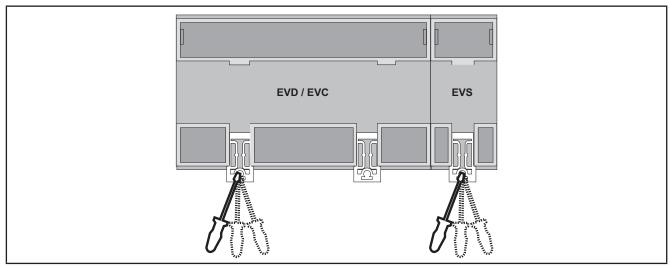


Fig. 6. Details of clip-on locks

2.8. Assembling the FREE Panel or FREE EVK1000

2.8.1. Panel mounting

The equipment is intended for panel mounting (refer to Fig. 7 on page 21).

The following figures show FREE Panel mounting; same steps are required for FREE EVK1000 mounting.

For panel mounting, follow the steps described below:

- 1. Cut from the panel a 138 x 68 mm rectangular opening.
- 2. Drill, at the specified spacing, 4 holes in the panel that the controller is to be mounted on or two holes, of diameter 2.7 mm.
- 3. Insert the device, fixing it with the screws.
- 4. Press the front of the FREE Panel to close.

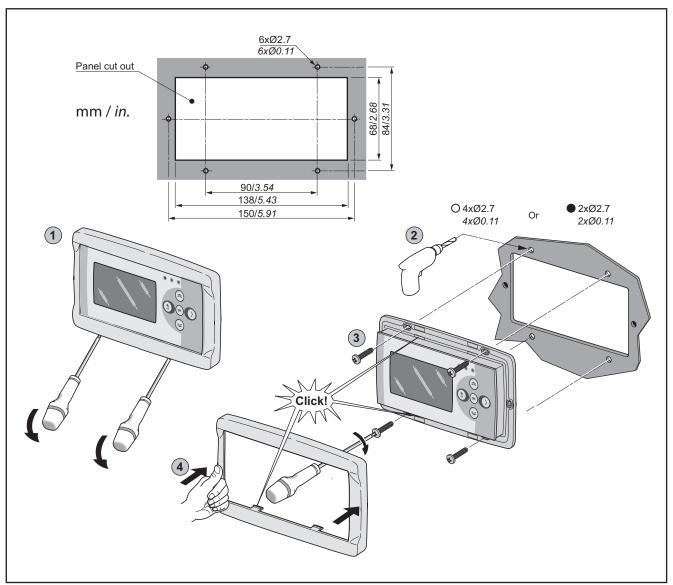


Fig. 7. Assembling the FREE EVK1000 or FREE Panel

2.8.2. Accessories for Wall mounting

The equipment is also intended for wall mounting (refer to **Fig. 8 on page 22**). Contact the **Eliwell** Sales Department for wall-mounting accessories.

- 1. Drill 4 holes of diameter 4.2 mm in the wall at the specified spacing to fix the backplate.
- 2. Use the two side slots, one at the bottom and one at the top, under the pre-formatted removable doors, preventing the opening of holes in the wall.
- 3. Insert the backplate, fixing it with the screws.
- 4. Insert the device, fixing it with the screws.
- 5. Press the front of the **FREE Panel** to close.

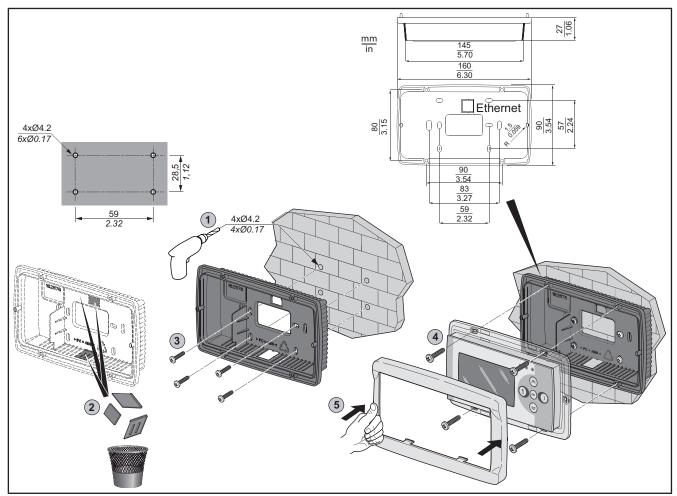


Fig. 8. Accessories for Wall mounting

Reference	Description	
EVA00WMRC0000	White backplate kit for wall mounting	
EVA00WMRC0001	Black backplate kit for wall mounting	
4 backplates per package.		

CHAPTER 3

Electrical connections

3.1. Wiring Best Practices

The following information describes the wiring guidelines and associated best practices to be respected when using the **FREE Evolution Logic Controller**.

A A DANGER

HAZARD OF ELECTRIC SHOCK, EXPLOSION OR ARC FLASH

- Disconnect all power from all equipment including connected devices prior to removing any covers or doors, or installing or removing any accessories, hardware, cables, or wires.
- Always use a properly rated voltage sensing device to confirm the power is removed.
- Replace and secure all covers, accessories, hardware, cables, and wires and confirm that a proper ground connection exists before applying power to the unit.
- · Use only the specified voltage when operating this equipment and any associated products.

Failure to follow these instructions will result in death or serious injury.

A WARNING

LOSS OF CONTROL

- The designer of any control scheme must consider the potential failure modes of control paths and, for certain critical control functions, provide a means to achieve a safe state during and after a path failure. Examples of critical control functions are emergency stop and overtravel stop, power outage and restart.
- Separate or redundant control paths must be provided for critical control functions.
- System control paths may include communication links. Consideration must be given to the implications of unanticipated transmission delays or failures of the link.
- Observe all accident prevention regulations and local safety guidelines.⁽¹⁾
- Each implementation of this equipment must be individually and thoroughly tested for proper operation before being placed into service.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

(1) For additional information, refer to NEMA ICS 1.1 (latest edition), "Safety Guidelines for the Application, Installation, and Maintenance of Solid State Control" and to NEMA ICS 7.1 (latest edition), "Safety Standards for Construction and Guide for Selection, Installation and Operation of Adjustable-Speed Drive Systems" or their equivalent governing your particular location.

3.1.1. Wiring Guidelines

The following rules must be applied when wiring a FREE Evolution logic controllers:

- I/O and communication wiring must be kept separate from the power wiring. Route these two types of wiring in separate cable ducting.
- Verify that the operating conditions and environment are within the specification values.
- Use proper wire sizes to meet voltage and current requirements.
- Use copper conductors (required).
- Use twisted pair, shielded cables for analog, and/or fast I/O.
- Use twisted pair, shielded cables for networks, and fieldbus.

Use shielded, properly grounded cables for all analog and high-speed inputs or outputs and communication connections. If you do not use shielded cable for these connections, electromagnetic interference can cause signal degradation. Degraded signals can cause the controller or attached modules and equipment to perform in an unintended manner.

A WARNING

UNINTENDED EQUIPMENT OPERATION

- Use shielded cables for all fast I/O, analog I/O and communication signals.
- Ground cable shields for all analog I/O, fast I/O and communication signals at a single point (1).
- Route communication and I/O cables separately from power cables.
- Make connections as short as possible and do not wind them around electrically connected parts.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

(1) Multipoint grounding is permissible if connections are made to an equipotential ground plane dimensioned to help avoid cable shield damage in the event of power system short-circuit currents.

NOTE: Surface temperatures may exceed 60 °C. Route primary wiring (wires connected to power mains) separately and apart from secondary wiring (extra low voltage wiring coming from intervening power sources). If that is not possible, double insulation is required such as conduit or cable gains.

3.1.2. Rules for Removable Screw Terminal Block

The following table presents the cable types and wire sizes for a 5.08 or 5.00 pitch removable screw terminal block:

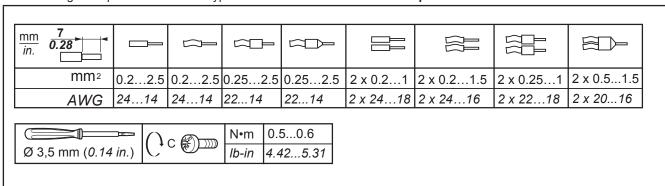


Fig. 9. Pitch 5.08 mm (0.20 in.) or 5.00 mm (0.197 in.)

The following table presents the cable types and wire sizes for a 3.81 or 3.50 pitch removable screw terminal block:

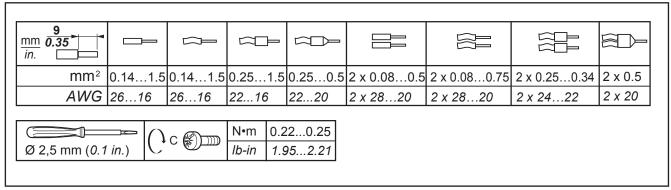


Fig. 10. Pitch 3.81 mm (0.15 in.) or 3.50 mm (0.14 in.)

A A DANGER

LOOSE WIRING CAUSES ELECTRIC SHOCK

Tighten connections in conformance with the torque specifications.

Failure to follow these instructions will result in death or serious injury.

A DANGER

FIRE HAZARD

- Use only the correct wire sizes for the current capacity of the I/O channels and power supplies.
- For 2 A relay output wiring, use conductors with a cross section at least equal to 0.5 mm² (AWG 20) and a temperature rating at least equal to 80 °C (176 °F).
- For 3 A relay output wiring, use conductors with a cross section at least equal to 1.5 mm² (AWG 16) and a temperature rating at least equal to 80 °C (176 °F).
- For common conductors of 8 A relay output wiring, or greater than 3 A relay output wiring, use conductors with a cross section at least equal to 2.0 mm² (AWG 12) and a temperature rating at least equal to 80 °C (176 °F).

Failure to follow these instructions will result in death or serious injury.

3.1.3. Protecting Outputs from Inductive Load Damage

If your controller or module contains relay outputs, these types of outputs can support up to 250 Vac (240 Vac if SSR). Inductive damage to these types of outputs can result in welded contacts and loss of control. Each inductive load must include a protection device such as a peak limiter, RC circuit or flyback diode. Capacitive loads are not supported by these relays.

A WARNING

RELAY OUTPUTS WELDED CLOSED

- Always protect relay outputs from inductive alternating current load damage using an appropriate external protective circuit or device.
- · Do not connect relay outputs to capacitive loads.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

Depending on the load, a protection circuit may be needed for the outputs on the controllers and certain modules. Inductive loads using DC voltages may create voltage reflections resulting in overshoot that will damage or shorten the life of output devices.

A CAUTION

OUTPUT CIRCUIT DAMAGE DUE TO INDUCTIVE LOADS

Use an appropriate external protective circuit or device to reduce the risk of inductive direct current load damage

Failure to follow these instructions can result in injury or equipment damage.

Choose a protection circuit from the following diagrams according to the power supply used. Connect the protection circuit to the outside of the controller or relay output module.

Protective circuit A: this protection circuit can be used for both AC and DC load power circuits.

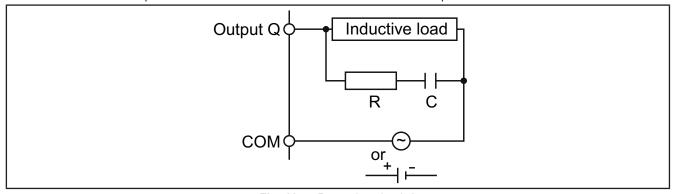


Fig. 11. Protective circuit A

C Value from 0.1 to 1 μF

R Resistor of approximately the same resistance value as the load

Protective circuit B: this protection circuit can be used for DC load power circuits.

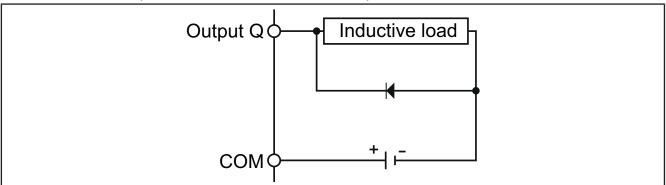


Fig. 12. Protective circuit B

Use a diode with the following ratings:

- Reverse withstand voltage: power voltage of the load circuit x 10.
- Forward current: more than the load current.

Protective circuit C: this protection circuit can be used for both AC and DC load power circuits.

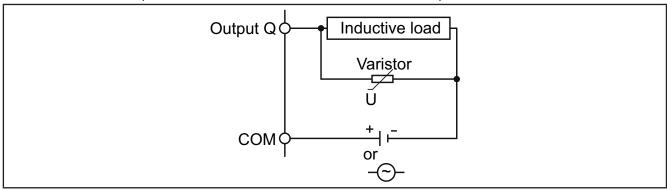


Fig. 13. Protective circuit C

In applications where the inductive load is switched on and off frequently and/or rapidly, ensure that the continuous energy rating (J) of the varistor exceeds the peak load energy by 20 % or more.

NOTE: Place protection devices as close to the load as possible.

3.1.4. Special handling considerations

Care must be taken to avoid damage from electrostatic sources when handling this equipment. In particular exposed connectors and, in some cases, exposed printed circuit boards are vulnerable to electrostatic discharge.

WARNING

UNINTENDED EQUIPMENT OPERATION DUE TO ELECTROSTATIC DISCHARGE DAMAGE

- · Keep equipment in the protective conductive packaging until you are ready to install the equipment.
- Only install equipment in approved enclosures and / or locations that prevent unauthorized access and provide electrostatic discharge protection.
- Use a conductive wrist strap or equivalent field force protective device attached to an earth ground when handling sensitive equipment.
- · Always discharge yourself by touching a grounded surface or approved antistatic mat before handling the equipment.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

3.1.5. Analog Inputs-Probes

Temperature probes have no connection polarity and can be extended using a normal bipolar cable.

A WARNING

UNINTENDED EQUIPMENT OPERATION DUE TO CONNECTION

- · Apply power to all externally powered devices after applying power to the FREE Evolution logic controllers.
- Signal leads (probes, digital inputs, communication and the electronic supply) must be routed separately from power cables.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

NOTICE

INOPERABLE EQUIPMENT

Verify all wiring connections before applying power.

Failure to follow these instructions can result in equipment damage.

NOTE: The extension of the probes influences the electromagnetic compatibility (EMC) of the equipment.

NOTE: Connection polarity must be correctly respected for probes which need a specific polarity.

3.1.6. Serial connections

	The reference has on-board serial	
FREE Evolution	CAN, RS485, USB	
FREE Panel	CAN, RS485, ETHERNET	

Pay special attention when connecting serial lines. Miswiring may lead to inoperable equipment.

NOTICE

INOPERABLE EQUIPMENT

- Do not connect equipment that communicate using RS485 serial to CAN terminals.
- Do not connect CAN equipment to RS485 terminals.

Failure to follow these instructions can result in equipment damage.

Communication modules **FREE EVS** provide additional serial ports for integration with industrial systems, BMS and Ethernet. Controller serials are defined as "on-board" (OB) whereas serials on **FREE EVS** are referred to as Communication modules (PI, stands for "Plug In").

CAN Expansion Bus

- Use a shielded and "twisted pair" cable with two 0.5 mm² section conductors (AWG 22), plus braid such as Belden cable reference 3105A (characteristic impedance 120 Ω) with PVC sleeve, nominal capacity between conductors 36 pF/m, nominal capacity between conductor and shielding 68 pF/m.
- Always follow regulations applicable to the routing and connection of cables. Make certain that data transmission circuits
 are properly separated from power lines.
- For connections over longer distances, it is better to end the line with resistors on both ends, inserting the two **R TERM** jumpers (available on the terminal strip next to the CAN Expansion Bus as the default configuration).
- The maximum distance depends on the baud setting (see the following table).

kb/s (kbaud)	On-board CAN (m) - FREE Evolution	CAN Communication module (m)
50	1000	1000
125	500	500
250	200	250
500	30	60

CAN Expansion Bus is used to communicate with FREE EVK1000 terminal and FREE EVE terminal.

RS 485

- Use a shielded and "twisted pair" cable with two 0.5 mm² section conductors (AWG 22), plus braid such as Belden cable reference 3105A (characteristic impedance 120 Ω) with PVC sleeve, nominal capacity between conductors 36 pF/m, nominal capacity between conductor and shielding 68 pF/m. Alternatively use a shielded and "twisted pair" cable with two 0.5 mm² section conductors (AWG 20), plus braid such as Belden cable reference 8762 with PVC sleeve, nominal capacity between conductors 89 pF/m, nominal capacity between conductor and shielding 161 pF/m. See EN 50174 standard on IT cabling for indications on how cables should be routed.
- Always follow regulations applicable to the routing and connection of cables. Make certain that data transmission circuits
 are properly separated from power lines.
- RS 485 network up to 1200 m in length with a maximum of 32⁽¹⁾ devices can be connected directly to the controller.
 - (1) Example of **FREE Evolution** Modbus Slave with single Master supervisor.
 - This length can be extended and the number of devices for each channel increased using appropriate repeater modules.
- · Single terminal strip with 3 conductors: use all 3 conductors ("+", "-" for the signal and "GND" for the braid).
- Attach the 120 Ω 1/4 W resistors between the "+" and "-" terminals of the interface and the last controller in each branch
 of the network.
- Maximum settable speed 115200 baud.
- RS 485 physical layer can be used for Modbus SL, as well as for BACnet MS/TP communication.
 Concurrent communication of different protocols on the same serial port is NOT allowed.

Pay special attention when connecting serial lines. Miswiring may lead to inoperable equipment.

NOTICE

INOPERABLE EQUIPMENT

Do not communicate through Modbus SL and BACnet MS/TP simultaneously on the same line.

Failure to follow these instructions can result in equipment damage.

Ethernet

The Ethernet connection of the Communication module **EVS ETH / EVS ETH + RS485** allows the **FREE Evolution** logic controller to communicate on an Ethernet network using TCP/IP protocol, whereas **FREE Panel**, with its embedded Ethernet, does **NOT** require an Ethernet Communication module.

The connection allows:

- · connection of different controllers and/or applications exchanging variables and/or parameters (network).
- · connection of a supervision system using Modbus TCP/IP protocol.
- connection of an IEC 61131-3 FREE Studio development system.
- · connection on device on a BACnet/TCP network, with B-AAC profile

Concurrent communication on different protocols using the same Ethernet port is allowed.

The Ethernet connector shield is internally connected to the earth of the equipment and therefore to the reference of the input and output channels.

USB

There are 2 USB connectors placed on the upper-left side of the **FREE Evolution** controller (in the front view) (see **Fig. 14 on page 29**).

- USB Type A is a connector for USB memory key.
- USB Type mini-B is used for programming purposes.
 The components required for FREE Evolution USB mini-B are: TCSXCNAMUM3P or BMXXCAUSBH018.

USB	PURPOSE	NOTE
Type A (HOST)	Used to connect a USB memory key when downloading the application. This should be done from the controller keypad (FREE EVD references) or from the FREE EVK1000 (FREE EVC reference).	See "USB-Host Handling" on 5.3.3. BIOS I/O Values on page 76 for information on how to manage files on USB memory key.
Type mini-B (DEVICE)	Used to connect FREE Evolution to a PC via mini-B USB cable for debugging, commissioning, downloading, uploading with FREE Studio (v3.5 or greater). The operations can be done from PC or another device.	Compatible with the following operating systems: • Windows Vista Business x86 + x64 (Service Pack 2) • Windows 7 x86 + x64 (Service Pack 1) • Windows 8 / 8.1 x86 + x64 • Windows Server 2008, SP2, and R2 • Windows Server 2012 and R2 The driver is supplied with the FREE Studio (v3.5 or greater) software.

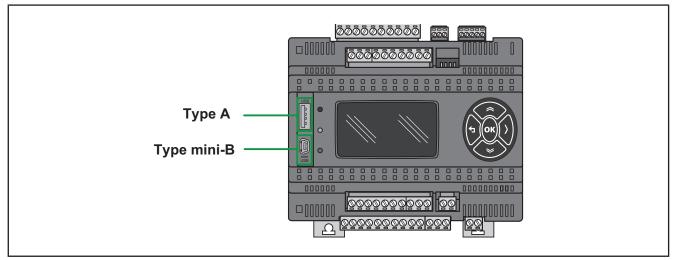


Fig. 14. FREE Evolution: type A USB and type mini-B USB

3.2. Wiring diagrams

Miswiring irreversibly damages the FREE Evolution.

NOTICE

INOPERABLE EQUIPMENT

Verify all wiring connections before applying power.

Failure to follow these instructions can result in equipment damage.

3.2.1. FREE Evolution wiring diagram

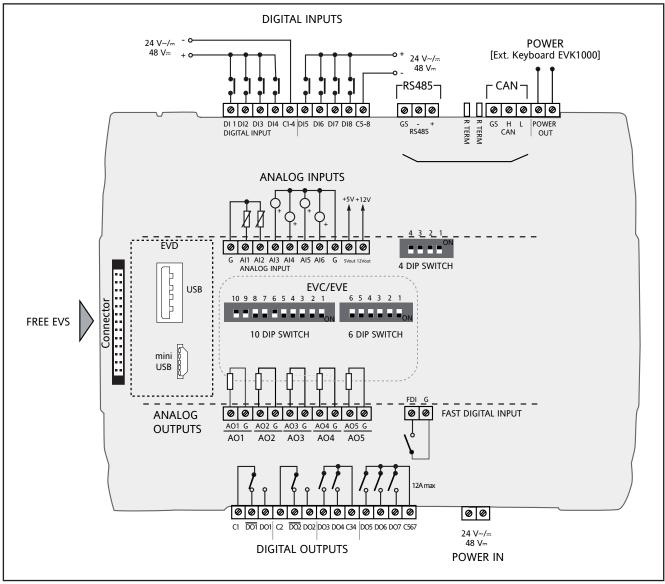


Fig. 15. FREE Evolution wiring diagram

Connector Labels Related To FREE Evolution

	LABEL	DESCRIPTION	NOTES
	4 DIP SWITCH	4-position selectors (Dip Switches)	Dip Switches default OFF
DIP SWITCH	6 DIP SWITCH	6-position selectors (Dip Switches)	Dip Switches default OFF EVC /EVE7500 reference
	10 DIP SWITCH	10-position selectors (Dip Switches)	Dip Switches located behind the panel
POWER	POWER IN	+24 Vac/dc or +48 Vdc power supply	-
SUPPLY	POWER OUT	+24 Vac/dc or +48 Vdc power supply	POWER [Ext. Keyboard EVK1000] output for display
ANALOG	AO1AO5	Analog outputs 15	See CHAPTER 4 Technical data on page
OUTPUTS	G	0 V signal ground	64 for further details
	C1 DO1 DO1	SPDT Relay 1	DO1 is the normally open side, DO1 is the normally closed side
	C2 DO2 DO2	SPDT Relay 2	DO2 is the normally open side, DO2 is the normally closed side
DIGITAL OUTPUTS	DO3 DO4	Relay output 3-4 also available as SSR outputs	
	C34	Common for digital outputs 3-4	-
	DO5 DO6 DO7	Relay output 5-6-7	
	C567	Common for digital outputs 5-6-7	12 A max
CAN	GS H L	Isolated CAN serial GS ground serial isolated from G	R TERM termination resistors for CAN
RS485	GS - +	Isolated RS485 serial GS ground serial isolated from G	Apply 120 Ω termination resistors
	DI1DI4	Digital inputs 14	
DIGITAL	C1-4	Common for digital inputs 14	_
INPUTS	DI5DI8	Digital inputs 58	_
	C5-8	Common for digital inputs 58	
FAST D.I.	FDI	Fast digital input	Pulse/frequency counter up to 1 kHz
	G	0 V signal ground	. discorrequency counter up to 1 KHZ
ANALOG	Al1Al6	Analog inputs	
INPUTS	G	0 V signal ground	
SENSOR	12Vout	12V output for analog inputs	· -
POWER SUPPLY	5Vout	5V output for ratiometric analog inputs	

3.2.2. EVE4200 wiring diagram

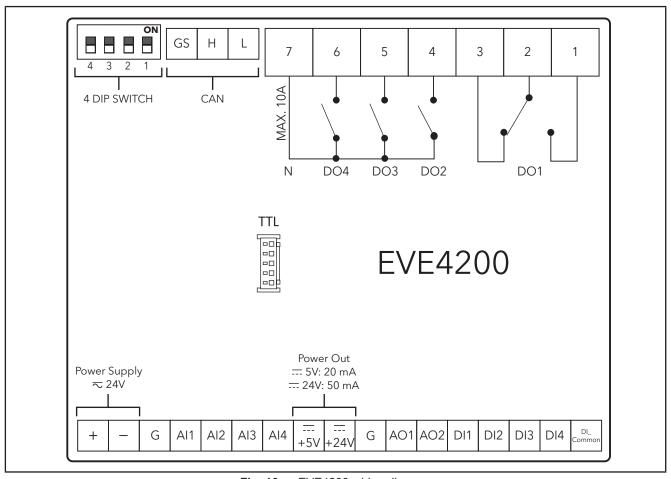


Fig. 16. EVE4200 wiring diagram

Connector Labels Related To EVE4200

	LABEL	DESCRIPTION	NOTES
DIP SWITCH	4 DIP SWITCH	4-position selectors (Dip Switches)	Dip Switches default OFF
POWER SUPPLY	+/-	+24 Vac/dc power supply	-
ANALOG OUTPUTS	AO1, AO2	Analog outputs 1 and 2	
	G	0 V signal ground	See CHAPTER 4 Technical data on page 64 for further details
	+24V	Power Out +24 Vdc output	
	+5V	Power Out +5 Vdc output	
DIGITAL OUTPUTS	1-2-3	SPDT Relay output DO1	1 is the normally open side,3 is the normally closed side
	4-5-6	SPST Relay output 2-3-4 DO2 DO3 DO4	-
	7	Common for relay outputs 2-3-4 N	10 A max
CAN	GS H L	Isolated CAN serial GS ground serial isolated from G	Dip Switches 3-4 termination resistors for CAN
DIGITAL INPUTS	DI1DI4	Digital inputs 14	
	DI_Common	Common for digital inputs 14	-
ANALOG INPUTS	Al1Al4	Analog inputs	
	G	0 V signal ground	-

3.2.3. Examples of analog input connection (FREE Evolution only)

Example: NTC/Pt1000 probe connection

- Analog inputs Al1...Al6 are available for NTC
- Analog inputs Al3...Al6 are available for NTC/Pt1000

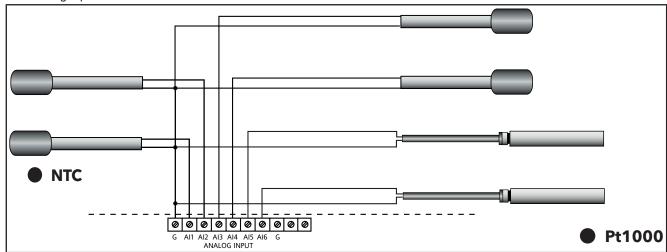


Fig. 17. NTC/Pt1000 probe connection

Example: 0-10 V transducer connection

Analog Inputs Al3...Al6 are available for 0-10 V transducer connection

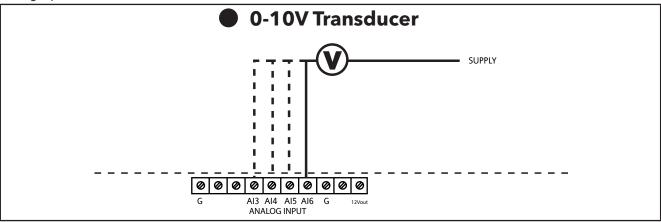


Fig. 18. 0-10 V transducer connection

Example: Digital Input Connection (through analog input terminal)

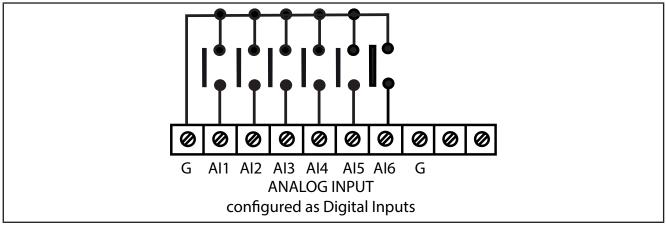


Fig. 19. Analog Inputs configured as Digital Inputs

Example: 4...20 mA pressure transducer connection

Analog Inputs Al3...Al6 are available as 4...20 mA pressure transducer connection.

In the case of a generic 3-wire transducer, connect the 0 V reference wire (ground if so indicated by the transducer manufacturer) to terminal GND and the transducer power supply to **12 Vdc** screw terminal.

NOTICE

INOPERABLE EQUIPMENT

Verify all wiring connections before applying power.

Failure to follow these instructions can result in equipment damage.

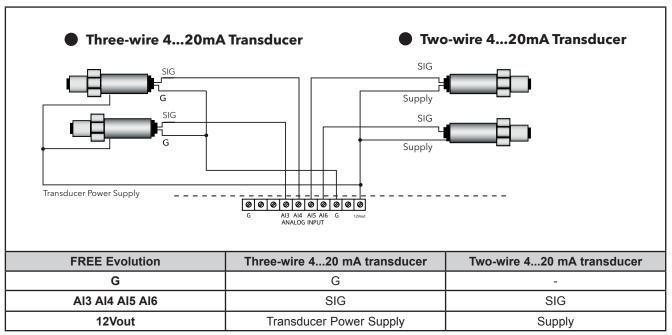


Fig. 20. 4...20 mA pressure transducer connection

Example: ratiometric transducer connection

Analog Inputs Al3...Al6 are available as ratiometric transducer connection

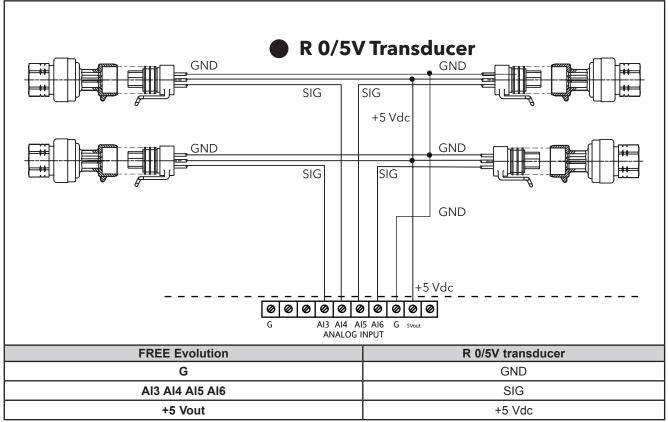


Fig. 21. Ratiometric transducer connection

Example: fan module connection

- 5 available analog outputs: AO1...AO5
- Example diagram with 4 ...20mA or 0-10V fan module

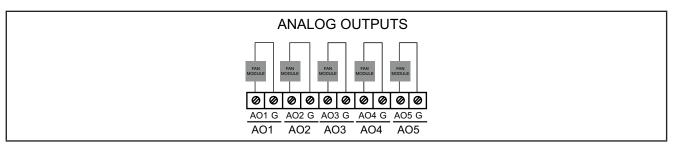


Fig. 22. Fan module connection

Example: Open Collector connection

- 2 Open Collector outputs available as Open Collector connection: AO4/AO5
- Example with an external relay

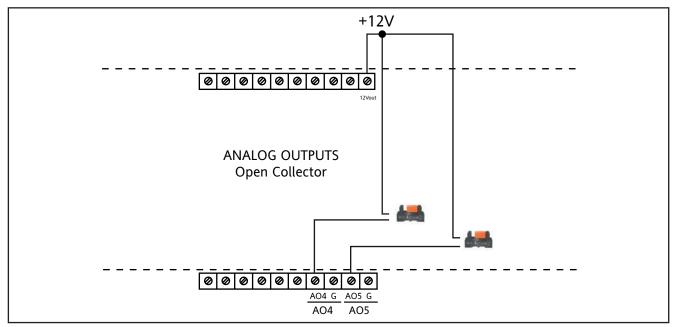


Fig. 23. Open Collector connection

3.2.4. FREE Evolution / EVK1000 connection

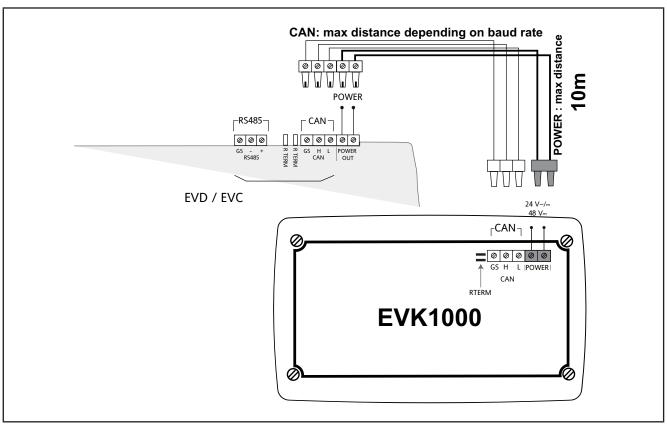


Fig. 24. FREE Evolution/ FREE EVK1000 terminal connection

NOTE: When supplying power from the **FREE Evolution logic controllers**, make the power connection cable as short as possible.

NOTICE

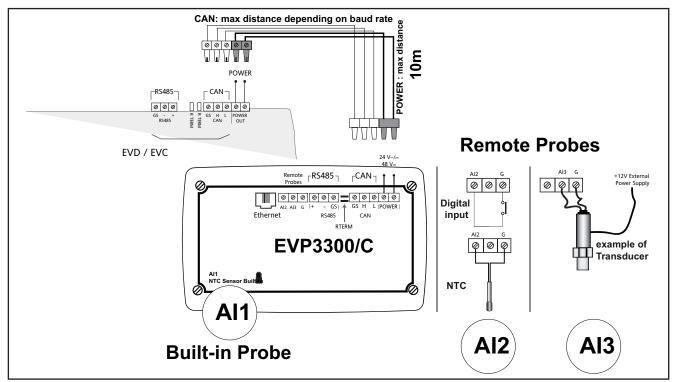
INOPERABLE EQUIPMENT

Do not connect a power cable longer than 10m.

Failure to follow these instructions can result in equipment damage.

	LABEL	DESCRIPTION	NOTES	
POWER POWER IN		+24 Vac/dc or +48 Vdc power supply	Maximum cable length 10m	
POWER POWE	POWERIN	+24 vac/dc of +46 vdc power suppry	from EVD or separate power supply	
		loolated CAN periol	R TERM termination resistors for CAN	
CAN GS	GS H L	S H L Isolated CAN serial GS ground serial insulated from G	Maximum cable length See 3.1.6. Serial connections on page 27	

3.2.5. EVP3300/C and EVP3500/C/RH connection



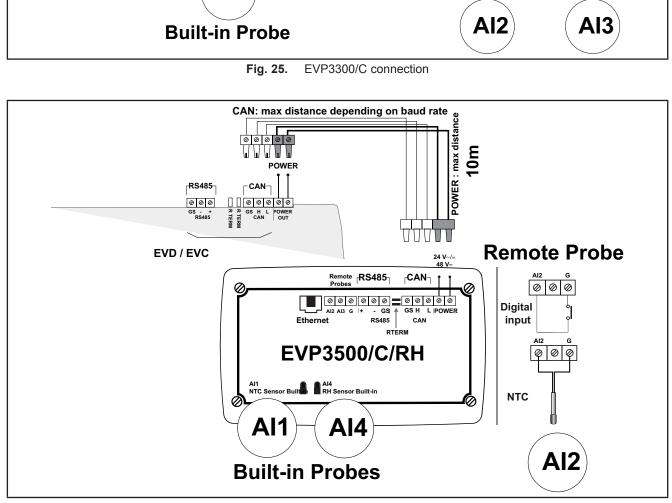


Fig. 26. EVP3500/C/RH connection

NOTE: When supplying power from the **FREE Evolution logic controllers**, make the power connection cable as short as possible.

NOTICE

INOPERABLE EQUIPMENT

Do not connect a power cable longer than 10m.

Failure to follow these instructions can result in equipment damage.

Label	Description	Notes
POWER	+24 Vac/dc or +48 Vdc power supply	Pin POWER Vout on EVD / EVC Max. distance 10m EVP / EVD / EVC
CAN GS H L	Isolated CAN serial GS ground serial isolated from G	R TERM termination resistors for CAN
RS485 GS - +	Isolated RS485 serial GS ground serial isolated from G	Apply 120 Ω terminal resistors
Ethernet ETHERNET serial		-
Built-in Al1 NTC Sensor On-board NTC sensor		-
Al2 Remote Probes G	NTC, D.I. remote Ground GND	Probe not included
Al3 Remote Probes G	420 mA / 0-10 V -+/ 0-5 V Ground GND	EVP3300/C Probe not included 12 V External power supply
Built-in Al4 RH Sensor On-board RH% sensor		EVP3500/C/RH

3.3. FREE Evolution protocol connectivity

3.3.1. Example: CAN (Field) network connection

A CAN (Field) network connection can be constituted by:

- Max 1 EVD functioning as MASTER
- Max 12 EVE functioning as SLAVES

NOTE: No more than two EVK1000 can be added to the network connected to EVD

The **EVK1000** is supplied by **EVD** via the POWER OUT output.

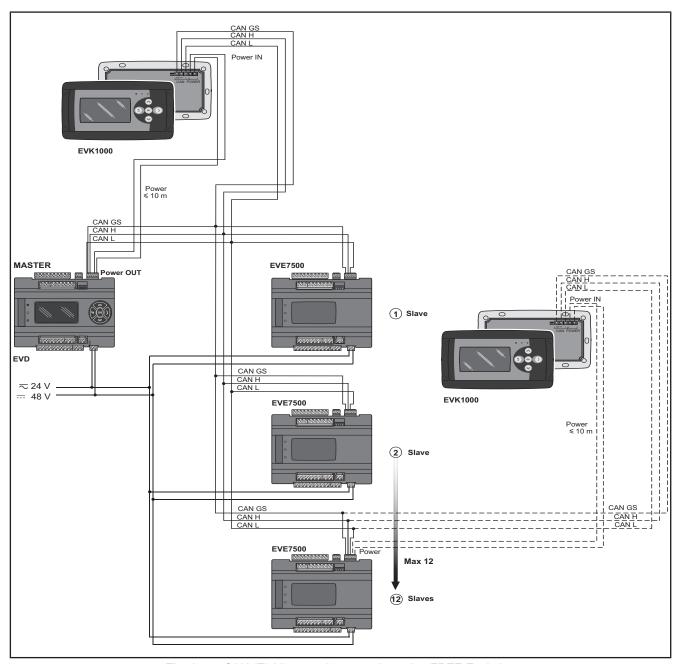


Fig. 27. CAN (Field) network connection using FREE Evolution

3.3.2. Example: CAN connection (Network)

A CAN connection (Network) can be constituted by:

- 1 EVD
- 1 EVK1000 connected in CAN to EVD or alternatively, to EVC.

NOTE: Max 10 EVC connected in CAN (binding).

The **EVK1000** is supplied by **EVD** via the POWER OUT output.

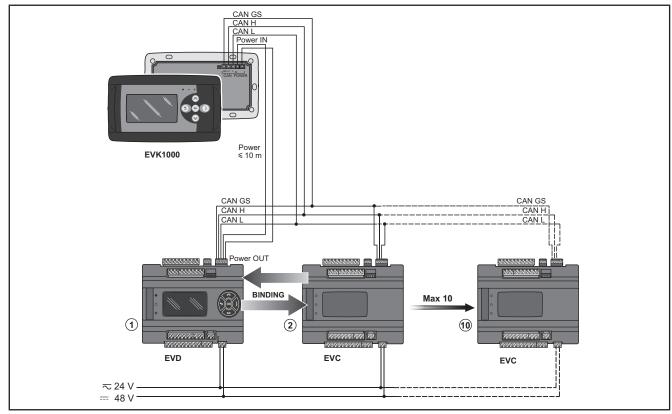


Fig. 28. CAN connection (Network) using FREE Evolution

3.3.3. Example: RS485 connection (Field)

A RS485 connection (Field) can be constituted by:

Description	Notes
1 EVD	EVD is in Modbus RTU Master mode
Max 127 EVE7500 expansion modules connected in RS485	EVE7500 are in Modbus RTU Slave mode
1 EVK1000 connected in CAN to EVD	-

The **EVK1000** is supplied by **EVD** via the POWER OUT output.

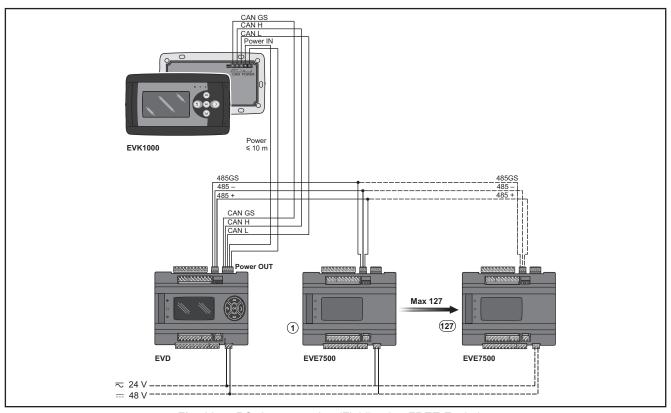


Fig. 29. RS485 connection (Field) using FREE Evolution

3.3.4. Example: RS485 connection with the FREE Smart network

A RS485 connection with the **FREE Smart** network can be constituted by:

Description	Notes
EVD	EVD is in Modbus RTU Master mode
Max 127 EVD / EVC or SMC-SMD-SMP4500-5500/C/S / SMD3600/C/S 2T or Eliwell and/or third-party devices equipped with RS485 serial	All devices equipped with RS485 are in Modbus RTU Slave mode (including the FREE Evolution logic controllers) See also the FREE Smart manual for further details.
CAN network – see 3.3.1. Example: CAN (Field) network connection on page 40.	The CAN connection can be • Field, as illustrated • Network, if one or more EVD / EVCs are connected
1 EVK1000 connected in CAN to EVD	-

The FREE EVK1000 is supplied by EVD via the POWER OUT output.

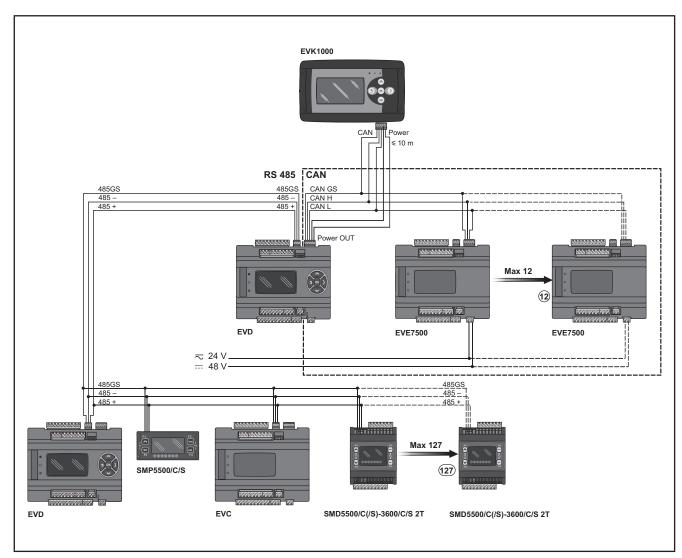


Fig. 30. RS485 connection with the FREE Smart using FREE Evolution

3.4. FREE Panel protocol connectivity

3.4.1. Example: RS485 connection (Field)

A RS485 connection (Field) can be constituted by:

Description	Notes
1 FREE Panel	FREE Panel is in Modbus RTU Master mode
Max 127 EVE7500 expansion modules connected in RS485	EVE7500 are in Modbus RTU Slave mode

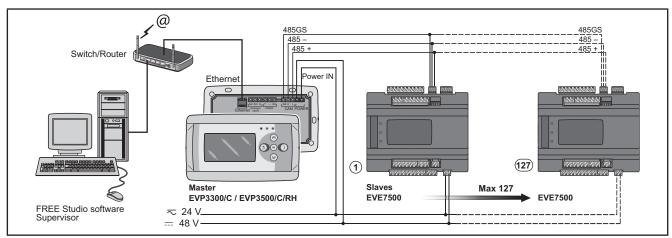


Fig. 31. RS485 connection (Field) using FREE Panel

3.4.2. Example: CAN connection

A CAN connection can be constituted by 1 FREE Panel.

NOTE: Max 12 EVE expansion modules connected in CAN.

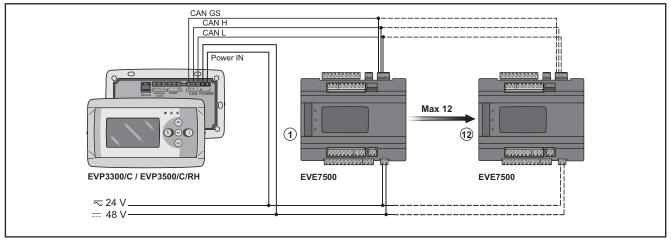


Fig. 32. CAN connection using FREE Panel

3.4.3. Example: RS485 connection with the FREE Smart network

A RS485 connection with the **FREE Smart** network can be constituted by:

Description	Notes
1 FREE Panel	FREE Panel is in Modbus RTU Master mode
Max 127 EVD / EVC or FREE Smart or Eliwell and/or third- party equipment equipped with RS485 serial	All devices equipped with RS485 are in Modbus RTU Slave mode (including the FREE Evolution logic controllers) See also the FREE Smart manual for further details.
CAN network	see 3.4.2. Example: CAN connection on page 44

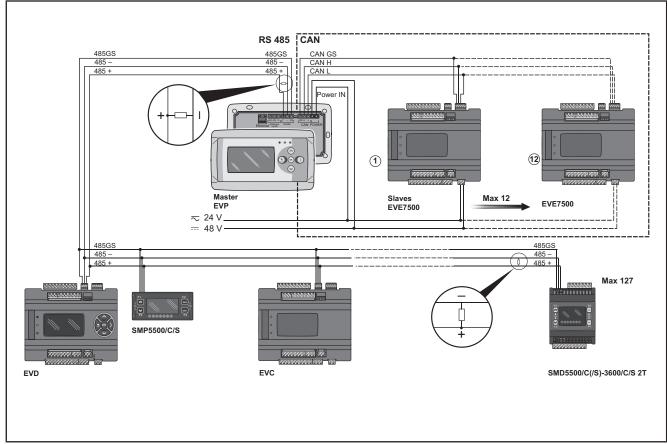


Fig. 33. RS485 connection with the FREE Smart network using FREE Panel

3.4.4. Example: CAN network connection

A CAN network connection can be constituted by 1 FREE Panel.

NOTE: Max 10 EVD / EVC.

NOTE: CAN network: see 3.4.2. Example: CAN connection on page 44

HMI menu

FREE Panel can be equipped with its own menu (named Network menu).

In this case **FREE Panel logic controller** is programmed with the network menu, which can read variables present in the **FREE Evolution logic controller** network.

FREE Panel logic controller can operate from the individual controllers and download up to 10 remote menus from the respective **FREE Evolution logic controllers**.

In this case the remote menu allows 'local' navigation of the individual FREE Evolution logic controller.

Controller application

The variables of the various controllers are shared (bound together).

An application present on **FREE Panel** logic controller can use variables present in the network and share its own variables with other applications present on the respective **FREE Evolution logic controllers**.

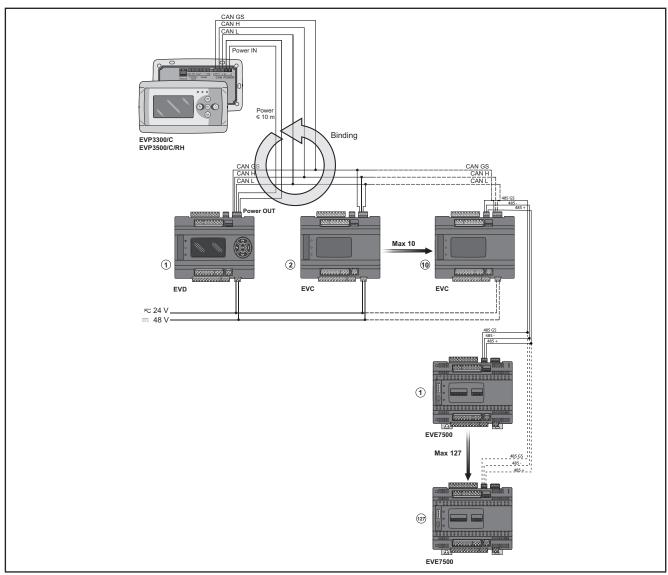


Fig. 34. CAN network connection using FREE Panel

3.5. EVS Communication modules

Communication modules are 2DIN modules that can be connected to an **FREE Evolution** controller or an **FREE Advance** controller (with restrictions, refer to the **FREE Advance** controller Hardware Guide) via the Communication module connector on the left side, behind the removable door. The Communication module is anchored to the controller with the two fixing hooks.

It mounts to the DIN rail in the same way as the controller.

3.5.1. Communication modules compatible with FREE Evolution and FREE Advance

Interface for	Communication module	
RS 232	EVS RS232/R	5A SPDT relay available
RS 485	EVS RS485 EVS RS485 BACnet MS/TP	RS 485 in Daisy Chain(1)
CAN Expansion Bus	EVS CAN	CAN Expansion Bus in Daisy Chain(1)
LON	EVS LON	LonWorks Communication module

⁽¹⁾ Use a shielded cable. See 3.1.6. Serial connections on page 27.

NOTE: The LonWorks Communication module supports up to 63 nodes. Exceeding this specification may result in an electrical overload condition in the **EVS LON** Communication module and consequently in the controller.

WARNING

UNINTENDED EQUIPMENT OPERATION

Do not exceed the maximum of 63 nodes on the EVS LON Communication module.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

For more information on the LonWorks network, visit www.echelon.com/technology/lonwork/

3.5.2. Communication modules exclusively compatible with FREE Evolution

Interface for	Communication module	
ETHERNET	EVS ETH EVS ETH + RS485	The MACADDRESS is supplied in the box, Expressed as barcode and 12-digit alphanumeric code. The Ethernet connector shield is connected internally to the equipment ground, and therefore to the reference of the input and output channels
		FREE WEB: WEB functionalities of EVD7500/C/U(/SSR) or EVC7500/C/U + EVS ETH/ EVS ETH + RS485 Communication module
PROFIBUS	EVS PROFIBUS Profibus DP Slave-V0	Contact your local Eliwell representative for more information concerning the .GSD Profibus configuration file
	Prolibus DP Slave-vu	See official Profibus documentation for more detailed information

Communication module EVS are shown below:

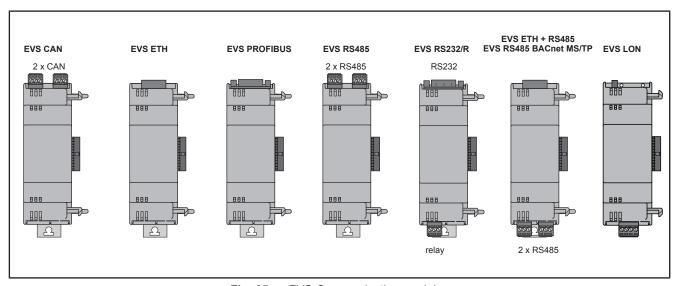


Fig. 35. EVS Communication modules

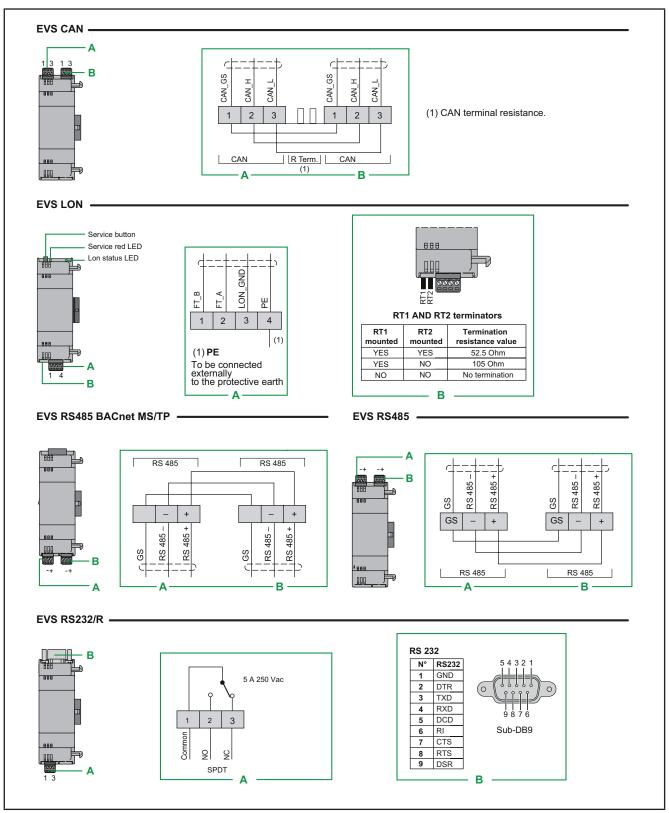


Fig. 36. Communication modules compatible with FREE Evolution / Advance

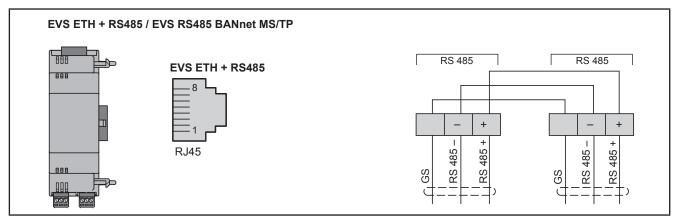


Fig. 37. ETHERNET, ETHERNET+RS485 Communication modules

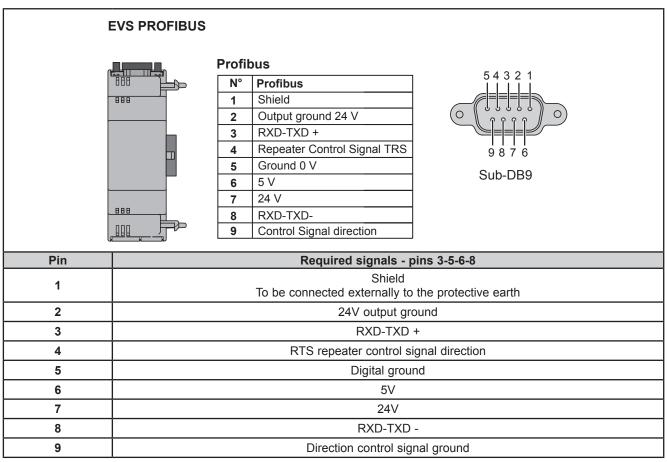


Fig. 38. PROFIBUS Communication module

NOTE: In a network with Profibus Communication modules, the first and last element in the network must terminate with Profibus resistors.

3.5.3. EVS RS232/R

The RS232 Communication module allows **FREE Evolution / Advance** DIN rail mounted controllers to communicate via an RS232 serial.

Modbus RTU communication protocol

The connection allows:

- · connection to a supervision system using the Modbus RTU protocol
- connection of an IEC 61131-3 FREE Studio development system

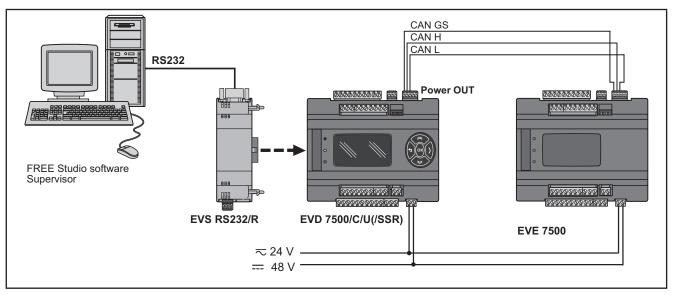


Fig. 39. Modbus RTU communication protocol using EVS RS232/R

Modbus ASCII communication protocol send/receive AT commands for modem⁽¹⁾

This protocol activates when there is a modem connected to the Communication module. The connection allows:

- connection to a monitoring system using the Modbus ASCII protocol;
- · connection of an IEC 61131-3 FREE Studio development system;
- send/receive TXT messages via a modem connected to the RS232⁽²⁾ port.

NOTE: The Communication module has a relay that can be piloted from the controller application to allow the modem to be activated/reset or as an additional digital output.

(1) Refer to the **Modem_IEC.pll** software library in

C:\Program Files (x86)\Eliwell\free Studio\Catalog\FreeEvolution\PLC

(2) Refer to the SMS IEC.pll software library in

C:\Program Files (x86)\Eliwell\free Studio\Catalog\FreeEvolution\PLC

See FREE Studio Manual for details.

NOTE:

Refer to the section on Parameters / RS232 PASSIVE PLUG-IN folder (see **CHAPTER 9 Parameters on page 102**). Refer to the section on Parameters / MODEM folder (see **CHAPTER 9 Parameters on page 102**).

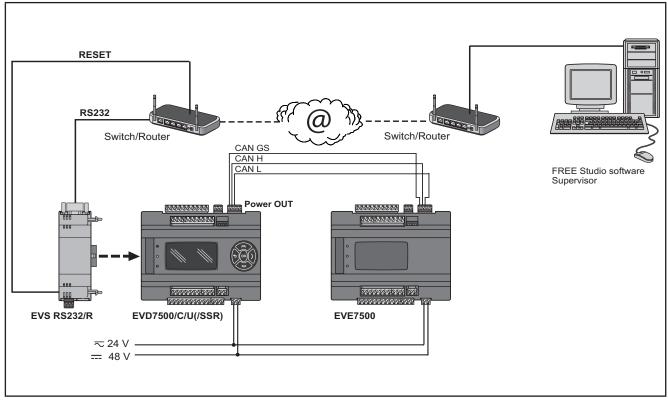


Fig. 40. Modbus ASCII communication protocol using EVS RS232/R

3.5.4. EVS ETH / EVS ETH + RS485

The Ethernet Communication module enables communication of the **EVD** / **EVC** on an Ethernet network using the Modbus TCP protocol.

The connection allows:

- network connection of different controllers and/or applications exchanging variables and/or parameters (network)
- · connection to a supervision system using the Modbus TCP protocol
- connection of an IEC 61131-3 FREE Studio development system

NOTE:

The MAC ADDRESS (<u>barcode and 12-digit alphanumeric code</u>) is supplied in the box containing the Ethernet Communication module.

Refer to the section on Parameters / ETHERNET PASSIVE PLUG-IN folder (see CHAPTER 9 Parameters on page 102).

NOTE: The Ethernet connector shield is connected internally to the functional ground, and therefore to the reference of the input and output channels. Care must be taken to the fact there may be within the Ethernet communications system other grounding points. Interconnection of multiple protective earth grounding points in the same installation can cause current loops and voltage shifts across conductive parts of the equipment.

WARNING

UNINTENDED EQUIPMENT OPERATION

Do not connect the connector shield to protective earth (PE) or to functional earth (FE) of your installation.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

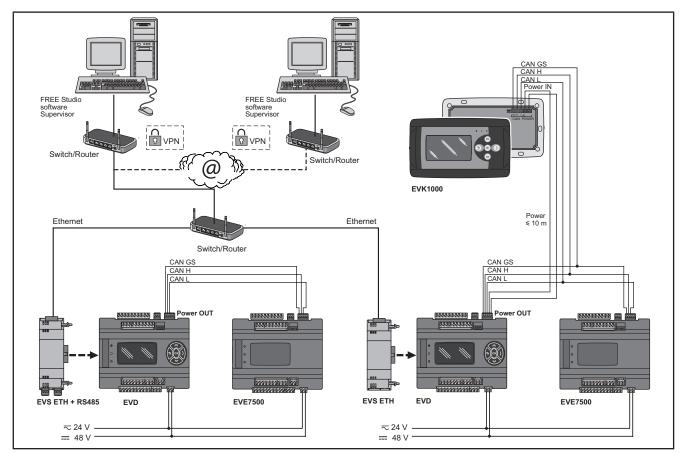


Fig. 41. Modbus TCP protocol using EVS ETH

VPN is not necessary when using DynDNS connection.

Protocol	Field	Network
Modbus TCP	-	Max 10 FREE Evolution+ 2 EVK1000 Max Modbus Messages = 128 / number of FREE Evolution connected

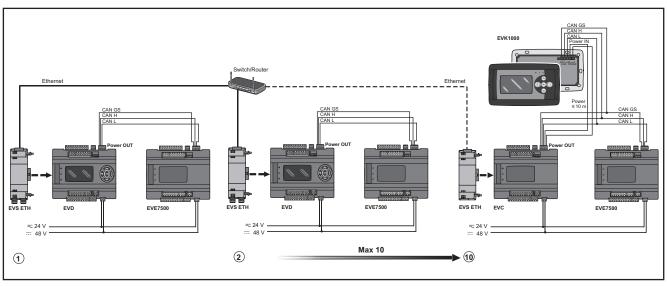


Fig. 42. Modbus TCP protocol using EVS ETH - limits

3.5.5. Example: BACnet / IP

Protocol	Field	Network
BACnet IP	-	Max 4 FREE Evolution

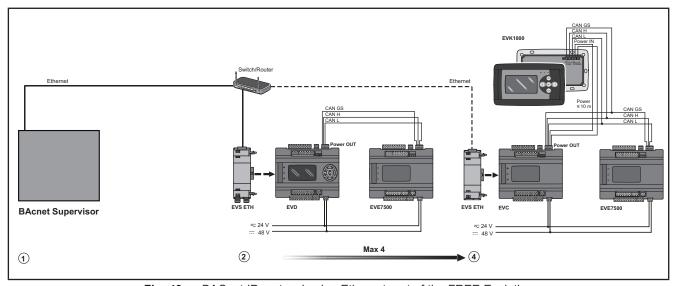


Fig. 43. BACnet IP protocol using Ethernet port of the FREE Evolution

FREE WEB (WEB SERVER HTTP)

FREE WEB is an EVD/ EVC with the EVS ETH Communication module.

The Ethernet Communication module also uses HTTP protocol, i.e. allowing access to a Web Server contained in **FREE Evolution**.

FREE Studio (v3.5 or greater) allows the creation and management of web pages internally of FREE WEB (WEB SERVER HTTP), i.e. a website in miniature.

WEB functionalities allow local and remote access by way of an ordinary browser. Thanks to the web connection, the system provides reading, support and diagnostics services, as well as e-mail alarm alerts.

Main web functionalities:

- · Web-based access.
- · Remote reading and support.
- · Local and remote system control, including alarms management.
- · Preventive and predictive maintenance.
- · Email alarm alerts.

Care must be taken and provisions made for use of this product as a control device to avoid inadvertent consequences of commanded machine operation, controller state changes, or alteration of data memory or machine operating parameters.

A WARNING

UNINTENDED EQUIPMENT OPERATION

- Configure and install the mechanism that enables the remote HMI local to the machine, so that local control over the machine can be maintained regardless of the remote commands sent to the application.
- You must have a complete understanding of the application and the machine before attempting to control the application remotely.
- Take the precautions necessary to assure that you are operating remotely on the intended machine by having clear, identifying documentation within the application and its remote connection.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

Refer to the section on Parameters / ETHERNET PASSIVE PLUG-IN folder (see CHAPTER 9 Parameters on page 102).

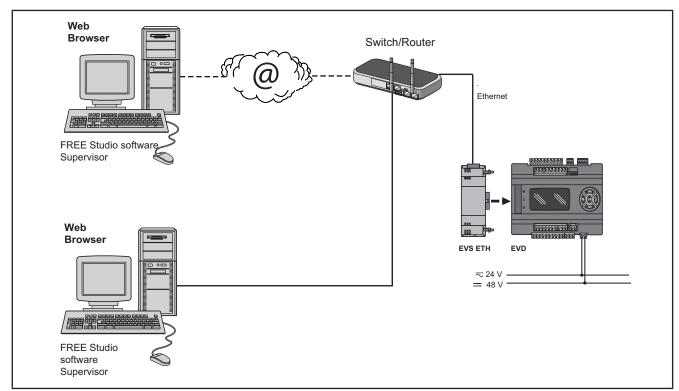


Fig. 44. FREE WEB (WEB SERVER HTTP) using FREE Evolution and EVS ETH

BRIDGE

FREE Studio allows monitoring of the **FREE Smart** or **FREE Evolution** controller or third party devices, typically Modbus/RTU slaves, where **FREE WEB** (or **FREE Evolution** with **EVS ETH** Communication module) is the Master Modbus/RTU.

In a **FREE Studio** project, more exactly, **FREE WEB** is used as a Modbus/TCP to Modbus/RTU protocol conversion element for Modbus 0x03 and 0x10 commands.

For example from **FREE Studio**, set the connection with the **FREE Smart** as Modbus/TCP, inserting the **FREE WEB** IP address and the Modbus/RTU address of the **FREE Smart** slave.

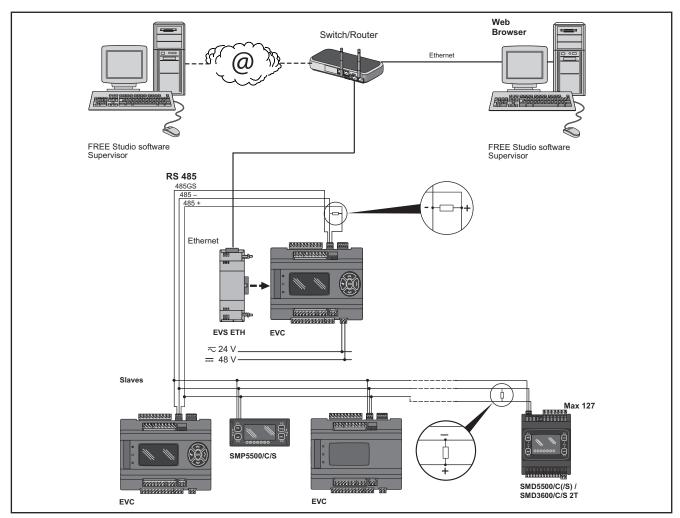


Fig. 45. BRIDGE using EVS ETH

TFTP (Trivial File Transfer Protocol)

TFTP can also be enabled for file transfer between PC and controller on an Ethernet network.

3.5.6. EVS RS485

The RS485 Communication module allows **FREE Evolution / Advance** DIN rail mounted controllers to communicate via an RS485 serial using a Modbus RTU Master/Slave communication protocol, in addition to the RS485 serial. The connection allows:

- · connection to a supervision system using the Modbus RTU protocol
- · connection of an IEC 61131-3 FREE Studio development system
- · connection to peripheral Modbus devices (for example EVE)

The two CAN serials ports (integrated and Communication module) offer the same level of services. **FREE Evolution**manages only one of the two as Modbus Master. Both can operate as a Modbus Slave.

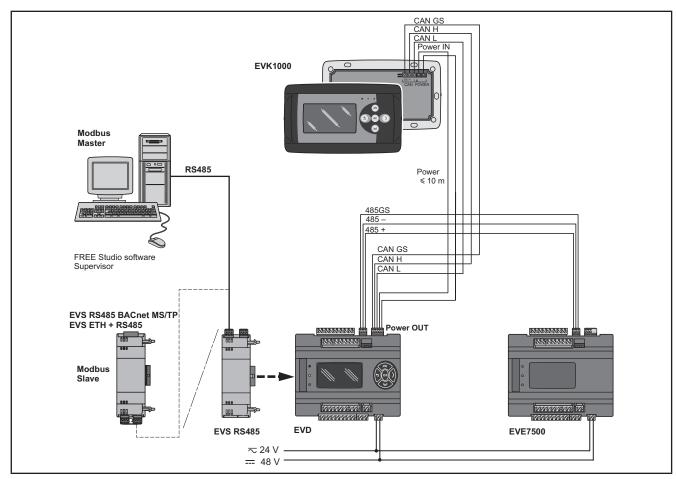


Fig. 46. Modbus RTU protocol using EVS RS485

3.5.7. EVS RS485 BACnet MS/TP / EVS ETH + RS485

The connection allows **FREE Evolution** controllers to connect to a BACnet supervision system using the BACnet MS/TP communication protocol.

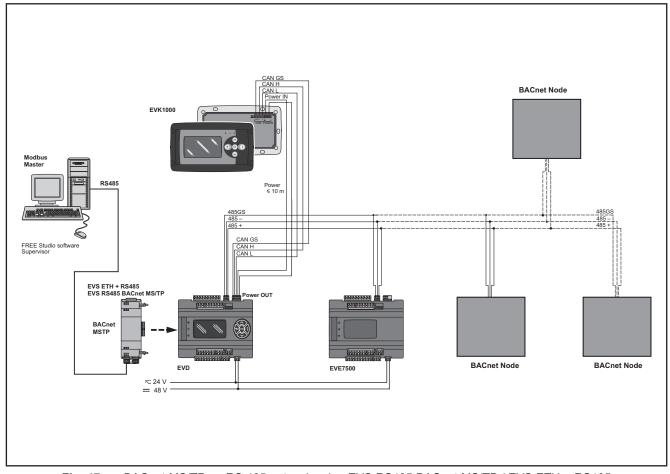


Fig. 47. BACnet MS/TP on RS 485 network using EVS RS485 BACnet MS/TP / EVS ETH + RS485

3.5.8. EVS CAN

The CAN Communication module allows **FREE Evolution / Advance** DIN rail mounted controllers to communicate via a CAN serial using a CAN protocol in addition to the existing CAN serial. It allows:

- connection to a supervision system using the CAN protocol.
- connection of an IEC 61131-3 FREE Studio development system.
- connection to **EVE** expansions.
- · connection to EVK1000 devices.

The two CAN serials ports (integrated and Communication module) offer the same level of services. **FREE Evolution**manages only one of the two to pilot expansions.

Refer to the section on Parameters / CAN PASSIVE PLUG-IN folder (see CHAPTER 9 Parameters on page 102).

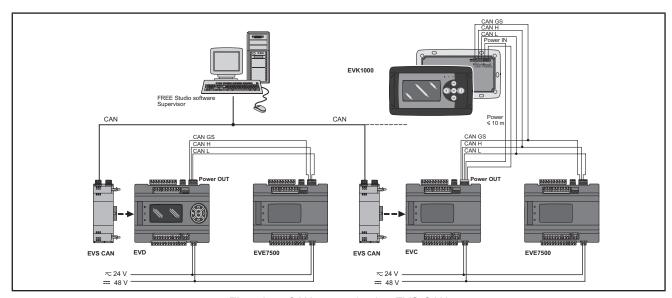


Fig. 48. CAN protocol using EVS CAN

3.5.9. EVS PROFIBUS

The PROFIBUS Communication module allows **EVD** and **EVC** to communicate via a Profibus serial using the Profibus DP Slave V-0 communication profile.

The connection allows interface with a supervision system or master controller using the Profibus protocol.

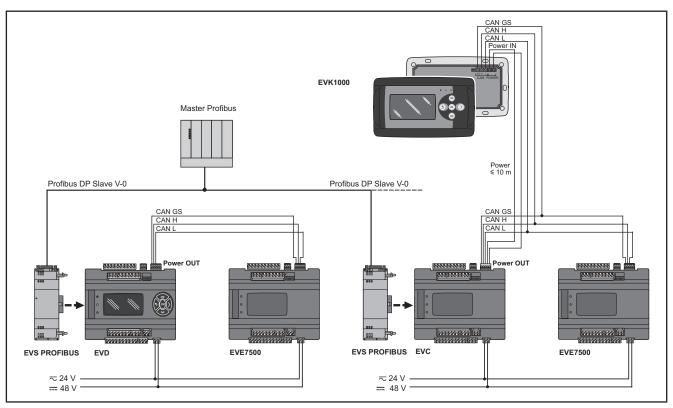


Fig. 49. Profibus protocol using EVS PROFIBUS

3.5.10. EVS LON

The LON Communication module allows **FREE Evolution / Advance** DIN rail mounted controllers to communicate via a LON serial using the LonWorkS (FFT-10) communication profile.

The connection allows interface with a supervision system or master controller using the LON protocol.

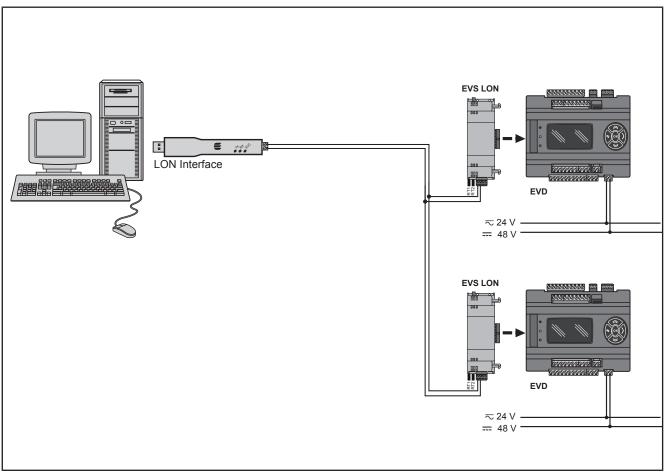


Fig. 50. LON protocol using EVS LON

NOTE: The LonWorks Communication module supports up to 63 nodes. Exceeding this specification may result in an electrical overload condition in the **EVS LON** Communication module and consequently in the controller.

A WARNING

UNINTENDED EQUIPMENT OPERATION

Do not exceed the maximum of 63 nodes on the EVS LON Communication module.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

For more information on the LonWorks network, visit www.echelon.com/technology/lonwork/

3.6. Ethernet connection (for FREE Panel)

The FREE Panel product is also designated for FREE WEB

The Ethernet connection also allows communication using HTTP protocol, i.e. access to a Web Server contained in **FREE Evolution**.

FREE Studio (v3.5 or greater) allows the creation and management of web pages internally of **FREE WEB** (**WEB SERVER HTTP**), i.e. a website in miniature.

WEB functionalities allow local and remote access by way of an ordinary browser. Thanks to the web connection, the system provides reading, support and diagnostics services, as well as e-mail alarm alerts.

Main web functionalities:

- Web-based access.
- · Remote reading and support.
- · Local and remote system control, including alarms management.
- · Preventive and predictive maintenance.
- · Email alarm alerts.

Care must be taken and provisions made for use of this product as a control device to avoid inadvertent consequences of commanded machine operation, controller state changes, or alteration of data memory or machine operating parameters.

A WARNING

UNINTENDED EQUIPMENT OPERATION

- Configure and install the mechanism that enables the remote HMI local to the machine, so that local control over the machine can be maintained regardless of the remote commands sent to the application.
- You must have a complete understanding of the application and the machine before attempting to control the application remotely.
- Take the precautions necessary to assure that you are operating remotely on the intended machine by having clear, identifying documentation within the application and its remote connection.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

Refer to the section on Parameters / ETHERNET PASSIVE PLUG-IN folder (see CHAPTER 9 Parameters on page 102).

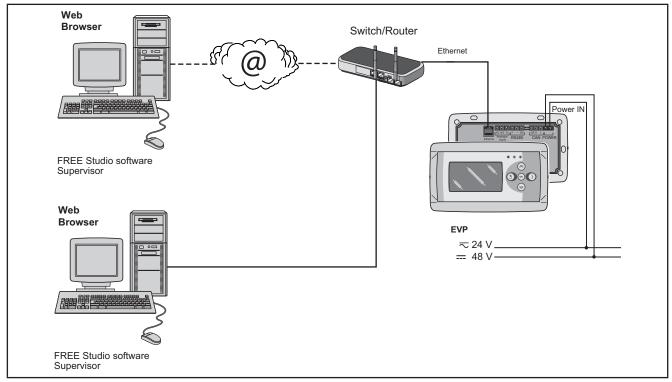


Fig. 51. FREE WEB using FREE Panel

BRIDGE

FREE Studio allows monitoring of the FREE Smart or FREE Evolution controller or third party devices, typically Modbus/RTU slaves, where FREE WEB (or FREE Panel logic controller with Communication module EVS ETH) is the Master Modbus/RTU.

In a **FREE Studio** project, more exactly, **FREE WEB** is used as a Modbus/TCP to Modbus/RTU protocol conversion element for Modbus 0x03 and 0x10 commands.

For example from **FREE Studio**, set the connection with the **FREE Smart** as Modbus/TCP, inserting the **FREE WEB** IP address and the Modbus/RTU address of the **FREE Smart** slave.

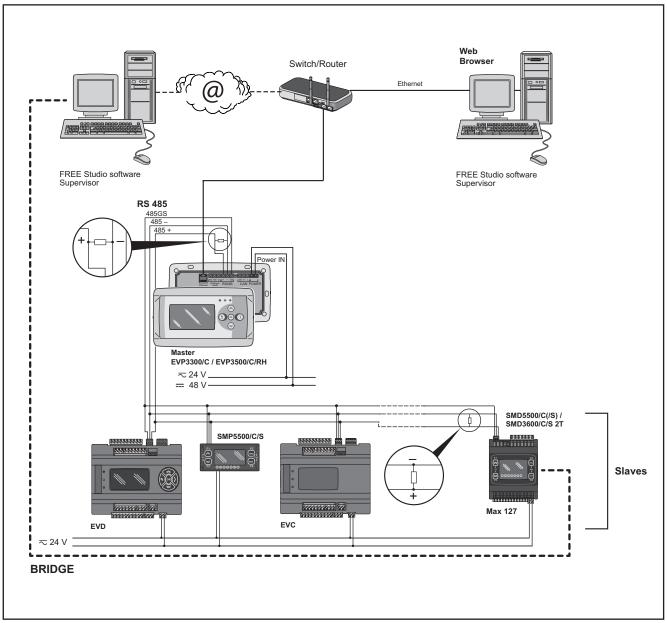


Fig. 52. FREE WEB using FREE Panel

TFTP (Trivial File Transfer Protocol)

TFTP (Trivial File Transfer Protocol) can also be enabled for file transfer between PC and controller on an Ethernet network.

CHAPTER 4

Technical data

All **FREE Evolution logic controllers** system components meet European Community (CE) requirements for open equipment. You must install them in an enclosure or other location designed for the specific environmental conditions and to minimize the possibility of unintended contact with hazardous voltages. Use metal enclosures to improve the electromagnetic immunity of your **FREE Evolution logic controllers** system. This equipment meets CE requirements as indicated in the table below.

A WARNING

UNINTENDED EQUIPMENT OPERATION

Do not exceed any of the rated values specified within this chapter.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

Applying incorrect current or voltage levels on analog inputs and outputs could damage the electronic circuitry. Further, connecting a current input device to an analog input configure for voltage, and vice-versa, will likewise damage the electronic circuitry.

NOTICE

INOPERABLE EQUIPMENT

- Do not apply voltages above 11 Vdc to the analog inputs of the controller or Input/Output expansion module when analog input is configured as 0-10 V input.
- Do not apply current above 30 mA to the analog inputs of the controller or Input/Output expansion module when analog input is configured as 0-20 mA or 4-20 mA input.
- Do not mismatch applied signal with analog input configuration.

Failure to follow these instructions can result in equipment damage.

4.1. General specifications

4.1.1. FREE Evolution / EVE4200

The product complies with the following harmonized regulations:	EN 60730-2-9 / EN 60730-1
Construction of control	Electronic automatic Incorporated Control
Type of action	1.B relay output - 1.Y SSR output
Pollution degree	2
Over voltage category	II
Rated impulse voltage	2500 V
Power Supply	24 Vac, 50/60 Hz, or 24 Vdc, 48 Vdc Class 2 or SELV power source for all EVx7500 models 24 Vac, 50/60 Hz, or 24 Vdc Class 2 or SELV power source for EVE4200
Power Draw	22 VA / 18 W All EVx7500 models 16 VA / 7 W EVE4200
Digital outputs	EVE4200: SPST: DO2, DO3, DO4: 3 A resistive 240 Vac SPDT: DO1: 3 A resistive 240 Vac EVD7500/C/U / EVC7500/C/U / EVE7500: SPST: DO3, DO4, DO5, DO6: 3 A resistive 240 Vac SPDT: DO1, DO2: 8 A resistive 240 Vac NO/NC - 1/2 HP 240 Vac NO EVD7500/C/U/SSR: SPST: DO5, DO6: 3 A resistive 240 Vac SPDT: DO1, DO2: 8 A resistive 240 Vac SPDT: DO1, DO2: 8 A resistive 240 Vac NO/NC - 1/2 HP 240 Vac NO SSR: DO3, DO4: 0,75 A resistive 240 Vac
Software class	A
Ambient operating conditions	-10 55 °C (14 131 °F) All EVx7500 models -10 60 °C (14 140 °F) EVE4200 1090% RH (non condensante)
Transportation and storage conditions	-2085 °C (-4185 °F) 1090% RH (non-condensing)
Environmental front panel rating	Open Type

4.1.2. FREE Panel

The product complies with the following harmonized regulations:	EN 60730-2-9 / EN 60730-1
Construction of control	Electronic automatic Incorporated Control
Type of action	1
Pollution degree	2
Over voltage category	I
Rated impulse voltage	330 V
Power Supply ¹	24 Vac, 50/60 Hz, or 24 Vdc, 48 Vdc Class 2 or SELV power source
Power Draw	5 W
Software class	A
Ambient operating conditions	-10 55 °C (14 131 °F) 1090% RH (non condensante)
Transportation and storage conditions	-2085 °C (-4185 °F) 1090% RH (non-condensing)
Environmental front panel rating	Type 1 enclosure

¹ For **FREE Panel** / **EVK1000**: powered by **EVD** / **EVC** or directly from an independent, properly rated power supply. **NOTE:** When supplying power from the **FREE Evolution logic controllers**, make the power connection cable as short as possible.

NOTICE

INOPERABLE EQUIPMENT

Do not connect a power cable longer than 10m.

Failure to follow these instructions can result in equipment damage.

4.2. I/O Features

4.2.1. FREE Evolution I/O features

FREE Evolutionfeatures for inputs and outputs.

Type and Label	No.	Description	EVD7500/C/U EVD7500/C/U EVE7500	EVD7500/C/U/SSR
Digital input DI1DI8	8	8 opto-isolated digital inputs Working voltage +24 Vac/dc ±20% or +48 Vdc ±20% Power draw max. 5 mA Digital inputs can be used as pulse counters. The length of the pulse (positive or negative) must be greater than 12 ms. See CHAPTER 8 Physical I/O and ports configuration on page 87.	>	✓
Digital input FAST DI	1	1 no-voltage digital input (Pulse count + Read frequency) Note: measure a signal with a maximum frequency of 1 kHz See CHAPTER 8 Physical I/O and ports configuration on page 87.	√	✓
Relay digital outputs High voltage DO1, DO2	_	2 x 8 A resistive 240 Vac relays NO/NC - 1/2 HP 240 Vac NO	V	-
Relay digital outputs High voltage DO3DO7	7	5 x 5 A resistive 240 Vac relays	V	-
Relay digital outputs High voltage DO1, DO2	_	2 x 8 A resistive 240 Vac relays NO/NC - 1/2 HP 240 Vac NO	-	✓
Relay digital outputs High voltage DO5, DO6, DO7	5	3 x 5 A resistive 240 Vac relays	-	✓
SSR digital outputs High voltage DO3, DO4	2	2 x 0.75 A resistive 240 Vac SSR	-	J
Analog outputs AO1AO5	5	5 x 0-10 V / 420mA / ON-OFF configurable outputs: • 010V 2% full scale Min.load 500 Ω ; 1% full scale with load greater than 5 k Ω • 420mA 2% full scale max. 400 Ω • ON-OFF Max.load 400 Ω Note: AO4 and AO5 can be configured as Open Collector. See CHAPTER 8 Physical I/O and ports configuration on page 87.	V	✓
Analog inputs Al1 Al2 Al3 Al4 Al5 Al6	6	See the following table	V	✓

	NTC (NK103) 10 kΩ at 25 °C (77 °F) BETA value 3435	DI (1)	NTC (103AT-2) 10 kΩ at 25 °C (77 °F) BETA value 3435	4-20 mA	0-10 V
Al1	✓	✓	✓	-	-
Al2	✓	√	✓	-	-
AI3	✓	√	✓	\checkmark	✓
Al4	✓	✓	\checkmark	√	✓
AI5	✓	✓	\checkmark	√	✓
Al6	\checkmark	√	\checkmark	\checkmark	V
Range	-40+150 °C (-40+302 °F)	-	-50+110 °C (-58+230 °F)	01000	01000
Accuracy	0.5% full scale + 1 digit	-	0.5% full scale + 1 digit	1% full scale + 1 digit	1% full scale + 1 digit
Resolution	0.1°C	-	0.1 °C	1 digit	1 digit
Input impedance	10 kΩ	20 kΩ	10 kΩ	100 Ω	21 kΩ

⁽¹⁾ DI Digital Input: voltage free digital input.

	0-5 V Ratiometric (1)	Pt1000	hΩ (NTC)	daΩ (Pt1000)
Al1	-	-	-	-
Al2	-	-	-	-
Al3	V	J	J	V
Al4	V	J	J	✓
AI5	V	J	√	✓
Al6	V	J	J	J
Range	01000	-200+800 °C (-328+1472 °F)	0150 kΩ	030 kΩ
Accuracy	1% full scale + 1 digit	0.5% full scale + 1 digit	1% full scale + 1 digit	1% full scale + 1 digit
Resolution	1 digit	0.1 °C	1 hΩ	1 daΩ
Input impedance	21 kΩ	2 kΩ	10 kΩ	2 kΩ

(1) 0-5 V Ratiometric. 50 mA maximum current at 5 V $\,$

Also see 8.1.1. Analog inputs configuration for FREE Evolution on page 88 for instructions on offsets and calibrations.

4.2.2. EVE4200 I/O features

EVE4200 features for inputs and outputs.

Type and Label	No.	Description	EVE4200
Digital input DI1DI4	4	4 digital inputs NOT ISOLATED Working voltage 24 Vac/dc ±10% (Vac: max 38Vac) Power draw max. 5mA	V
Relay digital outputs High voltage DO1DO4	4	1 x 5A 250 Vac SPDT relay 3 x 3A 250 Vac SPST relays (common max 10A)	√
Analog outputs AO1AO2	2	2 x 0-10 V outputs: 4% full scale Min.load 5K Ω ; 2% full scale with load greater than 5K Ω	✓
Analog inputs Al1 Al2 Al3 Al4	4	See the following table	√

	NTC (NK103) 10 kΩ at 25 °C (77 °F) BETA value 3435	DI (1)	NTC (103AT-2) 10 kΩ at 25 °C (77 °F) BETA value 3435	4-20 mA	0-10 V
Al1	✓	\checkmark	\checkmark	✓	✓
Al2	J	J	J	J	J
AI3	\checkmark	\checkmark	\checkmark	\checkmark	J
Al4	J	\checkmark	J	V	J
Range	-40+137 °C (-40+278.6 °F)	-	-50°+110 °C (-58230 °F)	01000	01000
Accuracy	0.5% full scale + 1 digit		0.5% full scale + 1 digit	1% full scale + 1 digit	1% full scale + 1 digit
Resolution	0.1 °C	-	0.1 °C	1 digit	1 digit
Input impedance	10 kΩ	10 kΩ	10 kΩ	<200 Ω	>10 kΩ

(1) DI Input: voltage free digital input.

	0-5 V (1)	Pt1000	hΩ (NTC)	daΩ (Pt1000)	PTC (KTY81)
Al1	V	✓	\checkmark	✓	✓
Al2	J	J	J	J	✓
Al3	J	\checkmark	J	J	\checkmark
Al4	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Range	01000	-200+295 °C (-328+563 °F)	0150 kΩ	030 kΩ	-50°C+150 °C (-58+302 °F)
Acquirect	1% full scale	0.5% full scale	1% full scale	1% full scale	0.5% full scale
Accuracy	1 digit	+ 1 digit	1 digit	1 digit	+ 1 digit
Resolution	1 digit	0.1 °C	1 hΩ	1 daΩ	0.1 °C
Input impedance	>20 kΩ	2 kΩ	10 kΩ	2 kΩ	2 kΩ

⁽¹⁾ Ratiometric. 50 mA maximum current at 5 V

Also see 8.1.1. Analog inputs configuration for FREE Evolution on page 88 for instructions on offsets and calibrations.

4.2.3. FREE Panel I/O features

FREE Panel features for inputs.

Type and Label Analog inputs	Probe	Description	Resolution	Accuracy	Measurement range	Impedance	EVP3300/C	EVP3500/C/RH
Al1	On-board	NTC	0.1 °C / °F	0.5% full scale + 1 digit	-	10 kΩ	✓	✓
	Remote	NTC 103AT	0.1 °C / °F	0.5% full scale + 1 digit	-50+110 °C (-58230 °F)	10 kΩ		
Al2 configurable	NOT included	NTC NK103	0.1 °C / °F	0.5% full scale + 1 digit	-40+150 °C (-40302 °F)	10 kΩ	✓	✓
	morada	D.I.(1)	-	-	-	20 kΩ		
	Remote	420 mA	1 digit	1% full scale + 1 digit	01000	100 Ω	✓	-
AI3 configurable	NOT	0-5 V (2)	1 digit	1% full scale + 1 digit	01000	21 kΩ	-	-
	included	010 V	1 digit	1% full scale + 1 digit	01000	21 kΩ	-	-
Al4	On-board	On-board %RH input	0.01 %RH (0%=0pt, 100% = 1000pt)	±3% [2080%] ±5%elsewhere	0-100 %RH	-	-	J

⁽¹⁾ D.I. Digital Input voltage-free.

Also see 8.1.2. Analog inputs configuration for EVE4200 on page 89 for instructions on offsets and calibrations.

^{(2) 50} mA maximum current at 5 V.

4.3. Display

EVD7500/C/U(/SSR) references, remote display and FREE Panel:

- · backlit with LEDs
- 3 LEDs

LEDs and backlighting can be controlled from application.

4.3.1. EVK1000 / FREE Panel display

Display	Monochromatic LCD graphic display 128x64px backlit with LEDs		
Container	Backplate + frame in PC+ABS UL94 V-0 plastic resin, transparent polycarbonate front cover, polyester membrane keypad		

4.4. Serials

Serial	Description	Notes	References	
		max 50 m at 500 kpbs; 200 m at 125 kpbs.	EVD / EVC	
CAN	CAN Expansion Bus	If necessary, apply a 120 Ω termination resistor to both the ends.	EVE EVK1000	
RS 485	2 x RS 485 serial	If the controller is connected at the end of the RS 485 communication line, apply a 120 Ω termination resistor between line + and line - of the RS 485	EVD / EVC EVE7500	
		Only one RS 485 serial port can be configured as Modbus master at the same time.	EVE/500	
USB	1 Type A USB female connector (Host)	'Mass Storage' profile External memory, FAT32 formatting.	EVD / EVC	
ОЗБ	1 Type mini-B USB female connector (Device)	Connection between PC and device through USB standard CDC profile.	EVDTEVC	
ETHERNET	Modbus TCP ETHERNET port	Equipment includes MACADDRESS, in barcode and 12-digit alphanumeric format.	EVP	

Pay special attention when connecting serial lines. Miswiring may lead to inoperable equipment.

NOTICE

INOPERABLE EQUIPMENT

- Do not connect equipments that communicate using RS 485 serial to CAN Expansion Bus terminals.
- Do not connect equipments that communicate using CAN Expansion Bus to RS 485 terminals.

Failure to follow these instructions can result in equipment damage.

4.4.1. EVS Communication module

	Serial	Notes	Terminals
EVS RS232/R	RS232 Nullmodem	Digital outputs 1 x SPDT 5 A 250 Vac relay	terminals 13 screw type removable, spacing 5, 90° insertion for cables with 2.5 mm² cross-section. + DB9 connector
EVS CAN	Double serial port	Opto-isolated CAN serial	removable screw type , spacing 3.81, 90° insertion for cables with 2.5 mm² crosssection.
EVS RS485 EVS RS485 BACnet MS/TP	Double serial port	Opto-isolated RS485 serial	removable screw type , spacing 3.81, 90° insertion for cables with 2.5 mm² crosssection.
EVS ETH	Modbus TCP ETHERNET port	-	RJ45 connector
EVS ETH + RS485	Modbus TCP ETHERNET port Double serial port	Opto-isolated RS485 serial	RJ45 connector removable screw type , spacing 3.81, 90° insertion for cables with 2.5 mm² crosssection.
EVS LON	LON	-	-
EVS PROFIBUS	Profibus DP Slave-V0	-	-

4.5. Power supply

The **FREE Evolution logic controllers** and associated devices require power supplies with a nominal voltage of 24 Vac / 24 Vdc or 48 Vdc. The power supplies/transformers must be rated Safety Extra Low Voltage (SELV) according to IEC 61140. These sources of power are isolated between the electrical input and output circuits of the power supply as well as simple separation from ground (earth), PELV and other SELV systems.

A A DANGER

GROUND LOOP CAUSING ELECTRIC SHOCK AND/OR INOPERABLE EQUIPMENT

- Do not connect the 0 V power supply/transformer connection supplying this equipment to any external ground (earth) connection.
- Do not connect any 0 V or ground (earth) of the sensors and actuators connected to this equipment to any external ground connection.
- If necessary, use separate power supplies/transformers to power sensors or actuators isolated from this equipment.

Failure to follow these instructions will result in death or serious injury.

If the specified voltage range is not maintained, or the effective separation of the SELV circuit connected to the concerned equipment is compromised, the products may not function as intended or may become damaged and inoperable.

A WARNING

POTENTIAL OF OVERHEATING AND FIRE

- Do not connect the equipment directly to line voltage.
- · Use only isolating SELV power supplies/transformers to supply power to this equipment.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

The equipment must be connected to a suitable power supply/transformers with the following features:

Primary voltage	Depending on requirements of the individual device and/or country of installation.
Secondary voltage	+24 Vac/dc ±20% or +48 Vdc ±20%
Power supply frequency Vac	50/60 Hz
Power	minimum 18 W (FREE Evolution) minimum 5 W (FREE Panel)

4.6. Mechanical dimensions

	Length (L) mm in	Depth (d) mm in	Height (H) <u>mm</u> in	Notes
EVD / EVC / EVE7500	<u>140</u> 5.51	61.6 2.42	<u>110</u> 4.33	-
EVE4200	<u>70</u> 2.75	61.6 2.42	<u>87</u> 3.42	-
EVS Communication module	<u>35</u> 1.38	61.6 2.42	<u>110</u> 4.33	-
EVK1000 EVP	160 6.3	<u>10</u> 0.39	<u>96</u> 3.8	-
Opening for panel-mounting of EVK1000 or EVP	<u>138</u> 5.43	-	<u>68</u> 2.68	(+0.2mm / -0.1mm)

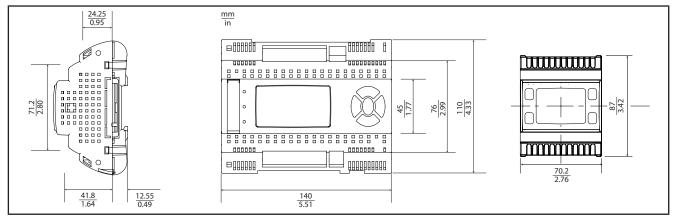


Fig. 53. EVD / EVC / EVE7500 / EVE4200

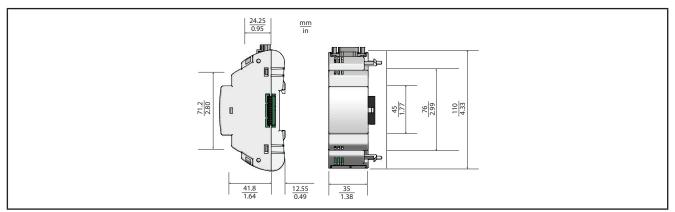


Fig. 54. EVS

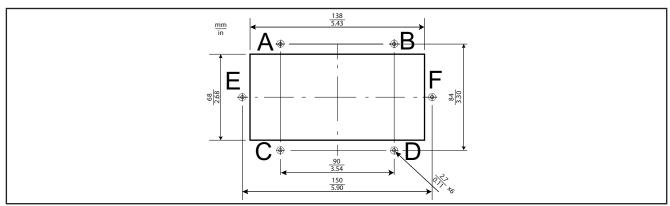


Fig. 55. Panel opening dimensions for EVK1000 or EVP

CHAPTER 5

FREE Evolution User Interface

The interface, comprising the front cover of the controller, allows you to perform operations to use the device.

5.1. Keys and LEDs

The data provided for keys refers to **EVD** references.

The EVC module has no display. Use the EVK1000 to work on this controller.

The **EVE** expansion module has no display.

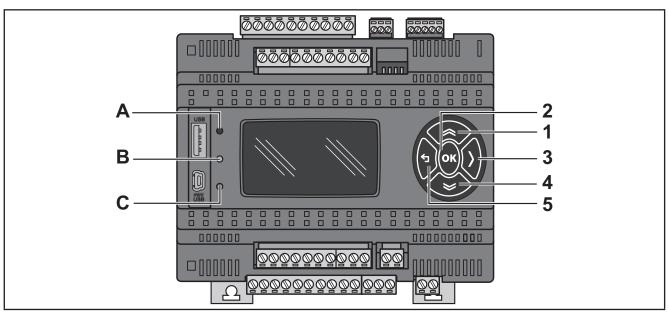


Fig. 56. EVD

The keys can be programmed from the controller application. By default, the device displays a short menu containing the following default settings.

No.	Key	Press once (press and release)
1	⇔ UP	Scroll upIncrease/modify a valueGo to next label
2	ОК	Scroll down Move to next level/menu (open folder, subfolder, parameter, value) Enter/exit Edit mode Confirm operation
3	RIGHT >	Move cursor to right in Edit Mode
4	DOWN ⇔	Scroll down Decrease/modify a value Go to previous label
5	← Exit	 Exit menu page / go back to previous menu Move cursor to left in Edit Mode (press and hold) Exit Edit Mode without saving

The LEDs can be programmed from the application.

By default, they are used for USB management - see the relative section on USB-Handling (see **3.1.6. Serial connections on page 27**).

LEDs	Description
ABC	A, B and C LEDs are programmable via controller application

5.2. First power on

When the equipment is powered on for the first time, a few summary pages are displayed showing system status (SYSTEM INFO).

SYSTEM INFO		
HW		
BIOS		
DATE		
BOOT		
EEPROM		

NOR FLASH	OK
NAND FLASH	OK
SDRAM	OK
BATRAM	OK
RTC	OK
Plug-in	None
USB-H	OK
USB-D	Service area

CHAPTER 6 EVK1000 user interface

The interface, comprising the front cover of the controller, allows you to perform operations to use the device.

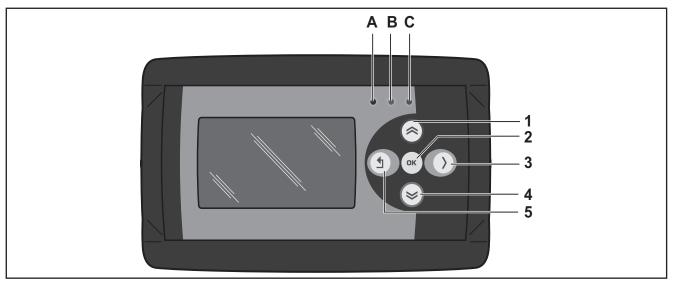


Fig. 57. EVK1000

6.1. Keys and LEDs

The keys can be programmed from the controller application. By default, the device displays a short menu containing the following default settings.

No.	Key	Press once (press and release)
	*	Scroll up
1		• Return to previous page (for example 1/3 ←2/3)
'	UP	Increase / modify a value
	OF .	Go to next label
		Scroll down
2	ок	Move to next level/menu (open folder, subfolder, parameter, value)
	J OK	Enter/exit Edit mode
		Confirm operation
3	RIGHT >	Move cursor to right in Edit Mode
		Scroll down
4	DOWN	Move to the next page (for example 1/3→2/3)
7		Decrease / modify a value
□ ₩		Go to previous label
		Exit menu page / go back to previous menu
5	← Exit	Move cursor to left in Edit Mode
		(press and hold) Exit Edit Mode without saving

DIAGNOSTICS Menu

EVK1000 is factory-configured with a default DIAGNOSTICS (DIA) menu that appears when the equipment is powered on. After uploading a controller application and/or a HMI menu from **FREE Studio**, the main display consists of the application menu created with **FREE Studio** Interface.

In which case, to open the DIAGNOSTICS menu proceed as follows:

No.	Key combination	Press and hold for about 3 seconds	
	DOWN		
4+5	← Exit	Open DIAGNOSTICS menu	

To return to the controller application menu, open the "HMI Management" page, select 11 and press the **OK** key. See **6.4. Remote interface on page 79**.

The LEDs can be programmed from the controller application.

LEDs	Description
ABC	A, B and C LEDs are programmable via controller application

6.2. First power on

When the equipment is powered on for the first time, a few summary pages are displayed showing system status (SYSTEM INFO).

SYSTEM INFO		
HW		
BIOS		
DATE		
BOOT		
EEPROM		

NOR FLASH	OK
SDRAM	OK

The system will also search for the controller application and the local menu... If present, the menu will appear on the display.

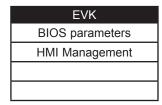
HMI searching	
DIA	

6.3. DIAGNOSTICS menu

The default DIAGNOSTICS menu of the **EVK1000** allows you to manage system parameters (BIOS parameters) and the interface (HMI).

The DIAGNOSTICS menu can be displayed in 5 languages: English, Italian, German, Spanish and French.

To change the default language, open BIOS Parameters > Display.



6.3.1. BIOS parameters

Parameter configuration menu. See CHAPTER 9 Parameters on page 102.

This menu is depopulated with respect to the parameters table contained in the corresponding chapter and in the **FREE Studio** device.

A language change example:

BIOS parameters \rightarrow < **OK** key > Display 1/3 \rightarrow < **OK** key > Edit Mode < **UP/DOWN** key > select language < **OK** key > < \leftarrow key >

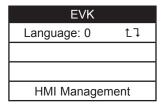


See parameter Display/Hmi_Language.

6.3.2. HMI Management

See 6.4. Remote interface on page 79.

6.4. Remote interface



6.4.1. Language

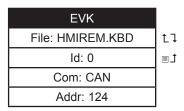
This section is for setting the language of the remote menu, defined from the **FREE Studio** User Interface. The number of languages and the order are established by the corresponding application/menu. See parameter HMI Management/**Hmi_Language** (see **CHAPTER 9 Parameters on page 102**).

6.4.2. L ↓

To return to the menu of the controller application, move the cursor onto the LI symbol and press the **OK** key.

6.4.3. HMI Management

This page shows the configuration of the remote page.

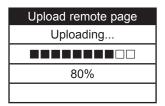


To "upload" a remote page use ■Ĵ

After selecting the desired menu move the cursor to LI to view the menu.

Upload remote page	
Upload page?	
The process cannot be interrupted	
Cancel OK	

Press **OK** to upload or any other key to cancel:



The upload may take up to a minute.

If there are no data to upload, the following screen displays:

Upload remote page
There are no remote
pages on the card.
Press OK

CHAPTER 7

FREE Panel user interface

The interface, comprising the front cover of the controller, allows you to perform operations to use the device.

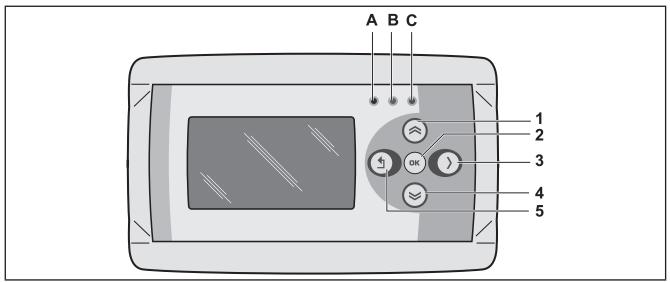


Fig. 58. FREE Panel

The keys can be programmed from the controller application. By default, the device displays a short menu containing the following default settings.

7.1. Keys and LEDs

No.	Key	Press once (press and release)	
	≈	Scroll up	
1		• Return to previous page (for example 2/10 ← 3/10)	
'	UP	Increase / modify a value	
	OP .	Go to the next label	
		Scroll down	
2	ок	Move to next level/menu (open folder, subfolder, parameter value)	
	OK	Enter/exit Edit mode	
		Confirm operation	
3	RIGHT >	Moves cursor to right in Edit Mode	
		Scroll down	
4	DOWN	Move to the next page (for example 1/10 → 2/10)	
4		Decrease / modify a value	
	>	Go to previous label	
		Exit menu page / go back to previous menu	
5	⊢ ← Exit	Move cursor to left in Edit Mode	
		(press and hold) Exit Edit Mode without saving any changes	

The **FREE Panel** is factory-configured with a default DIAGNOSTICS (DIA) menu that appears when the equipment is powered on.

After uploading of a controller application and/or a HMI menu from **FREE Studio**, the main display consists of the application menu created with **FREE Studio** Interface.

In which case, to open the DIAGNOSTICS menu proceed as follows:

Key combination		Press and hold for about 3 seconds
	DOWN	
4+5	←	Open DIAGNOSTICS menu
	Exit	

The LEDs can be programmed from the controller application.

LEDs	Description
ABC	A, B and C LEDs are programmable via controller application

To return to the controller application menu open the 'HMI Management' page (7.3.2. HMI management on page 83), select 11 and press the **OK** key.

See 7.4. Remote interface on page 85.

7.2. First power on

When the equipment is powered up for the first time, a few summary pages are displayed showing system status (SYSTEM INFO).

SYSTEM INFO
HW
BIOS
DATE
BOOT
EEPROM

NOR FLASH	OK
NAND FLASH	OK
SDRAM	OK
BATRAM	OK
RTC	OK

The system will also search for the controller application and the local menu... If present, the menu will appear on the display

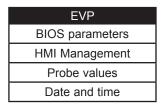
PLC searching	
HMI searching	
CON	loaded

7.3. DIAGNOSTIC menu

The DIAGNOSTICS menu of the **FREE Panel** is used to manage system parameters (BIOS parameters), remote interfaces (HMI) and to display I/O values and clock.

The DIAGNOSTICS menu can be displayed in 5 languages: English, Italian, German, Spanish and French.

To change the language, open BIOS Parameters > Display



7.3.1. BIOS parameters

For Parameter configuration menu, see CHAPTER 9 Parameters on page 102.

This menu is depopulated with respect to the parameters table contained in the corresponding chapter and in the **FREE Studio** device.

A language change example:

BIOS parameters \rightarrow < **OK** key > Display 1/3 \rightarrow < **OK** key > Edit Mode < **UP/DOWN** key > select language < **OK** key > < \leftarrow key >



See parameter Display/Hmi_Language.

7.3.2. HMI management

See 7.4. Remote interface on page 85.

7.3.3. Probe values

Shows input values (read only). **EVP** has 3 inputs. A **EVP3500/C/RH** example:

Probes values	1/3
Internal NTC	
27.3	
°C, °F	

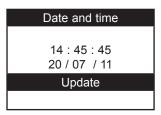
Probes values	2/3
External NT0	
°C, °F	

Probes values	3/3
Humidity sens	or
43.38	
RH%	

For offset programming see 8.1.2. Analog inputs configuration for EVE4200 on page 89.

7.3.4. Date and time

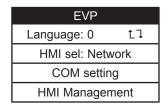
Shows time (HH: MM: SS) and date (DD / MM / YY) of the internal clock.



To edit the value press **OK**. Select the value that you want to modify. Press the **OK** key to enter Edit Mode. Use the **UP** and **DOWN** keys to modify value. Confirm with the **OK** key. Select 'Update' and press **OK** to update the clock.

Date and time
16 : 50 : 56 20 / 07 / 11
Update

7.4. Remote interface



7.4.1. Language

This section is for setting the language of the remote menu, defined from the **FREE Studio** User Interface. The number of languages and the order are established by the corresponding application/menu. See parameter HMI Management/**Hmi_Language**.

7.4.2. L↓

To return to the menu of the controller application, move the cursor onto the LI symbol and press the **OK** key. See **7.4.3. HMI sel on page 85**.

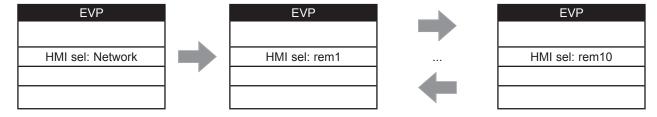
7.4.3. HMI sel

This section is for setting the menu to be shown on the display.

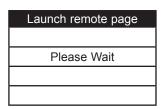
By default HMI menus are NOT present (only the DIAGNOSTICS menu is available).

Network: this is the FREE Panel 'local' menu (local HMI).

rem1...rem10: menus located on max 10 FREE Evolution devices connected to the network that can be 'uploaded' to FREE Panel.



To move from one page to the next press the $\bf UP$ and $\bf DOWN$ keys. After selecting the desired menu move the cursor onto $\bf L I$ to view the menu



If OK the display will show the selected menu (controller application). If the menu is not present, the following screen appears

Warning
Upload failed
Press OK

7.4.4. COM Setting

This **read-only** page shows the configuration of the **FREE Panel** serial ports.

FREE Panel
CAN: 1.500000
485s: 1.38400.P81
ETH: 010.000.000.100

7.4.5. HMI Management

This page shows the configuration of the 10 remote pages.

EVP	
1/10	
File: HMIREM.KBD	ĹŢ
ld: 0	Ĺ≣
Com: CAN	
Addr: 125	

EVP 1/10	
	ĹŢ
ld: 0	L ■
Com: CAN	
Addr: 000	

EVP	
10/10	
	ĹŢ
ld: 0	L ■
Com: CAN	
Addr: 000	

From these pages it is possible to 'launch' (run) the corresponding menu – if present Move the cursor onto 11 and press the **OK** key.

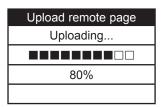
It will not be possible to launch the local (network) menu from this section. In the example only one remote page is present.

To 'upload' a remote page use ■1.

After selecting the desired menu move the cursor onto LI to view the menu.

Upload remote page								
Upload page?								
The process cannot be interrupted	_							
	_							
Cancel OK	_							

Press **OK** to upload or any other key to cancel



The upload may take up to a minute.

If there are no data to upload, the following screen displays

Warning
There are no remote
pages on the card
Press OK

CHAPTER 8

Physical I/O and ports configuration

From time to time, new input modules, output modules or other devices are made available that are not documented in the following information. For information on new devices, contact your local Eliwell representative.

NOTICE

INOPERABLE EQUIPMENT

Update the controller firmware to the latest version every time you install a newly released Input/Output expansion module or other device to this equipment.

Failure to follow these instructions can result in equipment damage.

NOTE: For more information on how to update the controller firmware, contact your local Eliwell representative.

	FREE Evolution	FREE Panel
Analog inputs	Configurable by parameter (see 8.1.1. Analog inputs configuration for FREE Evolution on page 88)	Configurable by parameter (see 8.1.2. Analog inputs configuration for EVE4200 on page 89)
Analog outputs	Configurable by parameter (see "8.2. Analog outputs configuration for FREE Evolution")	-
Digital inputs	Configurable by parameter (see 8.3. Digital inputs configuration for FREE Evolution on page 92)	-
Digital outputs	Configurable by parameter (see 8.4. Digital outputs configuration for FREE Evolution on page 92)	-
Serials	Configurable by parameter (see 9.1.1. EVD / EVC / EVE7500 parameters on page 104) or dip-switch (see on page 92)	Configurable by parameter (see 9.1.2. EVE4200 parameters on page 115)

Applying incorrect current or voltage levels on analog inputs and outputs could damage the electronic circuitry. Further, connecting a current input device to an analog input configure for voltage, and vice-versa, will likewise damage the electronic circuitry.

NOTICE

INOPERABLE EQUIPMENT

- Do not apply voltages above 11 Vdc to the analog inputs of the controller or Input/Output expansion module when analog input is configured as 0-10V input.
- Do not apply current above 30 mA to the analog inputs of the controller or Input/Output expansion module when analog input is configured as 0-20 mA or 4-20 mA input.
- Do not mismatch applied signal with analog input configuration.

Failure to follow these instructions can result in equipment damage.

8.1. Analog inputs

FREE Evolution and FREE Panel have analog inputs.

8.1.1. Analog inputs configuration for FREE Evolution

There are a total of 6 analog inputs, referred to below as Al1...Al6.

Using the parameters, a physical resource (probe, digital input, voltage/current signal) can be configured for each type of input:

- · 2 inputs can be configured as temperature probes (NTC type probe) or as digital inputs.
- 4 inputs (Al3...Al6) can be configured as temperature probes (NTC or Pt1000), as digital inputs or as a current/voltage input (4-20mA signal/ 0-10V, 0-5V ratiometric).

Inputs can be configured as specified in the table below.

						Value)			
Parameter Description		0	1	2	3	4	5	6	7	8
Cfg_Al1	Type of analog input Al1	NTC probe (NK103)	Probe configured as voltage-free digital input	NTC probe (103AT)	-	-	-	-	-	-
Cfg_Al2	Type of analog input Al2	NTC probe (NK103)	Probe configured as voltage-free digital input	NTC probe (103AT)	-	-	-	-	-	-
Cfg_Al3	Type of analog input AI3	NTC probe (NK103)	Probe configured as voltage-free digital input	NTC probe (103AT)	4-20 mA (1)	0-10 V (1)	0-5 V Ratiometric (1)	Pt1000	hΩ (NTC) (2)	daΩ (Pt1000) (3)
Cfg_Al4	Type of analog input Al4	NTC probe (NK103)	Probe configured as voltage-free digital input	NTC probe (103AT)	4-20 mA	0-10 V	0-5 V Ratiometric	Pt1000	hΩ (NTC)	daΩ (Pt1000)
Cfg_Al5	Type of analog input AI5	NTC probe (NK103)	Probe configured as voltage-free digital input	NTC probe (103AT)	4-20 mA	0-10 V	0-5 V Ratiometric	Pt1000	hΩ (NTC)	daΩ (Pt1000)
Cfg_Al6	Type of analog input Al6	NTC probe (NK103)	Probe configured as voltage-free digital input	NTC probe (103AT)	4-20 mA	0-10 V	0-5 V Ratiometric	Pt1000	hΩ (NTC)	daΩ (Pt1000)

(1) 4-20 mA / 0-10V / 0-5 V ratiometric

Minimum full scale Alx

- for current probe, value = 4 mA,
- for 0-10 V voltage probe, value = 0 V,
- for ratiometric probe (0÷5V), value = 10% (corresponding to 0.5 V)

Maximum full scale Alx

- for current probe, value = 20 mA,
- for 0-10V voltage probe, value = 10 V,
- for ratiometric probe (0÷5 V), value = 90% (corresponding to 4.5 V)
- (2) Cfg_Alx = 7 Resistance value read, expressed in $h\Omega$, for a resistance applied to the input using the controller in NTC configuration, i.e. creating a divider with pull-up resistance of 10 k Ω .
- (3) Cfg_Alx = 8 Resistance value read, expressed in da Ω , for a resistance applied to the input using the controller in Pt1000 configuration, i.e. creating a divider with pull-up resistance of 2 k Ω .

Note: Typically used with potentiometer at input.

The resistance range for the $h\Omega$ (NTC) configuration is up to 150 K, and up to 30 K for the $da\Omega$ (Pt1000) configuration.

Parameter	Range	Description
FullScaleMin_Al3	-9999+9999	Analog input Al3 start of scale value
FullScaleMax_Al3	-9999+9999	Analog input Al3 full scale value
FullScaleMin_Al4	-9999+9999	Analog input Al4 start of scale value
FullScaleMax_Al4	-9999+9999	Analog input Al4 full scale value
FullScaleMin_Al5	-9999+9999	Analog input Al5 start of scale value
FullScaleMax_Al5	-9999+9999	Analog input Al5 full scale value
FullScaleMin_Al6	-9999+9999	Analog input Al6 start of scale value
FullScaleMaxAl6	-9999+9999	Analog input Al6 full scale value

The values read by analog inputs can be configured via the following parameters:

Parameter	Description	Measurement Unit	Range
Calibration_Al1	Analog input Al1 differential	°C/10 or °F/10	-180 180
Calibration_Al2	Analog input AI2 differential	°C/10 or °F/10	-180 180
Calibration_Al3	Analog input Al3 differential	-	-1000 1000
Calibration_Al4	Analog input Al4 differential	-	-1000 1000
Calibration_Al5	Analog input AI5 differential	-	-1000 1000
Calibration_Al6	Analog input Al6 differential	-	-1000 1000

8.1.2. Analog inputs configuration for EVE4200

There are a total of 4 analog inputs, referred to below as Al1...Al4.

Using the parameters, a physical resource (probe, digital input, voltage/current signal) can be "physically" configured for each type of input

The inputs are configurable in pairs Al1, Al2 and Al3, Al4

Inputs can be "physically" configured as specified in the table below.

			Value									
Par	Description	0	1	2	3	4	5	6	7	8	9	10
Cfg_Alx	Type of	NTC	DI	NTC	4-20	0-10	0-5 V	Pt1000	hΩ	daΩ	PTC	0-5
	analog	probe	(1)	probe	mA	V	Ratiometric	1 11000	(NTC)	(Pt1000)	(KTY81)	🗸
x=14	input Alx	(NK103)	(1)	(103AT)	(2)	(2)	(2)		(3)	(4)	(101)	

(1) DI Input configured as voltage-free digital input

(2) 4-20 mA / 0-10 V / 0-5 V ratiometric

Minimum full scale Alx

- for current probe, value = 4 mA,
- for 0-10V voltage probe, value = 0 V,
- for ratiometric probe (0÷5 V), value = 10% (corresponding to 0.5 V)

Maximum full scale Alx

- for current probe, value = 20 mA,
- for 0-10 V voltage probe, value = 10 V, for ratiometric probe (0÷5V), value = 90% (corresponding to 4.5 V)
- (3) Cfg_Alx = 7 Resistance value read, expressed in $h\Omega$, for a resistance applied to the input using the controller in NTC configuration, i.e. creating a divider with pull-up resistance of 10 k Ω .
- (4) Cfg_Alx = 8 Resistance value read, expressed in $da\Omega$, for a resistance applied to the input using the controller in Pt1000 configuration, i.e. creating a divider with pull-up resistance of 2 k Ω .

Note: Typically used with potentiometer at input.

The resistance range for the $h\Omega$ (NTC) configuration is up to 150 K, and up to 30 K for the $da\Omega$ (Pt1000) configuration.

Allowed configurations for analog inputs

The pairs (Al1, Al2) and (Al3, Al4) shall be configured as specified in the table below.

Cells compiled show correct combinations. Empty cells indicate incorrect combinations. Applying incorrect configuration will produce 0x8003 error on probes range configuration

						(Cfg_Al1 / Cfg	_AI3				
		0	1	2	3	4	5	6	7	8	9	10
Cfg_Al2 / Cfg_Al4	0	NTC probe (NK103)	DI	NTC probe (103AT)	-	-	-	-	hΩ (NTC)	-	-	-
	1	NTC probe (NK103)	DI	NTC probe (103AT)	-	-	-	-	hΩ (NTC)	-	-	-
	2	NTC probe (NK103)	DI	NTC probe (103AT)	-	-	-	-	hΩ (NTC)	-	-	-
	3	-	-	-	4-20 mA	-	-	-	-	-	-	-
	4	-	-	-	-	0-10 V	-	-	-	-	-	-
	5	-	-	-	-	-	0-5 V Ratiometric	-	-	(Pt1000)	-	0-5 V
Cfg_,	6	-	-	-	-	-	-	Pt1000	-	daΩ (Pt1000)	-	-
	7	NTC probe (NK103)	DI	NTC probe (103AT)	-	-	-	-	hΩ (NTC)	-	PTC (KTY81)	-
	8	-	-	-	-	-	-	Pt1000	-	daΩ (Pt1000)	PTC (KTY81)	-
	9	-	-	-	-	-	-	Pt1000	-	daΩ (Pt1000)	PTC (KTY81)	-
	10	-	-	-	-	-	0-5 V Ratiometric	-	-	-	-	0-5 V

8.1.3. Analog inputs configuration for FREE Panel

Inputs can be configured as specified in the table below.

Parameter	Description	Values								
Parameter	Description	0	1	2	3	4	5			
Cfg_Al1	Type of input analog Al1	NTC probe (NK103)	Probe configured as voltage-free digital input	NTC probe (103AT-2)	-	-	-			
Cfg_Al2	Type of input analog Al2	NTC probe (NK103)	Probe configured as voltage-free digital input	NTC probe (103AT-2)	-	-	-			
Cfg_Al3	Type of input analog Al3	-	-	-	4-20 mA	0-10 V	0-5 V			

Parameter	Range	Description
FullScaleMin_Al3	-9999+9999	Analog input Al3 start of scale value
FullScaleMax_Al3	-9999+9999	Analog input Al3 full scale value

The temperature and humidity measurement, as well as the corresponding precisions and tolerances, refer to the application point of the probes inside the equipment.

If these same measurements are to be referred to air conditions outside of the equipment, for example ambient measurements, account must be taken of offset (differential) parameters that depend on the installation and usage conditions of the equipment itself. The differentials for example **Calibration** parameters that can be set are:

Parameter	Description	Unit of measure	Range
Calibration_Al1	Analog input Al1 differential	°C/10 or °F/10	-180 180
Calibration_Al2 Analog input Al2 differential		°C/10 or °F/10	-180 180
Calibration_Al3	Analog input Al3 differential	-	-1000 1000
Calibration_Al4	Analog input Al4 differential	-	-1000 1000

For on-board (built-in) sensors, **Compensation** parameters are also available

Parameter	Description	Unit of measure	Range
Compensation_Al1	Internal compensation Al1 difference between external air temperature and measurement read by NTC sensor Al1	°C/10 or °F/10	-1000 1000
Compensation_Al4	Internal compensation Al4 difference between external temperature and T measurement read by RH sensor Al4 (this temperature is used to calculate the relative humidity based on psychrometric charts)	°C/10 or °F/10	-1000 1000

Default values for these offsets assume a typical installation with wall mounted backplate in a non-ventilated environment and with the display backlighting mainly OFF. In these conditions the following calibration values are obtained:

Compensation_Al1 = -12.0 $^{\circ}$ C (10.4 $^{\circ}$ F) Compensation_Al4 = -10.5 $^{\circ}$ C (13.1 $^{\circ}$ F)

If the usage conditions require the backlight to be mainly ON, the values must be modified as follows:

Compensation_Al1 = -15.0 $^{\circ}$ C (5.0 $^{\circ}$ F) Compensation_Al4 = -13.0 $^{\circ}$ C (8.6 $^{\circ}$ F)

NOTE: For other mounting conditions carry out **calibration** during installation, checking the temperature and relative humidity differences between the external air and the internal probes and if necessary correcting the parameters **Compensation_Al1** / **Compensation_Al4**.

In any case it is possible to achieve a precision of \pm 1°C on the temperature measurement and \pm 3%RH on the relative humidity measurement.

8.2. Analog outputs configuration for FREE Evolution

See CHAPTER 3 Electrical connections on page 23 for the number and type of analog outputs used and for information on the symbols used on labels supplied with the controller.

There are 5 analog outputs with the following characteristics:

Configuration of analog output

AO1/AO5	AO2	AO3	A04
Current/voltage output AO1 and AO5 are configured in pairs.	Current/voltage output	Current/voltage output	Current/voltage output
Sub-mode configuration AO5 Only if AO1/AO5 have not been configured as voltage outputs (value ≠2)	-	-	-

Outputs AO1, AO2, AO3, AO4, AO5 are configurable as:

- 0 = 4-20mA current analog output
- 1 = output configured as 0...20mA switch (ON= max 20mA, OFF=0mA) for piloting switch loads such as ON/OFF.
- 2 = 0-10V voltage analog output.

Outputs AO4, AO5 can be configured as Open Collector output. Set:

- Cfg AO4 = 1 (ON/OFF type switching)
- Cfg AO1 AO5 = 0 or 1 (pair of outputs configured as current outputs)
- SubCfg_AO5 = 1 (ON/OFF type switching)
- Analog value piloted for both outputs = 0.

For developers using FREE Studio: see the sysAOasOC function (target block) in the FREE Studio Application Library

8.3. Digital inputs configuration for FREE Evolution

There are 8 digital inputs, identified below as DI1...DI8. They are grouped as:

- DI1...DI4
- DI5...DI8

Each one has its own common contact.

Digital inputs can be used as pulse counters.

The length of the pulse (positive or negative) must be greater than 12ms.

There is also a fast, voltage-free digital input that also works as a pulse counter:

- · It reads the number of times the contact applied to the input closes.
- · It reads frequencies from 0.1 Hz to 1 kHz.

8.4. Digital outputs configuration for FREE Evolution

See CHAPTER 3 Electrical connections on page 23 for the number and capacity of relays and/or SSR depending on the reference, and for information on the symbols used on labels supplied with the controller.

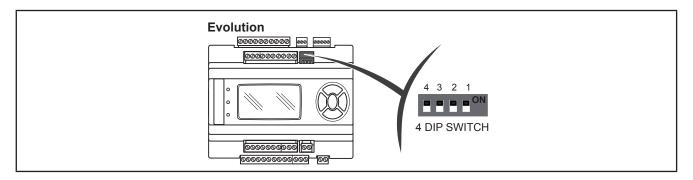
- There are 7 high voltage outputs (relays) identified as DO1...DO7.
- In references EVD7500/C/U/SSR there are 5 high voltage outputs (relays) identified as DO1...DO3, DO6, DO7 whereas there are 2 SSR outputs identified as DO3...DO4.

8.5. Ports configuration for FREE Evolution using DipSwitch

Dipswitches are used for the configuration of serial ports, which can be On-Board (**OB**) or available via Communication module **EVS** modules (**PI**).

4-position lateral DipSwitch

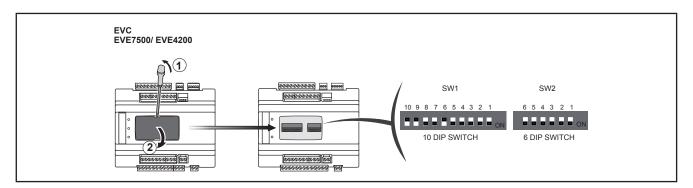
There is a 4-position lateral DipSwitch (microswitch) in all EVD, EVC and EVE expansion references.



6 and 10-position DipSwitch

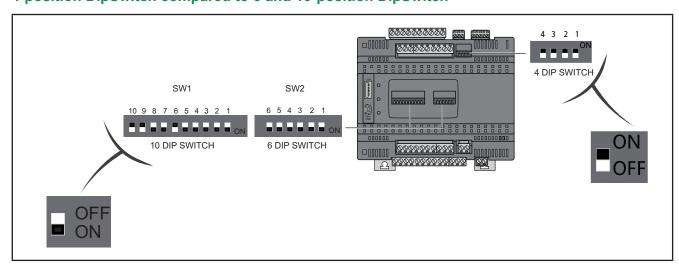
Under the front panel, EVC and EVE expansion references have:

- A 6-position DipSwitch (microswitch) (**SW2**)
- A 10-position DipSwitch (microswitch) (SW1)



Remove the front panel with a fingernail, or the tip of a slot head screwdriver. Configure as necessary then replace the front panel by pressing lightly back into place.

4-position DipSwitch compared to 6 and 10-position DipSwitch



NOTE. OFF=0 / ON=1

8.5.1. EVD DipSwitch

4-position lateral DipSwitch

Used for serial addressing only. The address is given by the sum of the value of a parameter (1) plus the value defined by the dipswitch (16 addresses).

		4-position dip			
Serial Addressing Default=0	Dip value	Dip4	3	2	1
4 3 2 1	0	0	0	0	0
	1	0	0	0	1
	2	0	0	1	0
	3	0	0	1	1
1.0\0/.0.11					
LOW Address	15	1	1	1	1

		Address	
Parameter (1)	Parameter (1) Default Parameter		LOW address Default=0
Addr_RS485_OB	1		4 3 2 1
Addr_CAN_OB	1		
Addr_RS485_PI	1		
Addr_CAN_PI	1	†	
Addr_RS232_PI	1		1.004/4.11
lp_4_ETH_PI	100		LOW Address

8.5.2. EVC DipSwitch

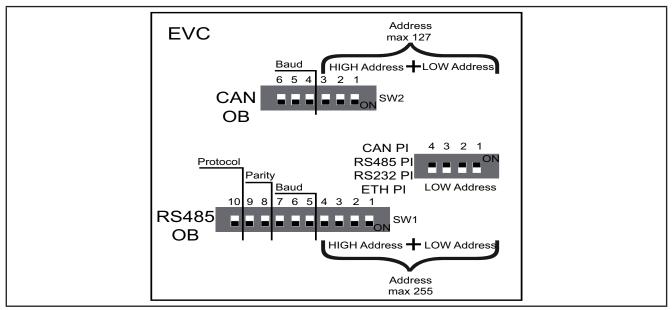


Fig. 59. EVC Dipswitch

Serial addressing

4-position DipSwitch

Used for the serial addressing of the Communication module port (PI) only.

In the serial addressing of On-Board (OB) serial ports, the 4-position dip is not used for EVC.

The address is given by the sum of the value of a parameter (1) plus the value defined by the dipswitch (16 addresses).

		4-position dip						
Serial Addressing Default=0	Dip value	Dip4	3	2	1			
4 3 2 1	0	0	0	0	0			
	1	0	0	0	1			
	2	0	0	1	0			
	3	0	0	1	1			
1 0 1 1 1								
LOW Address	15	1	1	1	1			

		Address	
Parameter (1)	Default Parameter		LOW address Default=0
Addr_RS485_PI	1		4 3 2 1
Addr_CAN_PI	1		ON
Addr_RS232_PI	1	+	
lp_4_ETH_PI	100		LOW Address

Baud

6-position EVC DipSwitch

The actual CAN Baud rate comprises the sum of parameter **Baud_CAN_OB** plus the composite value of the 3-position dip-switches (8 values).

CAN baud selection OB Default = 500 kbaud	Dip value	Dip6	5	4	3	2	1
Baud 6 5 4 3 2 1 CAN NSW2	0	0	0	0	-	-	-

Actual CAN Baud Value Default = 500 kbaud		Parameter Baud_CAN_OB		CAN baud selection Default = 0
2=500k				
3=250k]			Baud 6 5 4 3 2 1
4=125k	=	Parameter Baud_CAN_OB	+	CAN Sw2
5=125k]			ON
6=50k				
default example		2	+	0

CAN OB serial addressing

6-position dipswitch + 4-position dipswitch

The addressing comprises the sum of parameter **Addr_CAN_OB** plus the composite value of the 6 and 4-position dipswitches (127 addresses).

		6-position dip HIGH address					4-position dip LOW address				
CAN OB serial addressing Default = 1	Dip value	Dip6	5	4	3	2	1	Dip4	3	2	1
CAN Address	0	-	-	- 1	0	0	0	0	0	0	0
max 127	1	-	-	-	0	0	0	0	0	0	1
HIGH Address + LOW Address	2	-	-	-	0	0	0	0	0	1	0
6 5 4 3 2 1 4 3 2 1 ON	3	-	-	-	0	0	0	0	0	1	1
SW2 SW2											
LOW Address	126	-	-	-	1	1	1	1	1	1	0

	Address								
Parameter		HIGH+LOW address - Default = 0							
Addr_CAN_OB	+	HIGH Address 6 5 4 3 2 1 SW2 LOW Address LOW Address LOW Address							
1	+	0							

RS485 OB serial configuration

10-position dipswitch

		Dip value	Dip10	9	8	7	6	5	4	3	2	1
Protocol		0	0	-	-	-	-	-	-	-	-	-
selection RS485 OB Default = 1	RS485 OB 10 9 8 7 6 5 4 3 2 1 on SW1	1	1	-	1	-	-	-	-	-	-	-
Parity selec-	Parity	0	-	0	0	-	-	-	-	-	-	-
tion RS485 OB	RS485 10 9 8 7 6 5 4 3 2 1 SW1	1	- '	0	1	-	-	-	-	-	-	-
Default = EVEN	OB ON ON	2	-	1	0	-	-	-	ı	ı	-	-
		0	-	-	-	0	0	0	-	-	-	-
Baud selec-		1	-	-	-	0	0	1	-	-	-	-
tion RS485 OB	RS485 10 9 8 7 6 5 4 3 2 1	2	-	-	-	0	1	0	1	-	-	-
Default =	OB ON SW1	3	-	-	-	0	1	1	-	-	-	-
38400 baud		4	-	-	-	1	0	0	-	-	-	-
		5	-	-	-	1	0	1	-	-	-	-

Parameter	Default Parameter		LOW address Default = 0
	2=Reserved		Protocol RS485 10 9 8 7 6 5 4 3 2 1
Proto_RS485_OB	3= Modbus RTU	+	RS232 PI ON SW1
Parity_RS485_OB	0= NULL	+	Parity 10 9 8 7 6 5 4 3 2 1
	1= ODD	[RS485 OB OSW1
	2= EVEN		
	0=9600	Ī	
	1=19200]	
Baud_RS485_OB	2=38400		RS485 10 9 8 7 6 5 4 3 2 1
Bauu_K3405_OB	3=57600	Ī	OB on SW1
	4=76800]	
	5=115200		

RS485 OB serial addressing

10-position dipswitch + 4-position dipswitch

The address is given by the sum of the value of the two 6 and 4-position dipswitches (255 addresses).

					sition di addres			4-position dip LOW address					
	Serial addressing RS485 OB Default = 1	Dip value	Dip105	4	3	2	1	Dip4	3	2	1		
		0	-	0	0	0	0	0	0	0	0		
	10 9 8 7 6 5 4 3 2 1 4 3 2 1	1	- '	0	0	0	0	0	0	0	1		
RS485	SW1 - ON	2	-	0	0	0	0	0	0	1	0		
ОВ	HIGH Address +LOW Address	3	-	0	0	0	0	0	0	1	1		
	Address												
	max 254	254	-	1	1	1	1	1	1	1	0		

	Address								
Parameter		LOW address Default = 0							
Addr_RS485_OB	+	RS485 OB 10 9 8 7 6 5 4 3 2 1 HIGH Address + LOW Address Address max 254							
1	+	0							

NOTE: Any other combination of the dipswitches not listed here is not permitted.

To summarize, in the case of **EVC**, the default configuration for all dipswitches is as follows:

EVC DipSwitch default configuration

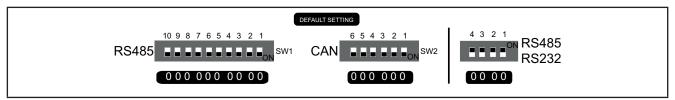


Fig. 60. Default setting

RS232 OB configuration and serial addressing

6 and **10**-position dipswitches are not used. See **CHAPTER 9** Parameters on page **102**.

8.5.3. EVE7500 expansion DipSwitch

EVE7500 expansion serials are configured by configuring dipswitches, without using the "internal" parameters visible in the **CHAPTER 9 Parameters on page 102**.

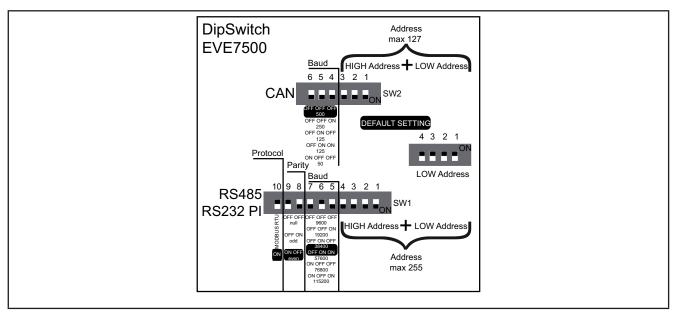


Fig. 61. Dipswitch EVE7500

Baud

6-position EVE7500 dipswitch

CAN baud selection OB and PI Default = 500 kbaud	kBaud	Dip value	Dip6	5	4	3	2	1
Baud	500	0	0	0	0	-	-	-
6 5 4 3 2 1	250	1	0	0	1	-	-	-
CAN III ON SW2	125	2	0	1	0	-	-	-
	125	3	0	1	1	-	-	-
	50	4	1	0	0	-	-	-

CAN OB and PI serial addressing

6-position dipswitch + 4-position EVE7500 dipswitch

The address is given by the value of the 6 and 4-position dipswitches (127 addresses).

			·							sition dip / address		
CAN serial addressing OB and PI Default = 1	Address	Dip value	Dip6	5	4	3	2	1	Dip4	3	2	1
CAN Address	1	0	-	-	-	0	0	0	0	0	0	0
max 127	2	1	-	-	- '	0	0	0	0	0	0	1
HIGH Address + LOW Address	3	2	-	-	-	0	0	0	0	0	1	0
6 5 4 3 2 1 4 3 2 1 ON	4	3	-	-	-	0	0	0	0	0	1	1
SW2 SW2												
LOW Address	127	126	-	-	-	1	1	1	1	1	1	0

RS232 PI and RS485 OB serial configuration

10-position dipswitch

		Protocol	Dip value	Dip10	9	8	7	6	5	4	3	2	1
Protocol selec-	RS485 10 9 8 7 6 5 4 3 2 1 sw1	Reserved for Eliwell use	0	0	ı	ı	-	-	1	ı	ı	-	-
RS485 OB Default = 1	RS232 PI ON SWI	ModBus RTU	1	1	-	1	-	-	ı	1	ı	-	-
Parity selection	Perity DC 405 10 9 8 7 6 5 4 3 2 1	Null	0	-	0	0	-	-	-	-	-	-	-
RS232 PI /	K3403	Odd	1	-	0	1	-	-	-	-	-	-	-
RS485 OB Default = EVEN	RS232 PI	Even Even	2	-	1	0	-	-	-	-	-	-	-
		9600	0	-	-	-	0	0	0	-	-	-	[-]
Baud selection	Baud	19200	1	-	1		0	0	1	-	1	-	-
RS232 PI / RS485 OB	RS485 10 9 8 7 6 5 4 3 2 1	38400	2	-	1	-	0	1	0	-	-	-	-
Default = 38400	RS232 PI ON SWI	57600	3	-	-	-	0	1	1	-	-	-	-
baud		76800	4	-	-	-	1	0	0	-	-	-	-
		115200	5	-	-	-	1	0	1	-	-	-	-

RS485 OB and PI serial addressing

10-position dipswitch + 4-position dipswitch

The address is given by the sum of the value of the two 6 and 4-position dipswitches (255 addresses).

				ositi iH ad						ion di ddres	
CAN serial addressing OB and PI Default = 1	Address	Dip value	Dip105	4	3	2	1	Dip4	3	2	1
D0405 10 9 8 7 6 5 4 3 2 1 4 3 2 1	1	0	-	0	0	0	0	0	0	0	0
RS485	2	1	-	0	0	0	0	0	0	0	1
RS232 PI	3	2	-	0	0	0	0	0	0	1	0
	4	3	-	0	0	0	0	0	0	1	1
Address max 255											
	255	254	-	1	1	1	1	1	1	1	0

NOTE: Any other combination of the dipswitches not listed here is not permitted.

To summarize, in the case of **EVE7500**, the default configuration for the dipswitches is as follows:

EVE7500 DipSwitch default configuration

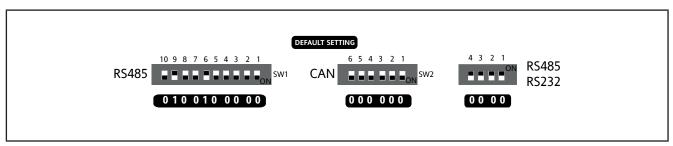


Fig. 62. Default setting

8.5.4. EVE4200 expansion DipSwitch

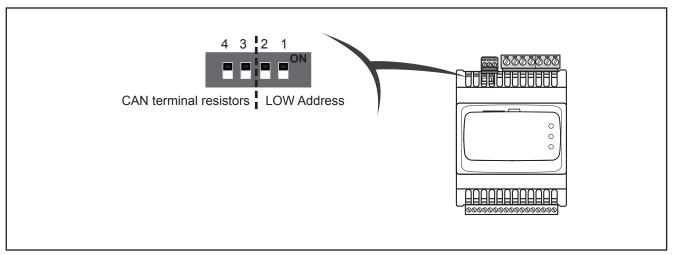


Fig. 63. 4-position lateral DipSwitch

Used for:

- serial addressing (dip 1 and 2)
- line termination (dip 3 and 4)

				4-positi	on dip	
Serial Addressing	Address = DipValue+1	Dip value	Dip4	3	2	1
	1	0	-	-	0	0
1	2	1	-	-	0	1
4 3 2 1	3	2	-	-	1	0
■ ■ ■ ON	4	3	-	-	1	1
CAN terminal LOW Address resistors	Dip value (Address)	Dip value (Address)	Dip4	3	2	1
	120 Ω termination	120 Ω termination	1	1	-	-

CAN OB serial addressing

The addressing comprises the sum of parameter **Addr_CAN_OB** plus the composite value of the 4-position dipswitches (only dip 1 and 2).

Actual CAN Adresss Default = 1		Parameter Addr_CAN_OB Default = 1		CAN address selection Default = 0
1				4 3 2 1
2				ON
	=	Parameter Baud_CAN_OB	+	
				CAN terminal LOW Address
127 max				resistors
default example		1	+	0

Baud

Baud rate is set by **Baud_CAN_OB** parameter

Line Termination resistors

Dip4 and Dip3 both = 1 connects L/H CAN lines to 120 Ω termination

CHAPTER 9

Parameters

User-parameterization renders the **FREE Evolution** configurable.

Parameters can be changed using:

- Keys on the EVD / EVP front panel or remote EVK1000 panel.
- PC and FREE Studio software.

The following sections provide a detailed analysis of each parameter, divided into categories (folders).

For **FREE Evolution**, the parameter table shows the configuration parameters for the controller saved in the non-volatile memory.

For **FREE Panel**, the parameter table contains the device configuration parameters available in **FREE Studio** Device and in the DIAGNOSTICS (DIA) / BIOS Parameters menu.

Modbus commands available and data areas

The following commands are implemented:

Modbus command	Description of command
3 (0x03)	Read multiple registers on Client side
6 (0x06)	Write single register on Client side
16 (0x10)	Write multiple registers on Client side
43 (0x2B)	Read device ID: • Manufacturer ID • Model ID • Version ID

NOTE

- Command 6 (0x06) not supported by EVE7500 expansion
- Command 15 (0x0F) 'Write multiple coils on Client side', supported only by EVE7500 expansion
- FREE Evolution / Panel logic controllers configured as Modbus Master support also commands 1, 2, 4 and 15 up to 16 registers.

9.1. FREE Evolution parameter table

This table presents the column headers of the parameter table that follows.

Column	Description
LABEL	Indicates the label used to display the parameters in the menu of the controller.
PAR. VALUE ADDRESS	Indicates the address of the modbus register containing the resource to be accessed.
DATA SIZE	Indicates the size of the data in bits.
CPL	Indicates the register value conversion. To carry out the conversion, proceed as follows: If the value in the register is between 0 and 32767, the result is the value itself (zero and positive values) If the value in the register is between 32768 and 65535, the result is the value of the register minus 65536
	 (negative values) When the field indicates "-1", the value read by the register requires conversion, because the value represents a number with a sign.
RESET	 Indicates whether the controller MUST be rebooted after the parameter has been modified. Y = YES the controller MUST be rebooted to modify the parameter. Empty " " = NO the controller does not need to be rebooted to modify the parameter
RANGE	Describes the interval of values that can be assigned to the parameter. It can be correlated with other equipment parameters (indicated in the parameter label).
DEFAULT	Indicates the factory setting for the reference.
U.M.	Indicates the unit of measurement for values converted according to the rules indicated in the CPL column. The unit of measurement shown is for example purposes only, as it may change depending on the application (for example parameters with a U.M. in °C/bar could also have %RH)

9.1.1. EVD / EVC / EVE7500 parameters

				1					
LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET	DESCRIPTION	RANGE	DEFAULT	U.M.	
ACKNOWLEDGEM	ENT fold	ler							
Par_TAB	15716	WORD	-	Υ	Map code Note: read/write parameter	0 65535	0	num	
Par_POLI	15717	WORD	-	Υ	Model Code Note: read/write parameter	0 65535	2049	num	
Par_PARMOD	15719	BOOL	-	-	Parameter modified Flag indicating change to default settings. • 0= map not modified. • 1= at least one parameter has been modified with respect to the original configuration.	0 1	0	num	
AI CALIBRATION folder									
Gain_Ntc_Al1	15616	WORD	-	-	Ai1 NTC calibration gain	0 65535	32768	num	
Gain_Ntc_Al2	15617	WORD	-	-	Ai2 NTC calibration gain	0 65535	32768	num	
Gain_Ntc_Al3	15618	WORD	-	-	Ai3 NTC calibration gain	0 65535	32768	num	
Gain_Pt1000_Al3	15619	WORD	-	-	Ai3 Pt1000 calibration gain	0 65535	32768	num	
Gain_5V_Al3	15620	WORD	-	-	Ai3 0-5V calibration gain	0 65535	32768	num	
Gain_10V_Al3	15621	WORD	-	-	Ai3 0-10V calibration gain	0 65535	32768	num	
Gain_mA_Al3	15622	WORD	-	-	Ai3 4-20mA calibration gain	0 65535	32768	num	
Gain_Ntc_Al4	15623	WORD	-	-	Ai4 NTC calibration gain	0 65535	32768	num	
Gain_Pt1000_AI4	15624	WORD	-	-	Ai4 Pt1000 calibration gain	0 65535	32768	num	
Gain_5V_AI4	15625	WORD	-	-	Ai4 0-5V calibration gain	0 65535	32768	num	
Gain_10V_Al4	15626	WORD	-	-	Ai4 0-10V calibration gain	0 65535	32768	num	
Gain_mA_Al4	15627	WORD	-	-	Ai4 4-20mA calibration gain	0 65535	32768	num	
Gain_Ntc_Al5	15628	WORD	-	-	Ai5 NTC calibration gain	0 65535	32768	num	
Gain_Pt1000_Al5	15629	WORD	-	-	Ai5 Pt1000 calibration gain	0 65535	32768	num	
Gain_5V_AI5	15630	WORD	-	-	Ai5 0-5V calibration gain	0 65535	32768	num	
Gain_10V_AI5	15631	WORD	-	-	Ai5 0-10V calibration gain	0 65535	32768	num	
Gain_mA_AI5	15632	WORD	-	-	Ai5 4-20mA calibration gain	0 65535	32768	num	
Gain_Ntc_Al6	15633	WORD	_	-	Ai6 NTC calibration gain	0 65535	32768	num	
Gain_Pt1000_Al6	15634	WORD	-	-	Ai6 Pt1000 calibration gain	0 65535	32768	num	
Gain_5V_Al6	15635	WORD	-	-	Ai6 0-5V calibration gain	0 65535	32768	num	
Gain_10V_Al6	15636	WORD	-	-	Ai6 0-10V calibration gain	0 65535	32768	num	
Gain_mA_Al6	15637	WORD	_	-	Ai6 0-10mA calibration gain	0 65535	32768	num	
Offs_Ntc_Al1	15650	WORD	-1	-	Ai1 NTC calibration offset	-32768 32767	0	num	
Offs_Ntc_Al2	15651	WORD	-1	-	Ai2 NTC calibration offset	-32768 32767	0	num	
Offs_Ntc_Al3	15652	WORD	-1	-	Ai3 NTC calibration offset	-32768 32767	0	num	
Offs_Pt1000_AI3	15653	WORD	-1	-	Ai3 Pt1000 calibration offset	-32768 32767	0	num	

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET	DESCRIPTION	RANGE	DEFAULT	U.M.
Offs_5V_AI3	15654	WORD	-1	-	Ai3 0-5V calibration offset	-32768 32767	0	num
Offs_10V_Al3	15655	WORD	-1	-	Ai3 0-10V calibration offset	-32768 32767	0	num
Offs_mA_Al3	15656	WORD	-1	-	Ai3 4-20mA calibration offset	-32768 32767	0	num
Offs_Ntc_Al4	15657	WORD	-1	-	Ai4 NTC calibration offset	-32768 32767	0	num
Offs_Pt1000_Al4	15658	WORD	-1	-	Ai4 Pt1000 calibration offset	-32768 32767	0	num
Offs_5V_AI4	15659	WORD	-1	-	Ai4 0-5V calibration offset	-32768 32767	0	num
Offs_10V_AI4	15660	WORD	-1	-	Ai4 0-10V calibration offset	-32768 32767	0	num
Offs_mA_Al4	15661	WORD	-1	-	Ai4 4-20mA calibration offset	-32768 32767	0	num
Offs_Ntc_Al5	15662	WORD	-1	-	Ai5 NTC calibration offset	-32768 32767	0	num
Offs_Pt1000_AI5	15663	WORD	-1	-	Ai5 Pt1000 calibration offset	-32768 32767	0	num
Offs_5V_AI5	15664	WORD	-1	-	Ai5 0-5V calibration offset	-32768 32767	0	num
Offs_10V_AI5	15665	WORD	-1	-	Ai5 0-10V calibration offset	-32768 32767	0	num
Offs_mA_AI5	15666	WORD	-1	-	Ai5 4-20mA calibration offset	-32768 32767	0	num
Offs_Ntc_Al6	15667	WORD	-1	-	Ai6 NTC calibration offset	-32768 32767	0	num
Offs_Pt1000_Al6	15668	WORD	-1	-	Ai6 Pt1000 calibration offset	-32768 32767	0	num
Offs_5V_Al6	15669	WORD	-1	-	Ai6 0-5V calibration offset	-32768 32767	0	num
Offs_10V_AI6	15670	WORD	-1	-	Ai6 0-10V calibration offset	-32768 32767	0	num
Offs_mA_Al6	15671	WORD	-1	-	Ai6 4-20mA calibration offset	-32768 32767	0	num
AO CALIBRATION	folder							
Gain_10V_AO1	15684	WORD	-	-	AO1 0-10V calibration gain	0 65535	32768	num
Gain_mA_AO1	15685	WORD	-	-	AO1 4-20mA calibration gain	0 65535	32768	num
Gain_10V_AO2	15686	WORD	-	-	AO2 0-10V calibration gain	0 65535	32768	num
Gain_mA_AO2	15687	WORD	-	-	AO2 4-20mA calibration gain	0 65535	32768	num
Gain_10V_AO3	15688	WORD	-	-	AO3 0-10V calibration gain	0 65535	32768	num
Gain_mA_AO3	15689	WORD	-	-	AO3 4-20mA calibration gain	0 65535	32768	num
Gain_10V_AO4	15690	WORD	-	-	AO4 0-10V calibration gain	0 65535	32768	num
Gain_mA_AO4	15691	WORD	-	-	AO4 4-20mA calibration gain	0 65535	32768	num
Gain_10V_AO5	15692	WORD	-	-	AO5 0-10V calibration gain	0 65535	32768	num
Gain_mA_AO5	15693	WORD	-	-	AO5 4-20mA calibration gain	0 65535	32768	num
Offs_10V_AO1	15700	WORD	-1	-	AO1 0-10V calibration offset	-32768 32767	0	num
Offs_mA_AO1	15701	WORD	-1	-	AO1 4-20mA calibration offset	-32768 32767	0	num
Offs_10V_AO2	15702	WORD	-1	-	AO2 0-10V calibration offset	-32768 32767	0	num
Offs_mA_AO2	15703	WORD	-1	-	AO2 4-20mA calibration offset	-32768 32767	0	num
Offs_10V_AO3	15704	WORD	-1	-	AO3 0-10V calibration offset	-32768 32767	0	num
Offs_mA_AO3	15705	WORD	-1	-	AO3 4-20mA calibration offset	-32768 32767	0	num
Offs_10V_AO4	15706	WORD	-1	-	AO4 0-10V calibration offset	-32768 32767	0	num

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET	DESCRIPTION	RANGE	DEFAULT	U.M.
Offs_mA_AO4	15707	WORD	-1	-	AO4 4-20mA calibration offset	-32768 32767	0	num
Offs_10V_AO5	15708	WORD	-1	-	AO5 0-10V calibration offset	-32768 32767	0	num
Offs_mA_AO5	15709	WORD	-1	-	AO5 4-20mA calibration offset	-32768 32767	0	num
ANALOG INPUTS	older	•						
Temp_UM	15725	WORD	-	Υ	Temperature unit of measurement • 0 = °C; • 1 = °F	0, 1	0	num
Cfg_Ai1	15726	WORD	-	-	Type of analog input Ai1 O= NTC (NK103) 1= DI 2= NTC (103AT)	0 2	2	num
Cfg_Ai2	15727	WORD	-	-	Type of analog input Ai2 See Cfg_Ai1	0 2	2	num
Cfg_Ai3	15728	WORD	-	-	Type of analog input Ai3 • 0= NTC (NK103) • 1= DI • 2= NTC (103AT) • 3 = 420mA • 4=0-10V • 5=0-5V • 6=Pt1000 • 7=hΩ(NTC) • 8=daΩ(Pt1000)	0 8	3	num
Cfg_Ai4	15729	WORD	-	-	Type of analog input Ai4 See Cfg_Ai3	0 8	3	num
Cfg_Ai5	15730	WORD	-	-	Type of analog input Ai5 See Cfg_Ai3	0 8	3	num

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET	DESCRIPTION	RANGE	DEFAULT	U.M.		
Cfg_Ai6	15731	WORD	-	-	Type of analog input Ai6 See Cfg_Ai3	0 8	3	num		
FullScaleMin_Ai3	15736	WORD	-1	-	Analog input Ai3 start of scale value Note: Minimum full scale: for current probes, value at 4mA, for 0-10V voltage probes, value at 0V, for ratiometric probes (0-5V), value at 10% (corresponding to 0.5V).	-9999+9999	0			
FullScaleMax_Ai3	15737	WORD	-	-	Analog input Ai3 full scale value Note: Maximum full scale for cur- rent probes, value at 20mA, for 0-10V voltage probes, value at 10V, for ratiometric probes (0-5V), value at 90% (corresponding to 4.5V).	-9999+9999	1000			
FullScaleMin_Ai4	15738	WORD	-1	-	Analog input Ai4 start of scale value See FullScaleMin_Ai3	-9999+9999	0			
FullScaleMax_Ai4	15739	WORD	-	-	Analog input Ai4 full scale value See FullScaleMAx_Ai3	-9999+9999	1000			
FullScaleMin_Ai5	15740	WORD	-1	-	Analog input Ai5 start of scale value See FullScaleMin_Ai3	-9999+9999	0			
FullScaleMax_Ai5	15741	WORD	-	-	Analog input Ai5 full scale value See FullScaleMax_Ai3	-9999+9999	1000			
FullScaleMin_Ai6	15742	WORD	-1	-	Analog input Ai6 start of scale value See FullScaleMin_Ai3	-9999+9999	0			
FullScaleMaxAi6	15743	WORD	-	-	Analog input Ai6 full scale value See FullScaleMax_Ai3	-9999+9999	1000			
Calibration_Ai1	15748	WORD	-1	-	Analog input Ai1 differential	-180 180	0	°C/10 or °F/10		
Calibration_Ai2	15749	WORD	-1	-	Analog input Ai2 differential	-180 180	0	°C/10 or °F/10		
Calibration_Ai3	15750	WORD	-1	-	Analog input Ai3 differential	-1000 1000	0			
Calibration_Ai4	15751	WORD	-1	-	Analog input Ai4 differential	-1000 1000	0			
Calibration_Ai5	15752	WORD	-1	-	Analog input Ai5 differential	-1000 1000	0			
Calibration_Ai6	15753	WORD	-1	-	Analog input Ai6 differential	-1000 1000	0			
ANALOG OUTPUTS V/I folder										

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET	DESCRIPTION	RANGE	DEFAULT	U.M.
Cfg_AO1_AO5	15758	WORD	-	Y	Type of analog output AO1/AO5 AO1 and AO5 are configured in pairs. See SubCfg_AO5 • 0 = 4-20mA current analog output • 1 = ON/OFF output configured as 0/420mA switch (ON=max 20mA, OFF=0mA) for piloting switch loads such as ON/OFF. • 2=0-10V analog output - voltage Note. AO4 and AO5 can be configured as Open Collector → A04=1, A01/A05=0 or 1, SubCfg_AO5=1	0 2	0	num
Cfg_AO2	15759	WORD	-	Υ	Type of analog output AO2 See Cfg_ AO1_AO5	0 2	0	num
Cfg_AO3	15760	WORD	-	Υ	Type of analog output AO3 See Cfg_ AO1_AO5	0 2	0	num
Cfg_AO4	15761	WORD	-	Υ	Type of analog output AO4	0 2	0	num
SubCfg_AO5	15762	WORD	-	Υ	Analog output AO5 sub-mode function Only applies if Cfg_AO1_AO5≠2 • 0 = 4-20mA current analog output • 1 = ON/OFF output configured as 0/420mA switch (ON=max 20mA, OFF=0mA) for piloting switch loads such as ON/OFF. Note. AO4 and AO5 can be configured as Open Collector → A04=1, A01/A05=0 or 1, SubCfg_AO5=1	0, 1	0	num

EVD / EVC parameters

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
ON BOARD RS485 fo	lder	1						
Addr_RS485_OB	15774	WORD	-	Υ	On-board RS485 serial address The actual address is determined by the sum of this value + the value of the dip switch.	0 255	1	num
Proto_RS485_OB	15775	WORD	-	Υ	On-board RS485 protocol selection • 2 = uNET • 3 = Modbus/RTU	2 3	3	num
Databit_RS485_OB	15776	WORD	-	Υ	On-board RS485 data bit number Fixed setting 8	8 8	8	num
Stopbit_RS485_OB	15777	WORD	-	Υ	On-board RS485 stop bit number 1= 1 stop bit 2= 2 stop bit	1 2	1	num
Parity_RS485_OB	15778	WORD	-	Υ	On-board RS485 protocol parity 0= NULL • 1= ODD • 2= EVEN	0 2	2	num
Baud_RS485_OB	15779	WORD	-	Υ	On-board RS485 protocol baudrate • 0=9600 baud • 1=19200 baud • 2=38400 baud • 3=57600 baud • 4=76800 baud • 5=115200 baud	0 5	2	num
ON BOARD CAN fold	er							
Addr_CAN_OB	15780	WORD	-	Υ	On-board CAN serial address The actual address is determined by the sum of this value + the value of the dip switch.	1 127	1	num
Baud_CAN_OB	15781	WORD	-	Υ	On-board CAN protocol baudrate • 2=500 kbaud • 3=250 kbaud • 4=125 kbaud • 5=125 kbaud • 6=50 kbaud	2 6	2	num
CAN PLUGIN PASSIV	E folder	,]
Addr_RS485_PI	15782	WORD	-	Υ	RS485 passive Communication module serial address The actual address is determined by the sum of this value + the value of the dip switch.	0 255	1	num

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
Proto_RS485_PI	15783	WORD	-	Υ	RS485 passive Communication modu- le protocol selection 2 = uNET 3 = Modbus/RTU	2 3	3	num
Databit_RS485_PI	15784	WORD	1	Υ	RS485 passive Communication module data bit number Fixed setting 8	8 8	8	num
Stopbit_RS485_PI	15785	WORD	1	Υ	RS485 passive Communication module stop bit number 1 = 1 stop bit 2 = 2 stop bit	1 2	1	num
Parity_RS485_PI	15786	WORD	1	Υ	RS485 passive Communication modu- le protocol parity 0= NULL 1= ODD 2= EVEN	0 2	2	num
Baud_RS485_PI	15787	WORD	-	Υ	RS485 passive Communication module protocol baudrate • 0=9600 baud • 1=19200 baud • 2=38400 baud • 3=57600 baud • 4=76800 baud • 5=115200 baud	0 5	2	num
Addr_CAN_PI	15788	WORD	-	Υ	CAN passive Communication module serial address The actual address is determined by the sum of this value + the value of the dip switch.	1 127	1	num
Baud_CAN_PI	15789	WORD	-	Y	CAN passive Communication module protocol baudrate • 2=500 kbaud • 3=250 kbaud • 4=125 kbaud • 5=125 kbaud • 6=50 kbaud	2 6	2	num
RS232 PASSIVE PLU	G-IN fold	der						
Addr_ RS232_PI	15790	WORD	-	Υ	RS232 passive Communication module serial address The actual address is determined by the sum of this value + the value of the dip switch.	0 255	1	num

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
Proto_ RS232_PI	15791	WORD	-	Υ	RS232 passive Communication module protocol selection 2 = uNET 3 = Modbus/RTU	2 3	3	num
Databit_ RS232_PI	15792	WORD	-	Υ	RS232 passive Communication module data bit number • 7= 7 bit • 8= 8 bit	7 8	8	num
Stopbit_ RS232_PI	15793	WORD	-	Υ	RS232 passive Communication module stop bit number 1 = 1 stop bit 2 = 2 stop bit	1 2	1	num
Parity_ RS232_PI	15784	WORD	-	Υ	RS232 passive Communication module protocol parity O= NULL 1= ODD 2= EVEN	0 2	2	num
Baud_RS232_PI	15795	WORD	-	Y	RS232 passive Communication module protocol baudrate • 0=9600 baud • 1=19200 baud • 2=38400 baud • 3=57600 baud • 4=76800 baud • 5=115200 baud	0 5	2	num

PASSIVE ETHERNET COMMUNICATION MODULE

ETHERNET configuration parameters for passive Communication module require configuration of the TCP/IP communication port (for example 502), the IP address, the gateway and the subnet mask

The 'Default Gateway' and 'Net mask' parameters are of no significance in the local point-to-point network.

For connections via a router the 'Default Gateway' parameters must match the IP address, as in the following example:

		Value			Value
lp_1_ETH_PI	Ethernet Passive Communication module IP address (part 1)	192	DefGtwy_1_ETH_PI	Default Gateway (part 1)	192
lp_2_ETH_PI	Ethernet Passive Communication module IP address (part 2)	168	DefGtwy_2_ETH_PI	Default Gateway (part 2)	168
lp_3_ETH_PI	Ethernet Passive Communication module IP address (part 3)	0	DefGtwy_3_ETH_PI	Default Gateway (part 3)	0
lp_4_ETH_PI	Ethernet Passive Communication module IP address (part 4)	100	DefGtwy_4_ETH_PI	Default Gateway (part 4)	1

The parameters necessary for the configuration of ports and protocols are these:

FREE WEB allows the use of HTTP and TFTP servers.

Parameter	Description	Label
HTTP ports	HTTP HyperText Transfer Protocol. An HTTP server generally monitors port 80 using TCP protocol.	Port_HTTP_PI
TFTP ports	TFTP Trivial File Transfer Protocol. Protocol using basic FTP functionalities. Typical use: transfer of small files between hosts on a network. TFTP USES PORT 69	Port_TFTP_PI
DHCP protocol	DHCP Dynamic Host Configuration Protocol	EnableDHCP_ETH_ PI
		PriDNS_1_ETH_PI
		PriDNS_2_ETH_PI
		PriDNS_3_ETH_PI
DNS system	DNS Domain Name System System for the conversion of host names, or network nodes, to IP addresses	PriDNS_4_ETH_PI
DIVO SYSTEM	Used by FREE Studio to send text e-mails (strings)	SecDNS_1_ETH_PI
		SecDNS_2_ETH_PI
		SecDNS_3_ETH_PI
		SecDNS_4_ETH_PI

LABEL	PAR VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
ETHERNET PASS	SIVE PLUG	G-IN folder						
Port_TFTP_PI	15772	WORD	-	Υ	TFTP port TFTP communication Port number Default 0 corresponds to port 69	0 65535	0	num
Port_HTTP_PI	15796	WORD	ı	Υ	HTTP port HTTP communication Port number Default 0 corresponds to port 80	0 65535	0	num
Port_ETH_PI	15797	WORD	-	Υ	Port TCP/IP Modbus communication port. Port 502 for example	0 65535	502	num
lp_1_ETH_PI	15798	WORD	ı	Υ	Ethernet passive Communication module IP address (part 1)	0 255	10	num
lp_2_ETH_PI	15799	WORD	ı	Υ	Ethernet passive Communication module IP address (part 2)	0 255	0	num
lp_3_ETH_PI	15800	WORD	-	Υ	Ethernet passive Communication module IP address (part 3)	0 255	0	num
lp_4_ETH_PI	15801	WORD	-	Υ	Ethernet passive Communication module IP address (part 4)	0 255	100	num
DefGtwy_1_ ETH_PI	15802	WORD	-	Υ	Default Gateway (part 1)	0 255	192	num
DefGtwy_2_ ETH_PI	15803	WORD	-	Υ	Default Gateway (part 2)	0 255	168	num
DefGtwy_3_ ETH_PI	15804	WORD	-	Υ	Default Gateway (part 3)	0 255	0	num
DefGtwy_4_ ETH_PI	15805	WORD	-	Υ	Default Gateway (part 4)	0 255	1	num
NetMsk_1_ ETH_PI	15806	WORD	-	Υ	Net mask (part 1)	0 255	255	num
NetMsk_2_ ETH_PI	15807	WORD	-	Υ	Net mask (part 2)	0 255	255	num
NetMsk_3_ ETH_PI	15808	WORD	-	Υ	Net mask (part 3)	0 255	255	num
NetMsk_4_ ETH_PI	15809	WORD	-	Υ	Net mask (part 4)	0 255	0	num
PriDNS_1_ ETH_PI	15810	WORD	-	Υ	Primary DNS server (part 1)	0 255	194	num
PriDNS_2_ ETH_PI	15811	WORD	-	Υ	Primary DNS server (part 2)	0 255	25	num
PriDNS_3_ ETH_PI	15812	WORD	-	Υ	Primary DNS server (part 3)	0 255	2	num

LABEL	PAR VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
PriDNS_4_ ETH_PI	15813	WORD	-	Υ	Primary DNS server (part 4)	0 255	129	num
SecDNS_1_ ETH_PI	15814	WORD	-	Υ	Secondary DNS server (part 1)	0 255	194	num
SecDNS_2_ ETH_PI	15815	WORD	1	Υ	Secondary DNS server (part 2)	0 255	25	num
SecDNS_3_ ETH_PI	15816	WORD	-	Υ	Secondary DNS server (part 3)	0 255	2	num
SecDNS_4_ ETH_PI	15817	WORD	-	Υ	Secondary DNS server (part 4)	0 255	130	num
EnableDHCP_ ETH_PI	15819	WORD	-	Υ	Enable DHCP	0 1 (False, True)	False	flag
Modems folder								
Modem_ RS232_PI	15820	BOOL	-	Υ	Presence of Modem	0 1	0	num
Modem_InitStr1	15821	19 BYTES	-	Υ	Modem initialization string (part I)	*****	(1)	string
Modem_InitStr2	15831	19 BYTES	-	Υ	Modem initialization string (part II)	*****		string
Modem_ Hangup	15851	19 BYTES	-	Υ	Hangup String	******	ATH0	string
Display folder								
Hmi_Language	15819	WORD	-	Υ	Display language	0 65535	0	num
Par_ContrLCD	15723	WORD	-	Υ	LCD Contrast Allows adjustment of the LCD display contrast.	0 64	30	num
Par_ BackLightTim e	15724	WORD	-	Υ	Backlight switch-on time Allows adjustment of LCD display switch-on time.	0 3600	10	num
(1) AT&F&C&D2E	0X1S0=0							

9.1.2. EVE4200 parameters

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
ACKNOWLEDGEM	ENT fold	ler						
Par_TAB	15716	WORD	-	Y	Map code Note: read/write parameter	0 65535	0	num
Par_POLI	15717	WORD	-	Υ	Model Code Note: read/write parameter	0 65535	2049	num
Par_PCH	15718	WORD	-	-	Model ID Code	0 65535	262	num
AI CALIBRATION fo	older							
Gain_Ntc_Al1	15616	WORD	-	_	Ai1 NTC calibration gain	0 65535	32768	num
Gain_Ntc_Al2	15617	WORD	-	-	Ai2 NTC calibration gain	0 65535	32768	num
Gain_Ntc_Al3	15618	WORD	-	-	Ai3 NTC calibration gain	0 65535	32768	num
Gain_Ntc_Al4	15619	WORD	-	-	Ai4 NTC calibration gain	0 65535	32768	num
Offs_Ntc_Al1	15621	WORD	-1	-	Ai1 NTC calibration offset	-32768 32767	0	num
Offs_Ntc_Al2	15622	WORD	-1	-	Ai2 NTC calibration offset	-32768 32767	0	num
Offs_Ntc_Al3	15623	WORD	-1	-	Ai3 NTC calibration offset	-32768 32767	0	num
Offs_Ntc_Al4	15624	WORD	-1	-	Ai4 NTC calibration offset	-32768 32767	0	num
Gain_PTC_Al1	15626	WORD	-	-	Ai1 PTC calibration gain	0 65535	32768	num
Gain_PTC_Al2	15627	WORD	-	-	Ai2 PTC calibration gain	0 65535	32768	num
Gain_PTC_Al3	15628	WORD	-	-	Ai3 PTC calibration gain	0 65535	32768	num
Gain_PTC_Al4	15629	WORD		-	Ai4 PTC calibration gain	0 65535	32768	num
Offs_PTC_AI1	15631	WORD	-1	-	Ai1 PTC calibration offset	-32768 32767	0	num
Offs_PTC_Al2	15632	WORD	-1	-	Ai2 PTC calibration offset	-32768 32767	0	num
Offs_PTC_Al3	15633	WORD	-1	-	Ai3 PTC calibration offset	-32768 32767	0	num
Offs_PTC_AI4	15634	WORD	-1	-	Ai4 PTC calibration offset	-32768 32767	0	num
Gain_daOhm_Al1	15636	WORD	-	-	Ai1 daOhm calibration gain	0 65535	32768	num
Gain_daOhm_Al2	15637	WORD	-	-	Ai2 daOhm calibration gain	0 65535	32768	num
Gain_daOhm_Al3	15638	WORD	-	-	Ai3 daOhm calibration gain	0 65535	32768	num
Gain_daOhm_Al4	15639	WORD	-	-	Ai4 daOhm calibration gain	0 65535	32768	num
Offs_daOhm_Al1	15641	WORD	-1	-	Ai1 daOhm calibration offset	-32768 32767	0	num
Offs_daOhm_Al2	15642	WORD	-1	-	Ai2 daOhm calibration offset	-32768 32767	0	num
Offs_daOhm_Al3	15643	WORD	-1	-	Ai3 daOhm calibration offset	-32768 32767	0	num
Offs_daOhm_Al4	15644	WORD	-1	-	Ai4 daOhm calibration offset	-32768 32767	0	num
Gain_mA_AI1	15646	WORD	-	-	Ai1 4-20mA calibration gain	0 65535	32768	num
Gain_mA_Al2	15647	WORD	-	-	Ai2 4-20mA calibration gain	0 65535	32768	num
Gain_mA_Al3	15648	WORD	-	-	Ai3 4-20mA calibration gain	0 65535	32768	num

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
Gain_mA_Al4	15649	WORD	-	-	Ai4 4-20mA calibration gain	0 65535	32768	num
Offs_mA_AI1	15651	WORD	-1	-	Ai1 4-20mA calibration offset	-32768 32767	0	num
Offs_mA_Al2	15652	WORD	-1	-	Ai2 4-20mA calibration offset	-32768 32767	0	num
Offs_mA_Al3	15653	WORD	-1	-	Ai3 4-20mA calibration offset	-32768 32767	0	num
Offs_mA_Al4	15654	WORD	-1	-	Ai4 4-20mA calibration offset	-32768 32767	0	num
Gain_5V_Ratio_ Al1	15656	WORD	-	-	Ai1 5V Ratiometric calibration gain	0 65535	32768	num
Gain_5V_Ratio_ Al2	15657	WORD	-	-	Ai2 5V Ratiometric calibration gain	0 65535	32768	num
Gain_5V_Ratio_ Al3	15658	WORD	-	-	Ai3 5V Ratiometric calibration gain	0 65535	32768	num
Gain_5V_Ratio_ Al4	15659	WORD	-	-	Ai4 5V Ratiometric calibration gain	0 65535	32768	num
Offs_5V_Ratio_ Al1	15661	WORD	-1	-	Ai1 5V Ratiometric calibration offset	-32768 32767	0	num
Offs_5V_Ratio_ Al2	15662	WORD	-1	-	Ai2 5V Ratiometric calibration offset	-32768 32767	0	num
Offs_5V_Ratio_ Al3	15663	WORD	-1	-	Ai3 5V Ratiometric calibration offset	-32768 32767	0	num
Offs_5V_Ratio_ Al4	15664	WORD	-1	-	Ai4 5V Ratiometric calibration offset	-32768 32767	0	num
Gain_10V_Al1	15666	WORD	-	-	Ai1 0-10V calibration gain	0 65535	32768	num
Gain_10V_Al2	15667	WORD	-	-	Ai2 0-10V calibration gain	0 65535	32768	num
Gain_10V_Al3	15668	WORD	-	-	Ai3 0-10V calibration gain	0 65535	32768	num
Gain_10V_AI4	15669	WORD	-	-	Ai4 0-10V calibration gain	0 65535	32768	num
Offs_10V_AI1	15671	WORD	-1	-	Ai1 0-10V calibration offset	-32768 32767	0	num
Offs_10V_AI2	15672	WORD	-1	-	Ai2 0-10V calibration offset	-32768 32767	0	num
Offs_10V_AI3	15673	WORD	-1	-	Ai3 0-10V calibration offset	-32768 32767	0	num
Offs_10V_AI4	15674	WORD	-1	-	Ai4 0-10V calibration offset	-32768 32767	0	num
Gain_5V_AI1	15676	WORD	-		Ai1 0-5V calibration gain	0 65535	32768	num
Gain_5V_Al2	15677	WORD	-	-	Ai2 0-5V calibration gain	0 65535	32768	num
Gain_5V_Al3	15678	WORD	_	-	Ai3 0-5V calibration gain	0 65535	32768	num
Gain_5V_Al4	15679	WORD	-	-	Ai4 0-5V calibration gain	0 65535	32768	num
Offs_5V_AI1	15681	WORD	-1	-	Ai1 0-5V calibration offset	-32768 32767	0	num
Offs_5V_AI2	15682	WORD	-1	-	Ai2 0-5V calibration offset	-32768 32767	0	num
Offs_5V_AI3	15683	WORD	-1	-	Ai3 0-5V calibration offset	-32768 32767	0	num
Offs_5V_AI4	15684	WORD	-1	-	Ai4 0-5V calibration offset	-32768 32767	0	num
Gain_Pt1000_Al1	15686	WORD	-	-	Ai1 Pt1000 calibration gain	0 65535	32768	num
Gain_Pt1000_Al2	15687	WORD	-	-	Ai2 Pt1000 calibration gain	0 65535	32768	num
Gain_Pt1000_Al3	15688	WORD	-	-	Ai3 Pt1000 calibration gain	0 65535	32768	num
Gain_Pt1000_Al4	15689	WORD	-	-	Ai4 Pt1000 calibration gain	0 65535	32768	num
Offs_Pt1000_AI1	15691	WORD	-1	-	Ai1 Pt1000 calibration offset	-32768 32767	0	num

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
Offs_Pt1000_Al2	15692	WORD	-1	-	Ai2 Pt1000 calibration offset	-32768 32767	0	num
Offs_Pt1000_Al3	15693	WORD	-1	-	Ai3 Pt1000 calibration offset	-32768 32767	0	num
Offs_Pt1000_AI4	15694	WORD	-1		Ai4 Pt1000 calibration offset	-32768 32767	0	num
AO CALIBRATION	folder							
Gain_10V_AO1	15696	WORD	-	-	AO1 0-10V calibration gain	0 65535	32768	num
Gain_10V_AO2	15697	WORD	-	-	AO2 0-10V calibration gain	0 65535	32768	num
Offs_10V_AO1	15698	WORD	-1	-	AO1 0-10V calibration offset	-32768 32767	0	num
Offs_10V_AO2	15699	WORD	-1	-	AO2 0-10V calibration offset	-32768 32767	0	num
ANALOG INPUTS 1	folder							
Temp_UM	15725	WORD	-	Υ	Temperature unit of measurement • 0 = °C; • 1 = °F	0, 1	0	num
Cfg_Ai1	15726	WORD	-	-	Type of analog input Ai1 0 = NTC (NK103) 1 = DI 2 = NTC (103AT) 3 = 420mA 4 = 0-10V 5 = 0-5V Ratiometric 6 = Pt1000 7 = $h\Omega$ (NTC) 8 = $da\Omega$ (Pt1000) PTC 10 = 0-5V	0 10	3	num
Cfg_Ai2	15727	WORD	-	-	Type of analog input Ai2 See Cfg_Ai1	0 10	3	num
Cfg_Ai3	15728	WORD	-	-	Type of analog input Ai3 See Cfg_Ai1	0 10	2	num
Cfg_Ai4	15729	WORD	-	-	Type of analog input Ai4 See Cfg_Ai1	0 10	2	num
FullScaleMin_Ai1	15736	WORD	-1	-	Analog input Ai1 start of scale value	-9999+9999	0	
FullScaleMax_Ai1	15737	WORD	-	-	Analog input Ai1 full scale value	-9999+9999	1000	
FullScaleMin_Ai2	15738	WORD	-1	-	Analog input Ai2 start of scale value See FullScaleMin_Ai1	-9999+9999	0	

LABEL	PAR. VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
FullScaleMax_A2	15739	WORD	-	-	Analog input Ai2 full scale value See FullScaleMAx_Ai1	-999+999	1000	
FullScaleMin_Ai3	15740	WORD	-1	-	Analog input Ai3 start of scale value See FullScaleMin_Ai1	-9999+9999	0	
FullScaleMax_Ai3	15741	WORD	-	-	Analog input Ai3 full scale value See FullScaleMax_Ai1	-999+999	1000	
FullScaleMin_Ai4	15742	WORD	-1	-	Analog input Ai4 start of scale value See FullScaleMin_Ai1	-9999+9999	0	
FullScaleMaxAi4	15743	WORD	-	-	Analog input Ai4 full scale value See FullScaleMax_Ai1	-999+999	100	
Calibration_Ai1	15748	WORD	-1	-	Analog input Ai1 differential	-180 180	0	°C/10 or °F/10
Calibration_Ai2	15749	WORD	-1	-	Analog input Ai2 differential	-180 180	0	°C/10 or °F/10
Calibration_Ai3	15750	WORD	-1	-	Analog input Ai3 differential	-1000 1000	0	
Calibration_Ai4	15751	WORD	-1	-	Analog input Ai4 differential	-1000 1000	0	
SubCfg_Al1	16010	WORD	-	Y	 Analog input Al5 sub-mode function 0 = Low Pass Filter disabled, analog value in raw points 1 = Low Pass Filter disabled, analog value converted 2 = Low Pass Filter enabled, analog value in raw points 1 = Low Pass Filter enabled, analog value converted 	0 3	3	num
SubCfg_Al2	16011	WORD	-	Υ	See SubCfg_Al1	0 3	3	num
SubCfg_Al3	16012	WORD	-	Υ	See SubCfg_Al1	0 3	3	num
SubCfg_Al4	16013	WORD	-	Υ	See SubCfg_Al1	0 3	3	num

9.1.3. EVP parameters

LABEL	PAR VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
ACKNOWLEDGE	MENT fo	lder						
Par_TAB	15716	WORD	-	Υ	Map code Note: read/write parameter	0 65535	0	num
Par_POLI	15717	WORD	-	Υ	Model Code Note: read/write parameter	0 65535	2049	num
Par_PARMOD	15719	BOOL	-	-	Parameter changed Flag indicating change to default settings. • 0= map not modified. • 1= at least one parameter has been changed from the original configuration.	0 1	0	num
AI CALIBRATION	l folder							
Gain_Ntc_Al1	15616	WORD	-	-	Ai1 NTC calibration gain	0 65535	32768	num
Gain_Ntc_Al2	15617	WORD	-	-	Ai2 NTC calibration gain	0 65535	32768	num
Gain_5V_Al3	15620	WORD	-	_	Ai3 0-5V calibration gain	0 65535	32768	num
Gain_10V_AI3	15621	WORD	-	-	Ai3 0-10V calibration gain	0 65535	32768	num
Gain_mA_Al3	15622	WORD	-	-	Ai3 4-20mA calibration gain	0 65535	32768	num
Offs_Ntc_Al1	15650	WORD	-1	-	Ai1 NTC calibration offset	-32768 32767	0	num
Offs_Ntc_Al2	15651	WORD	-1	-	Ai2 NTC calibration offset	-32768 32767	0	num
Offs_5V_AI3	15654	WORD	-1	-	Ai3 0-5V calibration offset	-32768 32767	0	num
Offs_10V_Al3	15655	WORD	-1	-	Ai3 0-10V calibration offset	-32768 32767	0	num
Offs_mA_Al3	15656	WORD	-1	-	Ai3 4-20mA calibration offset	-32768 32767	0	num
ANALOG INPUTS	S folder						1	
Temp_UM	15725	WORD	-	Y	Temperature unit of measure • 0 = °C; • 1 = °F	0, 1	0	num
Cfg_Al1	15726	WORD	-	-	Type of analog input Ai1 O= NTC (NK103) 1= DI 2= NTC (103AT)	0 2	2	num
Cfg_Ai2	15727	WORD	-	-	Type of analog input Ai2 See Cfg_Ai1	0 2	2	num

LABEL	PAR VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
Cfg_Ai3	15728	WORD	-	-	Type of analog input Ai3 • 3 = 420mA • 4=0-10V • 5=0-5V	3 5	3	num
Cfg_Ai4	15729	WORD	-	-	Type of analog input Ai4 See Cfg_Ai3	3 5	3	num
FullScaleMin_ Ai3	15736	WORD	-1	-	Analog input Ai3 start of scale value N.B.: Minimum full scale: for current probes, value at 4mA, for 0-10V voltage probes, value at 0V, 10% for (0-5V) probes, value at 10% (corresponding to 0.5V).	-9999+9999	0	
FullScaleMAx_ Ai3	15737	WORD	-1	-	Analog input Ai3 full scale value N.B.: Maximum full scale for current probes, value at 20mA, for 0-10V voltage probes, value at 10V, for (0-5V) probes, value at 90% (corresponding to 4.5V).	-9999+9999	1000	
Calibration_Ai1	15748	WORD	-1	-	Analog input Ai1 differential	-180 180	0	°C/10 or °F/10
Calibration_Ai2	15749	WORD	-1	-	Analog input Ai2 differential	-180 180	0	°C/10 or °F/10
Calibration_Ai3	15750	WORD	-1	-	Analog input Ai3 differential	-1000 1000	0	
Calibration_Ai4	15751	WORD	-1	-	Analog input Ai4 differential	-1000 1000	0	
Compensation_ Al1	15752	WORD	-1	-	Internal compensation Al1	-1000 1000 °C/10	0	°C/10
Compensation_ Al4	15753	WORD	-1	-	Internal compensation Al4	-1000 1000 °C/10	0	°C/10
RS485 ON BOAR	D folder							
Addr_RS485_ OB	15774	WORD	-	Y	On-board RS485 serial address The actual address is determined by the sum of this value + the value of the dip switch.	0 255	1	num
Proto_RS485_ OB	15775	WORD	-	Υ	On-board RS485 protocol selection • 2 = uNET • 3 = Modbus/RTU	2 3	2	num
Databit_ RS485_OB	15776	WORD	_	Υ	On-board RS485 data bit number Fixed setting 8	8 8	8	num
Stopbit_ RS485_OB	15777	WORD	-	Υ	On-board RS485 stop bit number 1 = 1 stop bit 2 = 2 stop bits	1 2	1	num

LABEL	PAR VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
Parity_RS485_ OB	15778	WORD	-	Υ	On-board RS485 protocol parity O= NULL 1= ODD 2= EVEN	0 2	2	num
Baud_RS485_ OB	15779	WORD	-	Y	On-board RS485 protocol baudrate • 0=9600 baud • 1=19200 baud • 2=38400 baud • 3=57600 baud • 4=76800 baud • 5=115200 baud	0 5	2	num
	Toluel				On-board CAN serial address			
Addr_CAN_OB	15780	WORD	-	Y	The actual address is determined by the sum of this value + the value of the dip switch.	1 127	1	num
Baud_CAN_OB	15781	WORD	-	Υ	On-board CAN protocol baudrate 2=500 kbaud 3=250 kbaud 4=125 kbaud 5=125 kbaud 6=50 kbaud	2 6	2	num

ON BOARD ETHERNET

The parameters necessary for the configuration of ports and protocols are these:

FREE WEB allows the use of HTTP and TFTP servers.

Parameter	Description	Label
HTTP ports	HTTP HyperText Transfer Protocol. An HTTP server generally monitors port 80 using TCP protocol.	Port_HTTP
TFTP ports	TFTP Trivial File Transfer Protocol. Protocol using basic FTP functionalities. Typical use: transfer of small files between hosts on a network. TFTP USES PORT 69	Port_TFTP
DHCP protocol	DHCP Dynamic Host Configuration Protocol	EnableDHCP_ ETH

Parameter	Description	Label
DNS system		PriDNS_1_ETH
		PriDNS_2_ETH
		PriDNS_3_ETH
	DNS Domain Name System System for the conversion of host names, or network nodes, to IP addresses	PriDNS_4_ETH
DING System	Used by FREE Studio to send text e-mails (strings)	SecDNS_1_ETH
		SecDNS_2_ETH
		SecDNS_3_ETH
		SecDNS_4_ETH

LABEL	PAR VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
ETHERNET ON BO	ARD fold	er						
Port_TFTP	15772	WORD	-	Υ	TFTP port TFTP communication Port number Default 0 corresponds to port 69	0 65535	0	num
Port_HTTP	15796	WORD	-	Y	HTTP port HTTP communication Port number Default 0 corresponds to port 80	0 65535	0	num
Port_ETH	15797	WORD	-	Υ	Port TCP/IP Modbus communication port. Port 502 for example	0 65535	502	num
lp_1_ETH	15798	WORD	-	Υ	On-board Ethernet passive IP address (part 1)	0 255	10	num
lp_2_ETH	15799	WORD	-	Υ	On-board Ethernet passive IP address (part 2)	0 255	0	num
lp_3_ETH	15800	WORD	-	Υ	On-board Ethernet passive IP address (part 3)	0 255	0	num
lp_4_ETH	15801	WORD	-	Υ	On-board Ethernet passive IP address (part 4)	0 255	100	num
DefGtwy_1_ETH	15802	WORD	-	Υ	Default Gateway (part 1)	0 255	192	num
DefGtwy_2_ETH	15803	WORD	-	Υ	Default Gateway (part 2)	0 255	168	num
DefGtwy_3_ETH	15804	WORD	-	Υ	Default Gateway (part 3)	0 255	0	num
DefGtwy_4_ETH	15805	WORD	-	Υ	Default Gateway (part 4)	0 255	1	num
NetMsk_1_ETH	15806	WORD	-	Υ	Net mask (part 1)	0 255	255	num
NetMsk_2_ETH	15807	WORD	-	Υ	Net mask (part 2)	0 255	255	num
NetMsk_3_ETH	15808	WORD	-	Υ	Net mask (part 3)	0 255	255	num
NetMsk_4_ETH	15809	WORD	-	Υ	Net mask (part 4)	0 255	0	num
PriDNS_1_ETH	15810	WORD	-	Υ	Primary DNS server (part 1)	0 255	194	num
PriDNS_2_ETH	15811	WORD	-	Υ	Primary DNS server (part 2)	0 255	25	num
PriDNS_3_ETH	15812	WORD	-	Υ	Primary DNS server (part 3)	0 255	2	num
PriDNS_4_ETH	15813	WORD	-	Υ	Primary DNS server (part 4)	0 255	129	num
SecDNS_1_ETH	15814	WORD	-	Υ	Secondary DNS server (part 1)	0 255	194	num
SecDNS_2_ETH	15815	WORD	-	Υ	Secondary DNS server (part 2)	0 255	25	num

LABEL	PAR VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
SecDNS_3_ETH	15816	WORD		Υ	Secondary DNS server (part 3)	0 255	2	num
SecDNS_4_ETH	15817	WORD	-	Υ	Secondary DNS server (part 4)	0 255	130	num
EnableDHCP_ ETH	15819	WORD	-	Υ	Enable DHCP	0 1 (False, True)	False	flag
Display folder			i					
Hmi_Language	15819	WORD	1	-	Display language 0 = Italian 1 = English 2 = French 3 = German 4 = Spanish	0 65535	0	num
Par_ContrLCD	15723	WORD	ı	Y	LCD Contrast Allows adjustment of the LCD display contrast.	0 64	30	num
Par_ BackLightTime	15724	WORD	-	-	Backlight switch-on time Allows adjustment of LCD display switch-on time.	0 3600	10	sec
Buzzer folder								
Buzzer_Mode	15990	WORD	-	-	Buzzer mode 0= always off 1= beep per key	0 1	0	num
HMI Management f								
Hmi_Language	15989	WORD				0 65535	0	num
HmiList_Current	15820	WORD	-	-	Current HMI 0= HMI remote 1 1= HMI remote 2 2= HMI remote 3 3= HMI remote 4 4= HMI remote 5 5= HMI remote 6 6= HMI remote 7 7= HMI remote 8 8= HMI remote 9 9= HMI remote 10 10 = not used 11= Local HMI	0 11	11	num
HMI remote 1 folde		pilowing to	laers	para	imeters are NOT USED.			
HmiList_ID_1	15821	WORD	_	_	HMI remote 1 navigation ID list	0 254	0	num
HmiList_Res_1	15833	WORD	-	-	HMI remote 1 navigation resource type HMI remote 1 navigation resource type 1=RTU (RS485 Modbus RTU) 2=TCP (Modbus TCP) 3=CAN (CAN)	1 3	3	num
HmiList_Addr_1	15845	WORD	-	-	HMI remote 1 navigation resource address for CAN, RTU and TCP (IP part 1)	0 255	0	num

LABEL	PAR VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
HmiList_Addr_2	15846	WORD	-	-	HMI remote 1 navigation resource address for TCP (IP part 2)	0 255	0	num
HmiList_Addr_3	15847	WORD	-	-	HMI remote 1 navigation resource address for TCP (IP part 3)	0 255	0	num
HmiList_Addr_4	15848	WORD	-	-	HMI remote 1 navigation resource address for TCP (IP part 4)	0 255	0	num
HmiList_File_1	15893	15 byte	-	-	HMI remote 1 navigation file (DOS 8.3 uppercase format)	******		string
HMI remote 2 folde	r							
HmiList_ID_2	15822	WORD	-	-	HMI remote 2 navigation ID list	0 254	0	num
HmiList_Res_2	15834	WORD	-	-	HMI remote 2 navigation resource type 1=RTU (RS485 Modbus RTU) 2=TCP (Modbus TCP) 3=CAN (CAN)	1 3	3	num
HmiList_Addr_1	15849	WORD	-	ı	HMI remote 2 navigation resource address for CAN, RTU and TCP (IP part 1)	0 255	0	num
HmiList_Addr_2	15850	WORD	-	ı	HMI remote 2 navigation resource address for TCP (IP part 2)	0 255	0	num
HmiList_Addr_3	15851	WORD	-	1	HMI remote 2 navigation resource address for TCP (IP part 3)	0 255	0	num
HmiList_Addr_4	15852	WORD	-	-	HMI remote 2 navigation resource address for TCP (IP part 4)	0 255	0	num
HmiList_File_2	15901	15 byte	-	ı	HMI remote 2 navigation file (DOS 8.3 uppercase format)	******		string
HMI remote 3 folde	r							
HmiList_Res_3	15835	WORD	1	1	HMI remote 3 navigation resource type 1=RTU (RS485 Modbus RTU) 2=TCP (Modbus TCP) 3=CAN (CAN)	1 3	3	num
HmiList_Addr_1	15853	WORD	-	ı	HMI remote 3 navigation resource address for CAN, RTU and TCP (IP part 1)	0 255	0	num
HmiList_Addr_2	15854	WORD	-	-	HMI remote 3 navigation resource address for TCP (IP part 2)	0 255	0	num
HmiList_Addr_3	15855	WORD	-	-	HMI remote 3 navigation resource address for TCP (IP part 3)	0 255	0	num
HmiList_Addr_4	15856	WORD	-	-	HMI remote 3 navigation resource address for TCP (IP part 4)	0 255	0	num
HmiList_File_3	15909	15 byte	-	-	HMI remote 3 navigation file (DOS 8.3 uppercase format)	******		string
HMI remote 4 folde	r							
HmiList_ID_4	15822	WORD	-	-	HMI remote 4 navigation ID list	0 254	0	num

LABEL	PAR VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
HmiList_Res_4	15836	WORD	ı	-	HMI remote 4 navigation resource type 1=RTU (RS485 Modbus RTU) 2=TCP (Modbus TCP) 3=CAN (CAN)	1 3	3	num
HmiList_Addr_1	15857	WORD	-	-	HMI remote 4 navigation resource address for CAN, RTU and TCP (IP part 1)	0 255	0	num
HmiList_Addr_2	15859	WORD	-	-	HMI remote 4 navigation resource address for TCP (IP part 2)	0 255	0	num
HmiList_Addr_3	15859	WORD	-	-	HMI remote 4 navigation resource address for TCP (IP part 3)	0 255	0	num
HmiList_Addr_4	15860	WORD	-	-	HMI remote 4 navigation resource address for TCP (IP part 4)	0 255	0	num
HmiList_File_4	15917	15 byte	-	-	HMI remote 4 navigation file (DOS 8.3 uppercase format)	*****		string
HMI remote 5 folde	r							
HmiList_ID_5	15825	WORD	-	-	HMI remote 5 navigation ID list	0 254	0	num
HmiList_Res_5	15837	WORD	-	-	HMI remote 5 navigation resource type 1=RTU (RS485 Modbus RTU) 2=TCP (Modbus TCP) 3=CAN (CAN)	1 3	3	num
HmiList_Addr_1	15861	WORD	ı	ı	HMI remote 5 navigation resource address for CAN, RTH and TCP (IP part 1)	0 255	0	num
HmiList_Addr_2	15862	WORD	-	-	HMI remote 5 navigation resource address for TCP (IP part 2)	0 255	0	num
HmiList_Addr_3	15863	WORD	-	-	HMI remote 5 navigation resource address for TCP (IP part 3)	0 255	0	num
HmiList_Addr_4	15864	WORD	-	-	HMI remote 5 navigation resource address for TCP (IP part 4)	0 255	0	num
HmiList_File_5	15925	15 byte	-	-	HMI remote 5 navigation file (DOS 8.3 uppercase format)	******		string
HMI remote 6 folde	r	•						
HmiList_ID_6	15826	WORD	-	-	HMI remote 6 navigation ID list	0 254	0	num
HmiList_Res_6	15838	WORD	-	-	HMI remote 6 navigation resource type 1=RTU (RS485 Modbus RTU) 2=TCP (Modbus TCP) 3=CAN (CAN)	1 3	3	num
HmiList_Addr_1	15865	WORD	-	-	HMI remote 6 navigation resource address for CAN, RTH and TCP (IP part 1)	0 255	0	num
HmiList_Addr_2	15866	WORD	-	-	HMI remote 6 navigation resource address for TCP (IP part 2)	0 255	0	num
HmiList_Addr_3	15867	WORD	-	-	HMI remote 6 navigation resource address for TCP (IP part 3)	0 255	0	num

LABEL	PAR VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.				
HmiList_Addr_4	15868	WORD	-	-	HMI remote 6 navigation resource address for TCP (IP part 4)	0 255	0	num				
HmiList_File_6	15933	15 byte	-	-	HMI remote 6 navigation file (DOS 8.3 uppercase format)	*****		string				
HMI remote 7 folder												
HmiList_ID_7	15827	WORD	-	-	HMI remote 7 navigation ID list	0 254	0	num				
HmiList_Res_7	15839	WORD	-	-	HMI remote 7 navigation resource type 1=RTU (RS485 Modbus RTU) 2=TCP (Modbus TCP) 3=CAN (CAN)	1 3	3	num				
HmiList_Addr_1	15869	WORD	1	ı	HMI remote 7 navigation resource address for CAN, RTU and TCP (IP part 1)	0 255	0	num				
HmiList_Addr_2	15870	WORD	-	-	HMI remote 7 navigation resource address for TCP (IP part 2)	0 255	0	num				
HmiList_Addr_3	15871	WORD	-	-	HMI remote 7 navigation resource address for TCP (IP part 3)	0 255	0	num				
HmiList_Addr_4	15872	WORD	-	-	HMI remote 7 navigation resource address for TCP (IP part 4)	0 255	0	num				
HmiList_File_7	15941	15 byte			HMI remote 7 navigation file (DOS 8.3 uppercase format)	*****		string				
HMI remote 8 folde	r											
HmiList_ID_8	15828	WORD	-	-	HMI remote 8 navigation ID list	0 254	0	num				
HmiList_Res_8	15840	WORD	ı	1	HMI remote 8 navigation resource type 1=RTU (RS485 Modbus RTU) 2=TCP (Modbus TCP) 3=CAN (CAN)	1 3	3	num				
HmiList_Addr_1	15873	WORD	1	-	HMI remote 8 navigation resource address for CAN, RTU and TCP (IP part 1)	0 255	0	num				
HmiList_Addr_2	15874	WORD	-	-	HMI remote 8 navigation resource address for TCP (IP part 2)	0 255	0	num				
HmiList_Addr_3	15875	WORD	-	-	HMI remote 8 navigation resource address for TCP (IP part 3)	0 255	0	num				
HmiList_Addr_4	15876	WORD	-	-	HMI remote 8 navigation resource address for TCP (IP part 4)	0 255	0	num				
HmiList_File_8	15949	15 byte	-	-	HMI remote 8 navigation file (DOS 8.3 uppercase format)	*****		string				
HMI remote 9 folde					,		Y					
HmiList_ID_9	15829	WORD	-	-	HMI remote 9 navigation ID list	0 254	0	num				
HmiList_Res_9	15841	WORD	-	-	HMI remote 9 navigation resource type 1=RTU (RS485 Modbus RTU) 2=TCP (Modbus TCP) 3=CAN (CAN)	1 3	3	num				

LABEL	PAR VALUE ADDRESS	DATA SIZE	CPL	RESET (Y/N)	DESCRIPTION	RANGE	DEFAULT	U.M.
HmiList_Addr_1	15877	WORD	-	-	HMI remote 9 navigation resource address for CAN, RTU and TCP (IP part 1)	0 255	0	num
HmiList_Addr_2	15878	WORD	-	1	HMI remote 9 navigation resource address for TCP (IP part 2)	0 255	0	num
HmiList_Addr_3	15879	WORD	-	-	HMI remote 9 navigation resource address for TCP (IP part 3)	0 255	0	num
HmiList_Addr_4	15880	WORD	-	-	HMI remote 9 navigation resource address for TCP (IP part 4)	0 255	0	num
HmiList_File_9	15957	15 byte	-	-	HMI remote 9 navigation file (DOS 8.3 uppercase format)	*****		string
HMI remote 10 fold	er							
HmiList_ID_10	15830	WORD	-	-	HMI remote 10 navigation ID list	0 254	0	num
HmiList_Res_10	15842	WORD	-	1	HMI remote 10 navigation resource type 1=RTU (RS485 Modbus RTU) 2=TCP (Modbus TCP) 3=CAN (CAN)	1 3	3	num
HmiList_Addr_1	15881	WORD	-	-	HMI remote 10 navigation resource address for CAN, RTU and TCP (IP part 1)	0 255	0	num
HmiList_Addr_2	15882	WORD	-	-	HMI remote 10 navigation resource address for TCP (IP part 2)	0 255	0	num
HmiList_Addr_3	15883	WORD	-	-	HMI remote 10 navigation resource address for TCP (IP part 3)	0 255	0	num
HmiList_Addr_4	15884	WORD	-	-	HMI remote 10 navigation resource address for TCP (IP part 4)	0 255	0	num
HmiList_File_10	15965	15 byte	-	-	HMI remote 10 navigation file (DOS 8.3 uppercase format)	******		string

CHAPTER 10

Programming of the EVE4200

The **DMI 100-3** and **MFK 100** are accessories that can be connected to the **EVE4200 expansion** (target) serial port to make a quick programming of :

- · Targets parameters (upload and download of a parameter map to/from one or more targets of the same type)
- · Targets BIOS

Connection of Programming Cable (DMI 100-3)

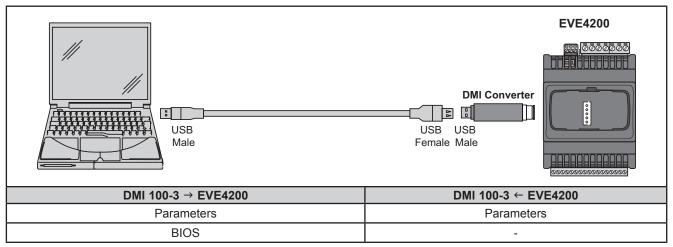


Fig. 64. Connections between DMI 100-3 Converter and the EVE4200

NOTE: When supplying power to the expansion module from the PC, **EVE4200** must not be connected to earth. If a ground (earth) connection exists for the PC as well as the **EVE4200** a ground loop condition could develop and render either PC or the **EVE4200** inoperable.

NOTICE

INOPERABLE EQUIPMENT

If you are unsure whether the **EVE4200** is connected to an SELV power supply, disconnect the power supply connection to the **EVE4200** before connecting a PC.

Failure to follow these instructions can result in equipment damage.

Connection of Multi Function Key (MFK 100)

To connect MFK 100 to DMI 100-3 the BLUE cable is used.

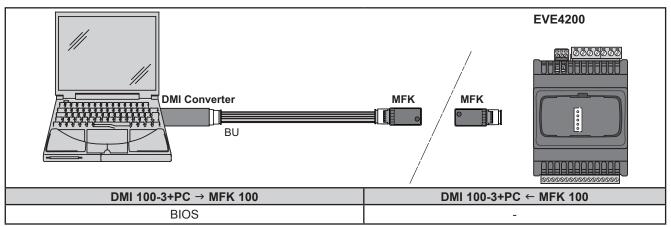


Fig. 65. Connections between MFK 100 and DMI 100-3 Converter + PC

A WARNING

UNINTENDED EQUIPMENT OPERATION

- Connect the programming cable to the PC first, then to the programming port of the controller.
- Disconnect the programming cable from the controller before disconnecting it from the PC.

Failure to follow these instructions can result in death, serious injury, or equipment damage

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